#### Frequency Inverters SJ Series Type P1







## SJ Series, Type P1 – High PerformanceInverter

Hitachi maintains research and development departments throughout the business. These are continually working on the further improvement of products and technologies and synergy effects are specifically used in product policy. As a result, many components for Hitachi products are manufactured within the company itself.

Hitachi offers a broad range of high performance inverters for many industrial applications. The inverters' modular design and high versatility ensure optimal, cost-efficient technical solutions which can be individually adapted to the respective application. The industrial inverters can be configured easily,

and are designed to deliver unprecedented perfor- mance, reliability and flexibility.

The new SJ Series, Type P1 is at the cutting edge of technology for premium inverters. Highly flexible, it is suitable for a wide variety of demanding applications. SJ-P1 has premium drive characteristics to achieve instantaneous force and efficient operation.





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### Ease of Use

#### ProDriveNext Software

Easy to use programming software allows user-friendly and intuitive operation.

- Onlinemonitoringofallparameters andl/Oterminalstatus
   Parameter conversion between different series
   Faster parameter download/ upload with USB communication
- □Windows XP, 7, 8,10 compatible



#### Easy operation LED control RS422 port Micro USBport

#### VOP colour LCD operator

12 languages available
Colour TFT display
Real time clock built-in
Parameter and EzSQ programmingdatacopyfunction

#### Password function

Helps to ensure that parameters remain secured and safeguarded.

#### User-friendly display







#### Network compatibility & external ports

The SJ-P1 Series is particularly suitable for easy integration into various networks using optional fieldbus modules.

RS485-Modbus(Built-in)
RS422 port (Built-in)
Ethernet
EtherCAT
ProfiNET
Profibus-DP





#### **Option slots**

- Hitachi original cassette option for flexible use. □Upto3optionscanbeused
  - simultaneously
- □Easy access from the inverter front □VariousfieldbusandI/Ooptions available

#### Option modules

Ethernet
EtherCAT
Profibus-DP
ProfiNET
Feedback
Safety
Analog input and output
Relay output



#### EzCOM Inverter-to-Inverter communication

SJ-P1 also gives the option to communicate by using Inverter-to-Inverter connections without a PLC or PC.





## Flexible & User-friendly

#### Easy wiring



Screwless terminal block (control terminal block).



Modbus communication as standard – two communication terminals are provided. Therefore daisy chain wiring is easy to realize.



0-10Vin/outand4~20mAin/out areeasilyswitchedbyDIPswitch.

2 analog inputs (3 inputs in total)
2 analogoutputs

#### Heat sink extraction

It is easy to place the cooling fans to the outside of the cabinet since the L-shaped brackets are separate parts.

#### Fulfilling lifetime prediction functions

ElectrolyticcapacitorofpowercircuitCoolingfan





#### Improved efficiency with 24 VDC supply

In addition to normal power supply (R0, T0), external 24 VDC control power can also be applied as standard. Parameter setting is also available if the main power is turned off meaning operational

efficiency is increased and stand by power is reduced. It will also contribute to energy savings. Connecting to the PL Candsettings via PC configurations of tware are also available.

# PC settingsoftware (ProDriveNext)

#### Quick diagnose of failure occurrence

P1 can also store internal data to the internal memory on a continuous basis. It can also upload data to the PC when an error occurs – making rapid diagnosis possible.

#### Error occurance



#### Easy to customize with configuration software PC software

The configuration software 'ProDriveNext' easily enables the user to set up, monitor and diagnose the device.

#### Customizationoffunctionscanbeeasily achieved

The existing functions can be modified by using a 'BASIC'-like programming language.





## Safety&SafeOperation

#### Certified "functional safety"

international standard Certified functional safety Thirdpartycertifiedelectricalsafety AlsoincomplianceEN61508, IEC/EN/UL61800-5-2SIL3 STOasfunctionalsafetystandard IEC/EN60204-1 Stop Cat.0 EN/ISO13849-1 Cat.3, PLe IEC61508, IEC / EN / UL61800-5-2, IEC / EN62061 SIL3 STO SS1,SL Sandothersareavailablewithsl ot-inoptioncard



#### Standard (without option card)



#### Optional (needs slot-in card)















#### Trip avoidance functions

Minimum time deceleration function, overcurrent suppression and DC bus AVR functions are included as standard.

These functions increase the robustness oftheproductandhelptoavoidunneces- sary tripping. Improved torque limiting / current limiting functionality enables load restrictions to be applied in order to protectmachineryandequipment.

#### Minimum time Deceleration Function



#### Over-current Suppression Function\*



\* Turn off this function for lifting equipment.



# SJ-P1 Smooth Operation and Precision

"Smooth operation" can be easily achieved High starting torque from the low speed area supports the smooth drive of heavy load.





smooth and stabilized operation with less shock.



Steady operation for crane, lift, transport etc. Trip can be prevented by smooth driving to support steady operation of crane and conveyer for better productivity.

"High speed rotation" for precision

590 Hz operation is available for precise metal

processing. PM motor is also available up to 400



Hz.



#### Induction motor & permanent magnet motor can be controlled with one inverter series

The SJ-P1 inverter can be used to drive both induction motors (IM) and permanent magnetic motors (PM). PM motors are energy efficient and make effective use of available space. Thanks to the over-current trip level setting, demagnetization of PM motors can be suppressed.





#### Multi-rating to support space and cost savings

Triple-rating for IM motor for various applications is available. Also dual-rate for PM motor control can be selected. Multi-rating helps to save space and costs.

Rating	VLD (VeryLightLoad)	LD (Light Load)	ND (Normal Load)		
Induction motor					
PM motor					
	Fan-pu	np			
Applications		Metal tooling	ling-conveyer		
			Crane-mixer		
Overload current rating	110 % 60 sec, 120 % 3 sec	120 % 60 sec, 150 % 3 sec	150 % 60 sec, 200 % 3 sec		
Example 400 V / 18.5 kW Max rated output current	47.0A	43.0A	39.0A		



## VariousFunctions

#### Intuitive and easy-to-use TFT LCD operator

Quick View: Get an overview



Multi-monitor(3lines)

60.00 Hz (0.00-60.001 0.58

Verify View:

et

Monitor all settings

MI

Option

Speed-M(Keypad) 60.00 Hz

Speed-M(Keypad)

Referencescreen

#### **Built-in BRD circuit**

Built-in braking resistor control circuit is available as standard in all models up to 37 KW (resistor optional). Clear View: Easy to see

Error View: Quick trouble shoot



Trip historyscreen

Largemonitorscreen

#### EzCOM (peer-to-peer communication)

SJ-P1 supports peer-to-peer communication between multiple inverters using the built-in RS485 port. In this configuration one administrator inverter is required in the network whilst the other inverters act as master or slave.



## **Eco-friendly**

#### **RoHS** compliant

The SJ Series, Type P1 meets EU RoHS requirements.

#### Endurance in severe conditions

Vanish coating of the internal PC board ensures an improved endurance to certain severe conditions (logic PCB and I / F PCB are excluded).

#### Long life components

The cooling fans and built-in capacitors have an estimated design lifetime of 10 years\*. By using the ON/OFFcontrolfunctionthelifetimecanbeextended. \* 10 years is a design lifetime based on calculation, not guaranteed



#### General specifications

ltern			General specifications						
PWM system			Sine-wave PWM system						
Output freque	ncy range		0.00 to 590.00 Hz						
Frequency acc	uracy		For the highest frequency, Digital: ±0.01 %, Analogue: ±0.2 % (25 ±10 °C)						
Frequency res	-		Digital: 0.01 Hz, Analogue: Max. frequency / 4000 (Ai1 terminal / Ai2 terminal: 12bit / 0 to +10V or 0 to +20 mA, Ai3 terminal 12bit / –10 to +10V)						
Volt./Freq. characteristi c	ІМ		//F control (constant torque/reduced torque/free),Automatic boost ontrol, V/F control with encoder (constant torque/reduced orque/free), utomatic boost control with encoder, Cascade type sensorless vector control, 0 Hz sensorless vector control						
	SM / PMM		Method of synchronous startup for smart sensorless vector control						
Acceleration /	Deceleration tin	18	0.00 to 3600.00 seconds (Linear, S-curve, U-curve, Inverted-U-curve, EL-S-curve)						
DC braking			Variable operating frequency, delay time, braking force, time						
Input signal	Digital		11 terminals, NO / NC switchable, Sink / Source changeable by switch (A or B terminal accept a pulse train)						
<b></b>	Analog		4 terminals Ai1 / Ai2 terminal (0 to 10VDC or 0 to 20 mA, Input impedance: 10 kΩ), Ai3 terminal (–10 to +10VDC, Input impedance: 10 kΩ) Thermistor input terminal (PTC / NTC resistor allowed)						
	Pulse train (These can be digital input too)		2 terminals (Maximum 27VDC, 5.6 mA, 32 kHz)						
Output signal	Digital		5 transistor output terminals						
	Analog		2 terminals (0 to 10VDC or 0 to 20 mA)						
	Pulsetrain		1 terminal (0 to 10VDC, Maximum 1.2 mA, 3.60 kHz)						
	Relay		1 1a contact relay, 1 1c contact relay						
Network	Standar d		RS485 (Modbus RTU), USB micro B port, RJ45 port						
	Option		Ethernet, EtherCAT, Profibus-DP, ProfiNET						
Other functions			V / F free setting (7 points), Upper and Iower frequency limit, Frequency jump, Curve acceleration and deceleration, Manual torque boost, Energy-saving operation, Analogue output adjustment, Mirmimium speed, Carrier frequency adjustment, Motor electronic thermal function, External start- end(speedandrate), Frequency inputselection, Tripretry, Restartstop, Various signal output, Initialization setting, PID control, Auto-decel at shut-off, Brake control function, Commercial switching function, Auto-tuning (on/offline), etc.						
Functional saf	etv		STO: SIL3, Cat. 3 / PLe						
Protection functions			Overcurrent error, Overload error, Brake resistor overload, Over voltage error, Memory error, Undervoltage error, Current detector error, CPU error, External trip error, USP error, Ground error, Supply overvoltage error, Phase output error, Thermistor error, Brake error, Low-speed range overload error, Inverter overload, RS485 communication error, RTC error, etc.						
Operating	Ambient	VLD	-10 to 50 °C						
environmen	temperatur	LD	-10 to 45 °C						
t	e	ND	-10 to 40 °C						
	Storagetemp	erature	-20 to 65 °C						
	Humidity		20 to 90 % RH (No condensation allowed)						
	Vibration	P1-00041-H (P1-004H) to P1-00620-H (P1- 220H)	5.9 m/s² (0.6 G), 10 to 55 Hz						
		P1-00770-H (P1-300H) to P1-03160-H (P1- 1320H)	2.94 m/s² (0.3 G), 10 to 55 Hz						
Installation place		lace	A maximum altitude of 1000 m, without gases or dust						
Certification			UL, c-UL, CE marking, RCM (planned: KC, EAC, NK)						
Options			Optioncassette: Input/Outputoption(Analoginput/outputoption,Relayoutputoption),Communication(Ethernet,EtherCAT,Profibus- s-DP, ProfiNET),Feedback(Linedriveoutput00041,Push pull output,Resol veroutput),Temperaturedetector(Optional temperaturemeasuring sensor)						
			Others: Braking resistor, AC / DC reactor, Noise filter, Operator cable, Harmonics suppresion unit, Noise filter, LCR filter, Analog panel, Regenerative braking unit, PC software "ProDriveNext", Relay expansion terminal board						

#### Conformity to global standards

CE, UL, c-UL, c-Tick approvals.

#### Sink / source logic is standard

Logic input and output terminals can be configured for sink or source logic.

#### Wide input power voltage range

Input voltage range from 380 V to 500 V as standard.



#### Standard specifications

Model name P1-***	***-H		00041	00054	00083	00126	00175	00250	00310	00400	00470
Enclosure							IP20				
Applicable motor capacity (4 poles) (kW)		VL D	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22
		LD	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22
		ND	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5
Rated capacity (kVA)	400 V	VL D	2.8	3.7	5.8	8.7	12.1	17.3	21.5	27.7	32.6
		LD	2.1	3.3	4.6	7.7	11.1	15.2	20.1	25.6	29.8
		ND	1.7	2.8	3.8	6.4	10.3	13.2	17.3	22.2	27.0
	500 V	VL D	3.6	4.7	7.2	10.9	15.2	21.7	26.8	34.6	40.7
		LD	2.7	4.2	5.8	9.6	13.9	19.1	25.1	32.0	37.2
		ND	2.2	3.5	4.8	8.0	12.8	16.5	21.7	27.7	33.8
Rated input AC voltaç	je		Control power: Single-phase supply 380 to 500V (+10 %, -15 %), 50 Hz / 60 Hz (±5 %)								
					Main powe	er: 3-phase (3 wir	e) 380 to 500V (	+10 %, –15 %), 5	50 Hz / 60 Hz (±	5%)	
Rated output current (A) VL D LD ND		4.1	5.4	8.3	12.6	17.5	25.0	31.0	40.0	47.0	
		LD	3.1	4.8	6.7	11.1	16.0	22.0	29.0	37.0	43.0
		ND	2.5	4.0	5.5	9.2	14.8	19.0	25.0	32.0	39.0
Overload current rati	ng	VL D	110 % 60 sec / 120 % 3 sec								
		LD	120 % 60 sec / 150 % 3 sec								
		ND	150 % 60 sec / 200 % 3 sec								
Rated output voltage			3-phase (3 wire): 380 to 500V (proportional to input voltage)								
Starting tor que (ND) 200 % / 0.3 Hz											
Regenerative braking			Internal BRD circuit (external discarge resistor)								
Minimum resistance value ( $\Omega$ )			100	100	100	70	70	35	35	24	24
H (height) (mm)			255	255	255	255	260	260	260	390	390
W (width) (mm)		150	150	150	150	210	210	210	245	245	
D (depth) (mm)			140	140	140	140	170	170	170	190	190
Weight (kg)			4	4	4	4	7	7	7	16	16

Model nameP1-***	**-H		00620	00770	00930	01160	01470	01760	02130	02520	03160	
Enclosure					IP20				IP00			
Applicable motor VL capacity (4 poles) (kW) D		VL D	30	37	45	55	75	90	110	132	160	
	•	LD	30	37	45	55	75	90	110	132	160	
		ND	22	30	37	45	55	75	90	110	132	
Rated capacity (kVA)	400 V	VL D	43.0	53.3	64.4	80.4	101.8	121.9	147.6	174.6	218.9	
		LD	39.5	48.5	58.9	72.7	93.5	110.9	135.1	159.3	200.9	
		ND	33.3	42.3	52.0	63.0	77.6	103.9	124.7	150.3	180.1	
	500 V	VL D	53.7	66.7	80.5	100.5	127.3	152.4	184.5	218.2	273.7	
		LD	49.4	60.6	73.6	90.9	116.9	138.6	168.9	199.2	251.1	
		ND	41.6	52.8	65.0	78.8	97.0	129.9	155.9	187.9	225.2	
Rated input AC voltage			Control power: Single-phase supply 380 to 500 V (+10 %, -15 %), 50 Hz / 60 Hz (±5 %)									
			Main power: 3-phase (3 wire) 380 to 500 V (+10 %, -15 %), 50 Hz / 60 Hz (±5 %)									
Rated output current (A)	(A)	VL D	62.0	77.0	93.0	116	147	176	213	252	316	
		LD	57.0	70.0	85.0	105	135	160	195	230	290	
		ND	48.0	61.0	75.0	91.0	112	150	180	217	260	
Overload currentrati	ng	VL D	110 % 60 sec / 120 % 3 sec									
		LD	120 % 60 sec / 150 % 3 sec									
		ND	150 % 60 sec / 200 % 3 sec									
Rated output voltage					3-p	ohase (3 wire): 38	30 to 500 V (prop	ortional to input voltage)				
Starting torque			200 % / 0.3 Hz 180 % / 0.3 Hz									
Regenerative braking			Internal BRD circuit opt. internal					Ext. regen. braking unit				
Minimum resistance value (Ω)			20	15	15	10	10	-	-	-	-	
H (height) (mm)			390	540	550	550	550	700	700	740	740	
W (width) (mm)			245	300	390	390	390	390	390	480	480	
D (depth) (mm)			190	195	250	250	250	270	270	270	270	
Weight (kg)			16	22	30	30	30	55	55	70	70	

## HTACH Inspire the Next

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