

# Programmable logic controller XG1/XL3/XD/XC series

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XG1<sup>NEW</sup> series middle-sized PLC



# XL3 NEW series ultrathin PLC



# Middle-sized PLC

#### XG1 series

## New light appearance

### Features

- Ethernet communication port, fast speed and powerful functions
- Motion control function
- More reliable



# **Ultrathin PLC**

**XL3 Series** 

# Small size, powerful function

### Features

- Ultrathin appearance, compact and practical, fit for different environment
- Good compatibility
- Support max 10 extension modules
- Outstanding cost performance Save installation sapce









# Dimension (unit: mm)





# XD series

XD2 series XD3 series XD5 series XDM series XDC series

Faster processing speed

• Rich expansion modules

• Stable performance, meet different needs





# XD Series

After XC series PLC, XINJE company developped XD series PLC which has faster speed, better performance and fit for various requirments.

	Da
256K prog	ram ca
I/O sequer	nce con

XD5-24/32/48/60 384K program capacity
 I/O sequence control
 USB communication port X-NET fieldbus Max 572 I/O points Basic instruction 0.02~0.05us 200KHz pulse output 2-axis pulse output 200KHz pulse output

	Motion contro	l model
XDM-24T4/3	2T4/60T4	XDM-6
<ul> <li>384K program capacity</li> <li>I/O sequence control</li> <li>Standard model PLC</li> <li>USB communication port</li> <li>X-NET fieldbus</li> <li>Function block programming</li> <li>200KHz pulse output</li> </ul>	Max 572 I/O points Basic instruction 0.02~0.05us Linear and circular interpolation Follow-up function 4-axis pulse output	384K program capacity     1/0 sequence control     Standard model PLC     USB communication port     X-NET fieldbus     Function block programn     200KHz pulse output





# Enhanced model XD5-24T4/32T4 XD5-48T6/60T6 384K program capacity X-NET fieldbus I/O sequence control Max 572 I/O points USB communication port Basic instruction 0.02~0.05us 384K program capacity X-NET fieldbus I/O sequence control Max 544 I/O points USB communication port Basic instruction 0.02~0.05us 4-axis pulse output ■ 200KHz pulse output ■ 6-axis pulse output



#### High speed processing

Basic instruction processing speed is 0.02~0.05µs, scanning time is 0.5ms for 10000 steps, program capacity is 256K~384K, the integrated speed is 12~15 times of XC series.



#### **Rich extensions**

XD series PLC has rich I/O modules, analog I/O modules, temperature modules, BD board, left extension modules. The PLC unit can connect 10~16 modules, 1~2 BD board, 1 left extension module.



Series	Туре	Left extension module	BD board	<b>Right extension module</b>
XD2	16 points	1	0	0
	16 points	1	0	10
XD3	24/32 points	1	1	10
	48/60 points	1	2	10
	24/32/24T4/32T4 points	1	1	16
XD5	48/60 points	1	2	16
	48T6/60T6 points	1	2	16
XDM	24T4/32T4 points	1	1	16
XD1VI	60T4/T10 points	1	2	16
XDC	24/32 points	1	1	16
XDC	60 points	1	2	16

#### • I/O extension module

▶ To extend the I/O numbers, 8~32 points, the PLC can extend to 572 points. • Output extension module has two types which are transistor and relay.

#### • Extension BD board

CPU processing spe

► The small card can install on the PLC directly, save space, with wireless and wired communication function.



#### • Left extension module

▶ PLC can transfer the data through WIFI, RS232 or RS485 with the left extension ED module.

#### • Analog and temperature extension module

- D/A and A/D transformation function. Apply to process control system including temperature, flow, liquid level, pressure.
- ▶ PID function, only four parameters to set. Fit for various applications, flexible using, high control accuracy.
- ► XD-E6TC-P, XD-E6PT-P have PID control for each channel, with auto-tune function, transfer data with PLC by instruction FROM and TO.

#### **XD3 series** Larger soft component capacity



#### **Communication function**

• Multi-communication ports (up to 5), support RS232, RS485, motion fieldbus, X-NET fieldbus, Ethernet, can connect VFD, meter and other devices, networking freely.



#### Faster data exchange speed between extension module and main PLC

• The data exchange between extension module and main PLC of XD series is SPI serial communication instead of parallel communication which used by XC series, the speed is faster ( $\mu$ s).

#### 100-segment high speed count interruption function

• High speed count interruption, good real time performance.

• XD series high speed counter has 100 segments of 32 bits preset value. The interruption is produced when the count value difference of each segment is equal to the preset value.



#### Subdivided soft component

- Subdivided soft component makes the ladder chart more visually.
- Normal soft component, power-off retentive and special soft component is different from each other by writing format.
- Single phase and AB phase of high speed count also can be distingui

	Туре	Symbol	Notes	
		Х	Input terminal	
		Y	Output terminal	
		M	Internal coil	
		S	Process coil	
		SM	Special internal coil	similar to the s
		Т	Timer coil	
В	lit object	ET	Precise timer coil	Similar to T600
		С	Counter coil	
		HM	Power-off retentive internal coil	Similar to pow
		HS	Power-off retentive process coil	Similar to pow
		HT	Power-off retentive timer coil	New soft comp
		HC	Power-off retentive counter coil	Similar to pow
		HSC	High speed counter coil	Similar to high phase and AB
		SEM	BLOCK WAIT instruction special coil	The wait coil o
		D	register	
		TD	Timer register	
		ETD	Precise timer register	
		CD	Counter register	
×	RAM	SD	Special register	
Word object		ID	Analog sampling register	
obj		QD	Analog output register	
ect		HD	Power-off retentive register	
		HTD	Power-off retentive timer register	
		HCD	Power-off retentive counter register	
		HSCD	High speed counter register	
		HSD	Power-off retentive special register	
	FLACU	FD	Flash register	protect the cus
	FLASH	SFD	Special flash register	

#### **High speed count**

• XD series PLC can configure 2 to 10 channels of 32-bit high speed count, the max frequency can up to 80KHz, it can connect the rotary encoder and count its value directly.

#### ▶ count input



Multi-counting mode



#### **Optimized Modbus instruction**

More than one modbus instruction can be triggered by one condition in the main program, these instructions will be executed one by one as the protocol station request. It will not run two instructions at the same time and cause error.





ished by writing format.	
Remark	
special auxiliary register after M8000 of XC series P	
00 to T618 of XC series PLC	
ver-off retentive internal coil of XC series PLC, defau ver-off retentive process coil of XC series PLC, defau ponent, the timer value and state will be kept even th ver-off retentive counter coil of XC series PLC, defau h speed counter coil C600 to C634 of XC series PLC hase mode, AB phase has 2-time frequency and 4 of XC series PLC can be anyone, in XD series it only	ult is S512 to S1023 te PLC power is off ult is C320 to C630 XD series PLC only have single -time frequency
istomer's intellectual property	
<ul> <li>There are two counting modes incl mode, max frequency 80KHz) and AE max frequency 50KHz).</li> </ul>	
2-time frequency mode	
ABB BB incremental counting	A
<ul> <li>4-time frequency mode AB phase counting has 4-time freq</li> </ul>	uency mode
A B incremental counting	A B C C C C C C C C C C C C C C C C C C
R K1 K500 K3 M1 K2 V K1 K500 K3 M1 K2 W K1 K500 D1 K2	M1 COLR K1 K500 K3 M1 K2 MOLW K1 K500 K3 M1 K2 REGW K1 K500 D1 K2
XC	XD3

#### Powerful pulse instruction

XD series PLC get rid of the disadvantages of XC pulse function too simple and too many pulse instructions. XD integrated the XC pulse instruction PLSR, PTO, PLSF in one, make the function powerful.



#### Powerful communication and networking function

XD series PLC communication port not only support Modbus protocol, but also support other complicated network. Users can make free format protocol to communicate with printer and meters.

#### Modbus network

XD series PLC support Modbus (RTU and ASCII) protocol master and slave mode. When PLC is master station, it will send requests to other devices which respond it. When PLC is slave station, it will answer the master station.



#### 200KHz 10 channels pulse output

XD2/XD3/XDC have 2 channels of pulse output, XD5 has 2 to 6 channels of pulse output, XDM has 4 to 10 channels pulse output. Multi-mode output by different instructions. The frequency can up to 200KHz.



- It needs transistor output PLC for pulse output, such as XD3-16T-E, XD3-60RT-E.
- XD5-24T4/32T4 have 4 channels of pulse output (Y0, Y1, Y2, Y3).
- XD5-48T6/60T6 have 6 channels of pulse output (Y0, Y1, Y2....Y5). • XDM series PLC has 4 to 10 channels pulse output (Y0, Y1, Y2..... Y11).

series	model	pulse output channel	pulse output terminal
XD2	16T	2	Y0/Y1
XD3	all the transistor output model	2	Y0/Y1
	24T/32T/48T/60T	2	Y0/Y1
XD5	48T6/60T6	6	Y0/Y1/Y2/Y3/Y4/Y5
	24T4/32T4	4	Y0/Y1/Y2/Y3
	24T4/32T4 and 60T4	4	Y0/Y1/Y2/Y3
XDM	60T10	10	Y0/Y1/Y2/Y3/Y4/Y5/
	00110	10	Y6/Y7/Y10/Y11
XDC	24T/32T	2	Y0/Y1
XDC	48T/60T	2	Y0/Y1

#### Interruption

XD series PLC interruption function includes external interruption, timing interruption, 100 segments high speed counter interruption. It can do some special operation by calling the interruption without PLC scanning period influence.



#### Timing interruption

► To run appointed program when the main program is long; to run the program every certain time. The timing interruption is useful for these occasions. It is not affected by PLC scanning period. It will run the subprogram every n ms.

► XD series PLC have 20 channels timing interruption, it is 2 times of XC series PLC.

#### Support C programming(the pioneer in the industry)







#### PWM pulse width modulation

- PWM instruction can modulate the pulse width
- The subdivision accuracy is 128 times of
- XC series PLC, up to 1/65536
- The output frequency is higher than XC
- series PLC, up to 200KHz
- Control the inverter and DC motor by this function





#### • External interruption

- ► The input terminal X is the input of interruption. Each terminal corresponds to an interruption which is activated by falling or rising edge.
- ► XD series PLC have more interruption terminals than XC series.

► The falling edge and rising edge can be used at the same time for XD series external interruption



only can use falling or rising edge of different interruption

can use the falling or rising edge of same interruption

#### PID control

- XD series PLC support PID control instruction and auto-tune function
- User can get the best sampling time and PID parameters via auto-tune
- to improve the control accuracy
- Two control methods: step-response and critical oscillation, applied to more occasions







#### Sequence block

• All the instructions in the sequence block will run one by one. The next instruction will run after the present instruction completed

#### • The sequence block can optimize the program

**Frequency measurement** 

Password protection

• 6 bits ASCII code, protect the program security

• The soft component FS can protect the intellectual property right of customers

• 32 bits instruction FRQM can measure the frequency



### XD series PLC all have RTC inside

Real time clock

 Built-in clock, Li-battery power loss retentive • XD-CLOCK-BD can apply to high precise clock occasions

 Clock protection function: the PLC clock cannot be changed through communication when secret downloading program in advanced mode



#### Self-diagnosis

• Power on self-diagnosis, monitor the timer, grammar checking

#### **Precise timing**

- 32-bit instruction STR can do precise timing
- The precise timer will generate an interruption when it reaches the
- timer value, each precise timer has related interruption flag
- The precise timer is 1ms 32 bits timer

#### Compact size, easy to installation

- Compact size, two installation methods
- Easy to change the Li-battery of XD series PLC without opening the PLC cover

#### XD2 basic type

#### I/O numbers: 16

Data processing function, high speed count, high speed pulse output, communication, real time clock, pulse width modulation (PWM), frequency measurement, precise timing, interruption and so on. The processing speed is 12 times of XC series. Cannot extend modules or BD. ED board.

32-bit CPU.

application



Modbus, free format and X-NET communication. Program capacity: 256KB. ■ The CPU processing speed is 12 times of

■ XD2 provides 16 points I/O, is fit for basic

2 RS232 ports and 1 RS485 port, support

- XC series. ■ Basic instructions: 0.02~0.05us, 6000 steps
- of instruction only need 0.1~0.2ms. 2-axis 200KHz pulse output.
- Powerful password function, protect the intellectual property right of customers.

E	Built-in high s <sub>l</sub>	peed co	unter
inci	remental mode	AB ph	nase mode
count ID	max frequency	count ID	max frequency
2	10KHz	2	5KHz

#### XD5 enhanced type

#### I/O numbers: 24/32, 48/60

The same functions to XD3. The processing speed is 15 times of XC series. Larger internal space. With serial port and one USB download port. All the models can connect 16 extension modules, 1 or 2 BD boards, 1 left extension module.

> 32-bit CPU. XD5 provides 24/32/48/60 points I/O, is fit for various applications. USB port makes the downloading and mmunication very fast. Program capacity: 25K steps/data register

- ID: 70K words. ■ The CPU processing speed is 15 times of
- XC3 series. Basic instructions: 0.02~0.05us, 6000 steps
- of instruction only need 0.1~0.2ms.
- 2-axis to 6-axis 200KHz pulse output.
- Powerful password function, protect the intellectual property right of customers.

Built-in high speed counter incremental mode AB phase mode counter max frequency counter max frequency 3/4/6 80KHz 3/4/6 50KHz

#### XDC motion control fieldbus type

#### I/O numbers: 24/32, 48/60

The processing speed is 15 times of XC series. Support floating-point calculation, 2 channels pulse output, 4 channels AB phase high speed count, and all the functions of XD series such as interruption, PID. All the models can connect 16 extension modules, 1 or 2 BD boards, 1 left extension module. Support SD card for data storage, with 2 serial ports, support motion control fieldbus, control 20-axis motions at the same time









#### XD3 standard type

#### I/O numbers: 16, 24/32, 48/60

Data processing function, high speed count, electronic cam, real time clock, communication (Modbus RTU/ASC II), pulse width modulation (PWM), frequency measurement, precise timing, interruption and so on. The processing speed is 12 times of XC series. All the models can connect 10 extension modules, 1 or 2 BD boards, 1 left extension module.



#### 32-bit CPU

- XD3 provides 16/24/32/48/60 points I/O, is fit for various applications
- USB port makes the downloading and
- communication very fast
- Program capacity: 10K steps/data register ID: 1K words.
- The CPU processing speed is 12 times of XC3 series. Basic instructions: 0.02~0.05us, 6000 steps of
- instruction only need 0.1~0.2ms.
- 2-axis 200KHz pulse output.
- 16 points I/O model also can extend modules.

Powerful password function, protect the intellectual property right of customers.

	Built-in high s	speed c	ounter
in	cremental mode	ABp	hase mode
count ID	max frequency	count ID	max frequency
2/3	80KHz/10KHz	2/3	50KHz/5KHz

#### XDM motion control type

#### I/O numbers: 24/32, 48/60

Support basic motion control instructions, 2-axis linkage motion, interpolation, follow-up, 4-axis separate pulse output, up to 10-axis pulse output, all the functions of XD series such as high speed count, interruption, PID control, the processing speed is 15 times of XC series, support SD card for data storage, with 1 serial port and 1 USB download port (high speed downloading, monitoring, speed up to 12M). All the models can connect 16 extension modules, 1 or 2 BD boards, 1 left extension module.



#### 32-bit CPU.

- XDM provides 24/32/48/60 points I/O, is fit for various applications.
- USB port makes the downloading and
- unication very fast.
- Program capacity: 25K steps/data register
- ID: 70K words.

■ The CPU processing speed is 15 times of XC3 series, 6000 steps of instruction only need

- 0.1~0.2ms
- 4-axis to 10-axis 200KHz pulse output.
- Linear or circular interpolation instructions.
- Follow-up control instructions.
- Powerful password function, protect the
- intellectual property right of customers.

В	uilt-in high s	speed	counter
incre	emental mode	AB	phase mode
counter	max frequency	counter	max frequency
4/10	80KHz/10KHz	4/10	50KHz/5KHz



#### 32-bit CPU.

- XDC provides 24/32/48/60 points I/O, is fit for various applications.
- Program capacity: 25K steps/data register ID: 70K words.

■ The CPU processing speed is 15 times of XC3 series, 6000 steps of instruction only need 0.1~0.2ms.

- 2-axis 200KHz pulse output.
- 1-axis to 20-axis fieldbus control.

Powerful password function, protect the intellectual property right of customers.

#### Built-in high speed counter

incre	mental mode	AB	phase mode
counter	max frequency	counter	max frequency
4	80KHz/10KHz	4	50KHz/5KHz

### XDM series motion control structure diagram

#### Multi-axis independent control structure diagram

# us RS-232 Modbus RS-485 XDM motion control

#### Multi-axis linkage motion control structure diagram





stacking, removing. Besides, it also includes counting and printing on the product. The packing machine can improve the production efficiency and reduce labor intensity, be suitable for mass production.

chemical, pesticide, cosmetics, etc. The machine has intelligent mechanical torque controlling, easy to adjusting and operation. The worker only needs to put the cap on the bottle, the caps will be auto-tightened by three groups of twisting wheels when the bottle is moving forward. It is fit for single production or attachment production.



at the same time. It used servo system to improve the precision, product consistency and production efficiency.



#### **Casting machine**



This machine can heat the pouring object, then control 2-axis or 3-axis path position through linear or circular interpolation function and pour the object onto the product for splicing and sealing.



#### Edge grinding machine



The machine can grind different size and shape of metal edge through linear and circular interpolation function. It contains the coarse grinding, fine grinding, polishing in one process. It has long service life and high efficiency, the shaping is ruled.

#### **Glass cutting machine**



This machine can control 2-axis or 3-axis path position through linear or circular interpolation function. The laser machine which is processing the organic glass has fast cutting speed, high precision, accurate positioning. It can produce artware, model toys, panel lens case, advertising light box, packing box, etc.

# **XDC** series motion fieldbus controller

#### X-NET motion control fieldbus



#### XDC system control structure diagram





The manipulator is widely used in industry production, medical treatment, entertainment service, military, semiconductor manufacturing, space exploration. Although the shape is different, they have the same characteristics which is receiving instructions and point positioning in 2D or 3D space.





### X-NET fieldbus control system

#### X-NET fieldbus

The fieldbus replaced the traditional Modbus and free format communication makes the system faster and reliable. The wiring also become easy. The nodes can up to 32 in single network, different network can communicate with each other



#### Network mode

Factory monitoring network, token structure, real-time multi-master station system. Multi-control, configuration or visual system can operate with each other on the same bus. Any node in the network has access right (token), no need external requests to send and receive data.

#### Communication speed and distance

The field bus communication speed and medium is related to the site environment The communication distance has limit as the field bus transferring signal is electricity. The distance is 100m at 3Mbps speed and using XINJE cable. The distance can be 1000m at 192kbps speed. The communication speed can up to 600bit~3Mbit



#### Three-servo packing machine



The packing machine can pack the product, the process includes filling, packing, sealing and before and after procedures such as cleaning, stacking, removing. Besides, it also includes counting and printing on the product. The packing machine can improve the production efficiency and reduce labor intensity, be suitable for mass production.



#### **CNC** lathe



CNC lathe is one of the automatic lathe installed with program control system which can process the special program and code then translate to digital code and input to CNC device. The CNC device will process the information and output various signals to control the lathe motion to produce the parts as the drawing. The CNC lathe is fit for complicated, accurate and different type of parts, is one type of flexible high-performance lathe

- XD2, XD3, XD5, XDM, XDC all support X-NET fieldbus.
- I/O numbers can up to 292 inputs and 280 outputs through the extension
- modules.
- X-NET fieldbus is token ring structure.
- Any node in the network who got the token can send message to other node.
- The speed can up to 3Mbps.



#### Shield

The shield cable of field bus X-NET must connect to the ground. If the high frequency is serious, it can multi-point-capacitance connect to the ground, cannot directly connect to the ground to avoid ground return current. The shield twin-core cable no need shield but it needs to shield under strong electromagnetism emission environment (automobile industry) to improve the compatibility of electromagnetism. The shielding line and foil must connect the both ends to the ground and cover with large area of shielding wiring to keep good conductivity. The data line must isolate with the high voltage line.

#### Isolation

The electrical signal of field bus X-NET is electrical isolated with the equipment. If the high voltage input in the network, all the equipment bus transceiver will damage. If there is no isolation, all the equipment circuits will damage.

#### Intelligent and autonomous

The fieldbus X-NET can process various parameters, running state and error information. It has high intelligence. It can auto-control the system, diagnosis the running status and send the error information to the control center, decrease the maintenance workload, improve the system reliability. Users can check the device running status, the maintenance information, find the error reason and solve the problem earlier. Finally it can save the cost.

#### Improve the accuracy and reliability

Compared with the analog signal, fieldbus device is intelligent, digitization. It improves the accuracy and reliability of whole system, reduces the transmission error. The system structure is simple, devices and wiring decreased, field meter function enhanced, signal transmission decreased. As the device standardization and function modularization, the system design and rebuilding is easy.

#### Powerful system expansion

The fieldbus can auto-identify the device reduction or addition, no need to connect new cable and cut the power supply.

#### Open system

XD series PLC, TN series HMI, DS3E and DS5 series servo drive and frequency inverter have fieldbus X-NET function which can meet most customers' requirements. XINJE company will cooperate with other instrument manufacturers, different devices can interchange information. XINJE products can match more products.

#### More communication stations

There can be 127 station numbers in the field bus X-NET system.

#### Save the installation cost

The field bus wiring is very simple. One pair of twisted pair cable can connect multi-devices, save the cables, terminals, slot box, bridges, decrease the workload of wiring design and joint proofreading. It saves the installation and maintenance cost. The system structure is simple, support linear and ring topology, save the time of project design, drafting, cable laying and hardware manage files.

#### Cable option

The transmission is affected by electromagnetic environment. XINJE cable is shield twin-core or optical fiber which can reach the standard speed and distance. (0.3mm2 and larger multi-strand copper shielded wire is recommended)

#### Connector

PLC terminal (A, B), extension BD board XD-NE-BD, XD-NO-BD make the connection faster, improve the working efficiency, easy to maintenance.

#### Terminal matching

The field bus X-NET has reflection phenomenon just like all the electromagnetic signal. Both ends of bus network segment must use resistor ( $120\Omega$ ) to absorb the radiation, make the correct voltage and ensure the communication.

#### Outstanding cost performance

Users have to spend lots of money for the fieldbus project in nowadays industrial control industry. The XINJE products all have fieldbus X-NET inside, it no needs extra costs. It will not limit by product brand.



### Flexible network topology

Support various network topology structures including star, line, star and line integrated, ring.

the ring topology



Multi-network structure







### Integrated network structure



#### X-NET fieldbus

XINJE XD all series of PLC support X-NET fieldbus, which has the features of intelligent, digital and strong stability. The max speed can up to 3M, the wiring and design is easy, reconsitution is simple.

#### X-NET motion fieldbus

XINJE XD all series of PLC support X-NET motion fieldbus, which can high speed connect servo system, be fit for multi-axis control, high speed and complicated motion applications. The max axis can up to 20, the max speed can up to 3Mbps.

#### MODBUS

Support standard Modbus serial port communication, easy to connect other brand of products. It contains RS232, RS485 and free format communication which can be selected as actual applications.

Support Modbus-TCP protocol, use together with XC series PLC to connect automation system with GPRS or GSM network. It is fit for distributed system and remote monitoring.

GPRS

# WIFI/433M



#### WIFI provides the wifi network that other nodes can access and high-speed wireless monitor the device in it. 433M means decreasing the frequency to improve the penetration and tranferring distance, get better wireless communication effect.

#### MODBUS-TCP

Support Modbus-TCP protocol, the automation devices connect to each other via the Ethernet. It has better communication performance and makes a widely range of open network.

#### NEW XD/EPPro edit tool

#### Support XD all series of products

• XD/EPPro software is suitable for XD, XE series PLC, make PLC program, configure the network module. extension module, extension BD and left extension module

PLC Config	#1 XD/E-E16X16Y	Select: XD/E-E16X16Y	✓ Cancel
PLC Serial Port	#2 no module #3 no module	Parameter	Value
BO ED	#4 no module	10-13 Filtering time(ms)	10
- ISE Module	#5 no module #6 no module	14-17 Filtering time(ms)	10
Tro L/O	=7 no module	10-13 Filtering time(ms)	10
-Img Pulse	#8 no module #9 no module	24-27 Filtering time(ms)	10
	=10 no module	10 Logie	positive logic
	#11 no module #12 no module	Il logie	positive logic
	#13 no module	12 logic	positive logic
	#14 no module	X3 logic	positive logic
	#15 no module #16 no module	14 logic	positive logic
		X:10000-10017, Y:10000-10017	
		Read From PLC Write To PLC	OK Cancel

#### Panel configuration

• Easy to write the complicated instruction ► XD/EPPro software provides easy editing platform for the complicated instructions including PID, 100-segment high speed counter interruption, electronic cam and so on.



• Easy to configure the pulse instruction XD/EPPro software has PLSR pulse instruction configuration interface which can configure all the pulse functions

Enhanced password function

• The password can block the program uploading,

protect the intellectual property right of user. The

program damage.

PLC Config PLC Sent PLC

password is added to the program downloading to avoid

OK Cancel

data start address:	00	user parans address:	D100	system parans	К1	autout	YD		
node.	relative ~	stat execute section count.	0	Config					
Add Delete	Upwards D	ownwards							
	frequence	pulse count		vait condition	_	**	át.	jung register	-
	ra educera	past ious		The monthly is		rep	ster	register	11
	a represe	Part room			ite To PL		ster		

#### Powerful programming language

• Support ladder chart and instruction, the two modes can switch to each other

•Support C programming in XD/EPPro, no need to use C programming software



#### **XD/EPPro serial port**

• Can configure the serial port from COM1 to COM256 Support Modbus-RTU and Modbus-ASCII protocol

• Support free format communication

#### **Program capacity** calculation

• Programmer can know the program capacity accurately.

#### • C library contains more C instructions which can be called directly.

• new function advanced save can encrypt the

File Edit Search View O

) New Project Ctrl+N

**Close Project** Save Project Ctrl+S

Save Project As

Advanced Save

• pulse configuration guide

Each palse paratise p

Sates: the project tree it evittem in the ML Palse instruction RIS, FISE 78

Prev Net DK Care

► The guide will help user to set the pulse

Copen Project

program notes.

parameters.

Comor paravelar - Put de daran - Nar esta de aran - Nar esta desarro cargo Geor desarro cargo - Banar da an - Ganta y alea - Ganta y alea - Canta y al

C · S 🔜 🭳 🔍 🗖 🕼 😫

#### **Rich downloading function**

• The data will not be reset, I/O will not be OFF when downloading online, the PLC will auto-run after downloading. User can choose the downloading data type.

#### **XD2** series PLC

# Basic small PLC

7 inputs, 8 outputs 2 channels 200KHz high speed pulse output Faster processing speed

Cannot support extension module, BD and ED



#### **XD3 series PLC**

Economical small PLC	<ul> <li>max I/O numbers are 380</li> <li>2 channels 200KHz high speed</li> <li>16 points model cannot support</li> </ul>
Economical small PLC	<ul> <li>Faster instruction processing s</li> <li>Rich extension functions</li> </ul>

model								spe	cificati	on						
XD3-16R-E	- <u>AC</u> -	8	â	$\odot$	RS485 XXXX	RS232	ጮ	<b></b>	<b>_</b> 131			<mark>≋</mark> 10	1	<mark>}</mark> 20	<b>≯</b> 6	fieldbus XNET
XD3-16R-C	- <u>DC</u> -	8	8	$\odot$	RS485	RS232	<b>®&gt;</b>	<b></b>	<b>_</b> 131			ĝ <mark>10</mark>	1	<b>5</b> 20	<mark>≯</mark> 6	fieldbus XNET
XD3-16T-E	-AC-	8	8	$\odot$	RS485	RS232	()>	<b></b>	<u>_131</u>			<mark>≋10</mark>	1	<b>¥</b> 20	<del>}</del> 6	fieldbus XNET
XD3-16T-C	- <u>DC</u> -	8	8	$\odot$	RS485	RS232	()>	<b></b>	<u>_131</u>	<b>121</b> ,		<mark>≋10</mark>	1	<mark>}</mark> 20	<mark>≯</mark> 6	fieldbus XNET
XD3-16RT-E	AC-	8 1		$\odot$	RS485	RS232	()>	<b></b>	<b>_131</b>			∭ <mark>10</mark>	1	<b>¥</b> 20	<mark>≯</mark> 6	fieldbus XNET
XD3-16RT-C	_ <mark>DC</mark> _	<b>₿</b>	8	$\odot$	RS485	RS232	()>	<b></b>	<b>_</b> []	<b>121</b> ,		∭ <mark>10</mark>	1	<b>5</b> 20	<del>≫</del> 6	fieldbus XNET
XD3-16PR-E	AC-	8	8	$\odot$	RS485	RS232	₿⇒	<b></b>	<b>_</b> []]			<mark>≋10</mark>	1	<mark>&gt;</mark> 20	<b>≯</b> 6	fieldbus XNET
XD3-16PR-C	- <u>DC</u> -	8		$\odot$	RS485	RS232	(₿>>	<b></b>	<u>_131</u>			<mark>≋10</mark>	1	<b>¥</b> 20	<del>×</del> 6	fieldbus XNET
XD3-16PT-E	AC-	8	8	$\odot$	RS485	RS232	()>	<b></b>	<b>_</b> 131	<b>121</b> ,		<mark>≋</mark> 10	1	<mark>}</mark> 20	<del>}</del> 6	fieldbus XNET
XD3-16PT-C	-00-	8		$\odot$	RS485 XXXX	RS232	()>	ø	<b>_</b> []]			ĝ <mark>10</mark>	1	<b>¥</b> 20	<mark>≫</mark> 6	fieldbus XNET
XD3-16PRT-E	AC-	8	Å	$\odot$	RS485 XXXX	RS232	()>	<b></b>	<u>_131</u>	<b>121</b> ,		ĝ <mark>10</mark>	1	<mark>&gt;</mark> 20	<b>≯</b> 6	fieldbus XNET
XD3-16PRT-C	- <u>DC</u> -	8	8	$\odot$	RS485	RS232	()>	<u></u>	<b>_</b> 131	<b>121</b> ,		<mark>≋10</mark>	1	<b>5</b> 20	<mark>≫</mark> 6	fieldbus XNET
XD3-24R-E	-AC-	14 V	10	$\odot$	RS485	RS232	<b>®&gt;</b>	<b></b>	<b>_</b> []		1	<mark>≋</mark> 10	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
XD3-24R-C	-DC-	14	10	$\odot$	RS485	RS232	®⇒	<b></b>	<b>_</b> 131		1	≌ <mark>10</mark>	1	<mark>}</mark> 20	<b>X</b> 10	fieldbus XNET
XD3-24T-E	-AC-	14	10	$\odot$	RS485	RS232	()>	<b></b>	<b>_</b> 131	<b>12</b> ,	1	<mark>≋</mark> 10	1	<mark>&gt;</mark> 20	<mark>) ×</mark> 10	fieldbus XNET
XD3-24T-C	DC	14	10	$\odot$	RS485	RS232	()≫	<b></b>	<b>_</b> []]	<b>121</b> ,	1	≌ <mark>10</mark>	1	<mark>}</mark> 20	<b>×</b> 10	fieldbus XNET
XD3-24RT-E	-AC-	14 †	10	$\odot$	RS485	RS232	()>	<b></b>	<u>_131</u>		1	≌ <mark>10</mark>	1	<b>7</b> 20	<b>×</b> 10	fieldbus XNET
XD3-24RT-C	-00-	14	10	$\odot$	RS485	RS232	(0>>	<b></b>	<b>_</b> 131	<b>12</b> ,	1	<mark>≋</mark> 10	1	<mark>&gt;</mark> 20	<mark>) ×</mark> 10	fieldbus XNET
XD3-24PR-E	-AC-	14	10	$\odot$	RS485 XXXX	RS232	ጮ	<b></b>	<b>_1</b> 31		1	≌ <mark>10</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
XD3-24PR-C	- <u>DC</u> -	14	10	$\odot$	RS485	RS232	₿⇒	ø	<b>_131</b>		1	≌ <mark>10</mark>	1	<mark>&gt;</mark> 20	<mark>) ×</mark> 10	fieldbus XNET
XD3-24PT-E	-AC-	14	10	$\odot$	RS485	RS232	ତ⇒	ø	<b>_131</b>		1	<mark>≋10</mark>	1	<mark>&gt;</mark> 20	<mark>) ×</mark> 10	fieldbus XNET
XD3-24PT-C		14 V	10	$\odot$	RS485	RS232	☞	<b></b>	<u>_131</u>		1	≌ <mark>10</mark>	1	<b>&gt;</b> 20	<b>X</b> 10	fieldbus XNET
XD3-24PRT-E	- <u>AC</u> -	14 V	10	$\odot$	RS485	RS232	()>	<b></b>	<u>_131</u>	<b>121</b> ,	1	∭ <mark>10</mark>	1	<b>5</b> 20	<b>¥</b> 10	fieldbus XNET
XD3-24PRT-C	_ <mark>_00</mark> _	14 †	10	$\odot$	RS485	RS232	()>	<b></b>	<u>_131</u>	<b>121</b> ,	1	∭ <mark>10</mark>	1	<b>5</b> 20	<b>¥</b> 10	fieldbus XNET
XD3-32R-E	- <u>AC</u> -	18 V	14	$\odot$	RS485	RS232	ጮ	<b></b>	<u>_</u> []		1	≌ <mark>10</mark>	1	<b>7</b> 20	<mark>) ×</mark> 10	fieldbus XNET
XD3-32R-C	_ <mark>_00</mark> _	18 V	14	$\odot$	RS485	RS232	ഭ⇒	<b></b>	<u>_</u> []		1	∭ <mark>10</mark>	1	<b>5</b> 20	<b>X</b> 10	fieldbus XNET
XD3-32T-E	-AC-	18 †	14	$\odot$	RS485	RS232	☞	<b></b>	<b>_131</b>		1	≋ <mark>10</mark>	1	<b>5</b> 20	<b>X</b> 10	fieldbus XNET
XD3-32T-C	_ <mark>DC</mark> _	18	14	$\odot$	RS485	RS232	☞	<b></b>	<b>_</b> []]	<b>121</b> ,	1	≝ <mark>10</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
XD3-32RT-E	-AC-	18 V	14	$\odot$	RS485	RS232	<b>()</b> >	<b></b>	<b>.</b> 🖪	<b>121</b> ,	1	∭ <mark>10</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
XD3-32RT-C		18 V	14	$\odot$	RS485 XXXX	RS232	()>	<b></b>	<b>,</b> 🚹	<b>121</b> ,	1	<mark>≋10</mark>	1	<mark>7</mark> 20	<mark>) ×</mark> 10	fieldbus XNET
XD3-32PR-E	-AC-	18 V	14	$\odot$	RS485 XXXX	RS232	(€>	ø	<b>,</b> 🛐		1	<mark>≋10</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
XD3-32PR-C	_ <u>DC</u> _	18 V	14	$\odot$	RS485 XXXX	RS232	⊗	<b></b>	<b>,</b> 🚹		1	≌ <mark>10</mark>	1	<mark>7</mark> 20	<b>×</b> 10	fieldbus XNET
XD3-32PT-E	AC-	18	<b>A</b> 14	$\odot$	RS485	RS232	(>>	<b></b>	<b>_</b> 131	<b>12</b> ,	1	≌ <mark>10</mark>	1	<b>&gt;</b> 20	<b>×</b> 10	fieldbus XNET

better

Good compatibility

XD/EPPro software.

• XC series PLC program can be

transformed to XD program through

convert XC project file to XD project file?

OK Cancel





or	۱						
	<b></b>	.13		<b>*</b> 20	<b>×</b> 6	fieldbus XNET	
	<b></b>			<mark>/</mark> 20	<b>×</b> 6	fieldbus XNET	
	<b></b>	-131	<b>121</b> ,	<b>7</b> 20	<b>×</b> 6	fieldbus XNET	
	<b></b>	<u>, 131</u>	<b>121</b> ,	<b>¥</b> 20	<b>×</b> 6	fieldbus XNET	
	_					fieldbus	_

320 timer interruption 320 external interruption

ed pulse output ort right extension module speed

model								speci	fication							
D3-32PT-C	_ <u>DC</u> _	18	14	$\odot$	RS485 XXXX	RS232 XXXX	☞	<u></u>		<b>2</b> ,	1	<b>≋</b> 10	1	<b>2</b> 0	<b>X</b> 10	fieldbus XNET
D3-32PRT-E	-AC-	1		$\overline{\mathbf{O}}$	RS485	RS232	0>	ø	<b>.</b> 131		1	≝ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
D3-32PRT-C	_ <u>DC</u> _	18		$\odot$	RS485	RS232	0>	<u></u>	<b>.</b> 131		1	≝ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
D3-48R-E	-AC-	28	20	$\overline{\mathbf{O}}$	RS485	RS232	8>	<u></u>	<b>_</b> ]]]		2	<b>≋</b> 10	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
D3-48R-C	-DC-	28	20	$\odot$	RS485	RS232	<b>®&gt;</b>	<u></u>	<b>_</b> []]		2	∰ <mark>10</mark>	 1≋	<b>2</b> 0	<b>X</b> 10	fieldbus XNET
D3-48T-E	-AC-	28	20	$\odot$	RS485	RS232	ĵ≫	-	<u>, 131</u>		2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>X</b> 10	fieldbus XNET
D3-48T-C	_ <u>DC</u> _	28	20	$\odot$	RS485	RS232	≫	-	<u>, 131</u>	<b>121</b>	2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
D3-48RT-E	-AC-	28	20	$\odot$	RS485	RS232	()>	-	<u>_</u> []]		2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>X</b> 10	fieldbus
D3-48RT-C	_ <b>DC</b> _	28	20	$\odot$	RS485	RS232	0>	-	<b>_</b> 131		2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
D3-48PR-E	-AC-	28	20	$\odot$	RS485	RS232	8>	ø	<b>_</b> 131		2	≝ <mark>10</mark>	1	<b>\$</b> 20	<b>X</b> 10	fieldbus
D3-48PR-C	_ <u>DC</u> _	28	20	$\odot$	RS485	RS232	(₿>>	ø	<b>_</b> []]		2	≝ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbus
D3-48PT-E	-AC-	28	20	$\odot$	RS485	RS232 XXXX	ĵ≫	ø	<b>_</b> []]		2	∰ <mark>10</mark>	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
D3-48PT-C	-00-	28	20	$\odot$	RS485	RS232 XXXX	()≫	<u></u>	.131		2	≝ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
D3-48PRT-E	-AC-	28	20	$\odot$	RS485	RS232	<b>()&gt;</b>	<u></u>	<u>, 131</u>		2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>×</b> 10	fieldbu: XNET
D3-48PRT-C	_ <u>DC</u> _	28	20	$\odot$	RS485	RS232 XXXX	()>	<u></u>	<b>_</b> 131		2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>X</b> 10	fieldbus XNET
D3-60R-E	-AC-	36	24	$\odot$	RS485	RS232	(₿>		<b>_</b> []		2	≝ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbu: XNET
D3-60R-C	_ <u>DC</u> _	36	24	$\odot$	RS485	RS232	₿>		<b>_</b> []		2	∰ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbu: XNET
D3-60T-E	-AC-	36	24	$\odot$	RS485	RS232	☞		<b>_</b> []		2	≣ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbu: XNET
D3-60T-C	- <u>DC</u> -	36	24	$\odot$	RS485	RS232	☞		<b>_</b> [3]		2	∭ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbu: XNET
D3-60RT-E	-AC-	36	24	$\odot$	RS485	RS232	()>				2	<b>≋</b> 10	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
D3-60RT-C	- <u>DC</u> -	36	24	$\overline{\mathbf{O}}$	RS485	RS232 XXXX	<b>&gt;</b>	-	<b>_</b> 131	<b>121</b> ,	2	≝ <mark>10</mark>	1	<b>\$</b> 20	<b>X</b> 10	fieldbus XNET
D3-60PR-E	-AC-	36	24	$\odot$	RS485	RS232 XXXX	8>	ø	<b>_</b> 13		2	∰ <mark>10</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
D3-60PR-C	- <u>DC</u> -	36	24	$\odot$	RS485	RS232 XXXX	8>	<b></b>	<b>_</b> 131		2	≝ <mark>10</mark>	1	<b>5</b> 20	<b>X</b> 10	fieldbus XNET
D3-60PT-E		36	24	$\odot$	RS485	RS232 XXXX	ĵ≫	ø	<b>,</b> 🖪		2	≝ <mark>10</mark>	1	<b>*</b> 20	<b>X</b> 10	fieldbus XNET
D3-60PT-C	<b>DC</b>	36	24	$\odot$	RS485	RS232 XXXX	ĵ≫	<b></b>	<b>,</b> 🖪		2	≝ <mark>10</mark>	1	<b>&gt;</b> 20	<b>X</b> 10	fieldbus XNET
D3-60PRT-E		36	24	$\odot$	RS485	RS232	0>	<b></b>	<b>.</b> 131		2	<b>≋10</b>	1	<mark>}</mark> 20	<b>X</b> 10	fieldbu: XNET
D3-60PRT-C	-DC-	36 V	24	$\odot$	RS485	RS232 XXXX	<b>*</b>	<b></b>	<b>,</b> 131	<b>121</b> ,	2	≣ <mark>10</mark>	1	<b>¥</b> 20	<b>X</b> 10	fieldbus XNET
D3-20T3TC-E	-AC-	8	12	$\odot$		RS232 XXXX	ĵ≫	<b></b>	<b>.</b>	<b>121</b> ,				<b>5</b> 20	<b>×</b> 6	
D3-20T3TC-E(S)	-AC-	8	12	$\odot$	RS485 XXXX	RS232 XXXX	☞	<u></u>	.,[2]					<b>7</b> 20	≯6	
C – AC power supply	18 ▼ inpu ▲ outp		) () ()			<sup>232</sup> RS232 485 RS485	🕸 NPI	_	pulse input		t extension		motion fieldb	IET fieldbus <sup>us</sup> NET motion		
BD board	real-	time cloc	k 💮	<ul> <li>transisto</li> </ul>	r and relay	output	<mark>∛</mark> 20 tir	ner interru	uption 🄀 10	external int	erruption					

#### XDM series PLC

#### Powerful motion control PLC

- Max I/O numbers are 572
  4/10 channels 200KHz high speed pulse output
  Support 16 right extension modules
  Support linear, circular interpolation
  Faster processing speed



model							S	peci	ficatio	n						
XDM-24T4-E	-AC-	14	10	$\odot$	RS485 XXXX	RS232 XXXX	()>	<b></b>	<b>.</b>	<b>14</b> ,	1	∰ <mark>16</mark>	1	<b>7</b> 20	<b>X</b> 10	fieldbus XNET
XDM-24T4-C	- <u>DC</u> -	14	10	$\odot$	RS485 XXXX	RS232 XXXX	☞	<b></b>	<b>.</b>		1	<b>≋</b> 16	1	<b>2</b> 0	<b>X</b> 10	fieldbus XNET
XDM-32T4-E		18 V	14	$\odot$	RS485	RS232	()>	<b></b>	<b>_</b>		1	<b>≋</b> 16	1	<b>2</b> 0	<b>X</b> 10	fieldbus XNET
XDM-32T4-C	- <u>DC</u> -	18 V	14	$\odot$	RS485 XXXX	RS232 XXXX	☞	<b></b>	<b>.</b>		1	<b>≋</b> 16	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
XDM-60T4-E		36 V	24	$\odot$	RS485	RS232	☞	<b></b>	<b>_</b>	<b>141</b>	2	<mark>≋16</mark>	1	<b>2</b> 0	<b>X</b> 10	fieldbus XNET
XDM-60T4-C		36	24	$\odot$	RS485	R\$232 XXXX	ତ⇒	<b></b>	<b>_</b>	<b>14</b> ,	2	<b>≋</b> 16	1	<b>/</b> 20	<b>×</b> 10	fieldbus XNET
XDM-60T10-E		36	24	$\odot$	RS485	RS232	ତ⇒	<b></b>	<b>_10</b>	<b>10</b> ,	2	≣ <mark>16</mark>	1	<b>&gt;</b> 20	<b>X</b> 10	fieldbus XNET
XDM-60T10-C		36 V	24	$\odot$	RS485	RS232 XXXX	ତ⇒	<b></b>	<b>_1</b>	<b>10</b> ,	2	∰ <mark>16</mark>	1	<b>2</b> 0	<b>X</b> 10	fieldbus XNET
AC power supply	input		ᢙ	transistor	output 🗙	32 RS232	\land NPN	<b>,</b> 13	pulse inp	ut	right exte	nsion modul	e XNE	aldbus TX-NET fi n fieldbus	eldbus	
DC power supply	output		⊗	relay outp	ut XX	🗙 RS485	🚯 PNP	<b>[2</b> ],	pulse out	put 1	left exten	sion module	XNE	T X-NET	motion fieldb	us
BD board	🕒 real-tin	ne clock	0>	transistor	and relay o	utput	<mark>≯</mark> 20 time	er interru	uption 🄰	10 externa	ıl interrup	tion				

#### XD5 series PLC

XD3 soft component updated PLC	<ul> <li>Max I/O numbers are 572</li> <li>2 to 6 channels 200KHz hig</li> <li>Large capacity of program a</li> <li>Faster processing speed</li> <li>Rich extension function</li> </ul>
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model								spe	cificat	on						
D5-24R-E	- <u>AC</u> -	14 V	10	$\odot$	RS485 XXXX	RS232	₿⇒	極	<b>_</b> ]]]		1	∰ <mark>16</mark>	1	<b>7</b> 20	<b>×</b> 10	fieldbus XNET
D5-24R-C	- <u>DC</u> -	14	10	$\odot$	RS485	RS232	₿⇒	痧	<b>_</b> 131		1	<mark>≋16</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-24T-E	-AC-	14	10	$\odot$	RS485	RS232	☞	⑳	<u>_131</u>		1	∭ <mark>16</mark>	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
D5-24T4-E	- <u>AC</u> -	14	10	$\odot$	RS485	RS232	ĵ≫	痧	<b>.</b>		1	∰ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
D5-24T-C	- <u>DC</u> -	14	10	$\odot$	RS485	RS232	ĵ≫	<b></b>	<b>_</b> 13		1	¥16	1	<b>2</b> 0	<b>×</b> 10	fieldbus XNET
D5-24T4-C	- <u>DC</u> -	14	10	$\odot$	RS485	RS232	;>>	痧	-11		1	<b>≋</b> 16	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-32R-E	- <u>AC</u> -	18	14	$\odot$	RS485	RS232	₿>		<b>_</b> 131		1	<mark>≋16</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-32R-C	- <u>DC</u> -	18	14	$\odot$	RS485 XXXX	RS232	<b>®&gt;</b>	痧	<b>_</b> 131		1	<b>≋</b> 16	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-32T-E	- <mark>AC</mark> -	18	14	$\odot$	RS485	RS232	()>		<b>,</b> 131	<b>1</b>	1	∰ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-32T4-E		18	14	$\odot$	RS485	RS232	()>		<b>.</b>	<b>1</b> .	1	∰ <mark>16</mark>	1	<mark>7</mark> 20	<b>×</b> 10	fieldbus XNET
D5-32T-C	- <u>DC</u> -	18	14	$\odot$	R\$485	RS232	()>	ø	<b>_131</b>	<b>1</b>	1	∭ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
D5-32T4-C	DC	18	14	$\odot$	RS485	RS232	☞		<b>_</b> 141		1	¥ <mark>€16</mark>	1	<mark>7</mark> 20	<b>×</b> 10	fieldbus XNET
D5-48R-E	-AC-	28	20	$\odot$	RS485	RS232	<b>®&gt;</b>	愈	<b>_</b> 13		2	¥ <mark>€16</mark>	1	<mark>7</mark> 20	<b>×</b> 10	fieldbus XNET
D5-48R-C	- <u>DC</u> -	28	20	$\odot$	RS485	RS232	(₿>>	痧	<b>_</b> 13		2	<b>≋</b> 16	1	<mark>&gt;</mark> 20	<b>¥</b> 10	fieldbus XNET
D5-48T-E	- <u>AC</u> -	28	20	$\odot$	RS485	RS232	ĵ≫	痧	<b>,</b> 🖪		2	∭ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-48T-C	- <b>DC</b> -	28	20	$\odot$	RS485	RS232	ĵ≫	痧	<b>_</b> []		2	∭ <mark>16</mark>	1	<mark>/</mark> 20	<b>×</b> 10	fieldbus XNET
D5-48T6-E	- <u>AC</u> -	28	20	$\odot$	RS485	RS232	()>	痧	<b>,</b> 61		2	∰ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-48T6-C	- <u>DC</u> -	28	20	$\odot$	RS485	RS232	ĵ≫		<b>,</b> [6]		2	∭ <mark>16</mark>	1	<mark>7</mark> 20	<b>X</b> 10	fieldbus XNET
D5-60R-E	- <u>AC</u> -	36 V	24	$\odot$	RS485	RS232	₿⇒	<b></b>	<b>,</b> 131		2	∭ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-60R-C	- <u>DC</u> -	36	24	$\odot$	RS485	RS232	₿⇒	痧	<b>_</b> 131		2	<b>≋</b> 16	1	<mark>&gt;</mark> 20	<b>×</b> 10	fieldbus XNET
D5-60T-E	-AC-	36	24	$\odot$	RS485 XXXX	RS232	ĵ>	痧	<b>_</b> ]]		2	<mark>≋</mark> 16	1	<mark>7</mark> 20	<b>×</b> 10	fieldbus XNET
D5-60T-C	-DC-	36	24	$\odot$	RS485 XXXX	RS232	0>		<b>_</b> ]]]		2	∰ <mark>16</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
D5-60T6-E	-AC-	36	24	$\odot$	RS485	RS232	ົ>	痧	<b>.</b> 161		2	<mark>∭16</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET
D5-60T6-C	-DC-	36 V	24	$\odot$	RS485 XXXX	RS232 XXXX	⊳		<b>, 161</b>	<b>61</b> ,	2	<mark>∭16</mark>	1	<mark>&gt;</mark> 20	<mark>) ×</mark> 10	fieldbus XNET
- AC power supply	inpu	ut	•	<ul> <li>transiste</li> </ul>	or output 🖁	C RS232	🔊 NPM	N	🛐 pulse ir	iput 🛒	o right ext	ension mod	iule XN	fieldbus ET X-NET	fieldbus	
DC power supply	outp	out	<b>®</b>	<ul> <li>relay ou</li> </ul>	tput 🖁	RS485	pnf	• 😰	🖕 pulse o	utput 1	🛢 left exte	nsion modu	ile XN	ion fieldbus	T motion field	bus
BD board	real	-time clo	k 🔐		or and relav		<b>1</b> 20		rruption	×10 exter						

#### XDC series PLC

Powerful motion fieldbus PLC	<ul> <li>Max I/O numbers are 572</li> <li>2 channels 200KHz high speed pu Support 16 right extension module</li> <li>Support motion fieldbus X-NET</li> <li>Faster processing speed</li> </ul>
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model								spec	ificati	on							
XDC-24T-E	- <u>AC</u> -	14 V	10	$\odot$	RS485	RS232	ᢙ	<b></b>	<b>,</b>	<b>121</b> ,	1	<mark>≋16</mark>	1	<mark>}</mark> 20	<b>X</b> 10	fieldbus XNET	motion fieldbus
XDC-24T-C	<b>DC</b>	14 V	10	$\odot$	RS485	RS232	☞	<b></b>	<b>.</b>		1	<mark>≋16</mark>	1	<mark>7</mark> 20	<b>¥</b> 10	fieldbus XNET	motion fieldbu XNET
XDC-32T-E	- <u>AC</u> -	18 V	14	$\odot$	RS485	RS232	☞	<b></b>	<b>_</b>		1	<mark>∭16</mark>	1	<mark>7</mark> 20	<b>X</b> 10	fieldbus XNET	motion fieldbu XNET
XDC-32T-C	_ <u>DC</u> _	18	14	$\odot$	RS485	RS232	ᢙ	<b></b>	<b>.</b>	<b>121</b> ,	1	<mark>∭16</mark>	1	<mark>/</mark> 20	<b>¥</b> 10	fieldbus XNET	motion fieldbu XNET
XDC-60T-E	-AC-	36 V	24	$\odot$	RS485	RS232	ᢙ			<b>121</b> ,	2	<mark>≋16</mark>	1	<mark>&gt;</mark> 20	<b>X</b> 10	fieldbus XNET	motion fieldbu XNET
XDC-60T-C	_ <u>DC</u> _	36 V	24	$\odot$	RS485	RS232	ᢙ	<b></b>	<b>.</b>		2	<mark>≋16</mark>	1	<mark>&gt;</mark> 20	<mark>) ×</mark> 10	fieldbus XNET	motion fieldbu XNET
AC power supply     DC power supply     BD board	outpu	ıt	<b>©</b> >	relay ou		232 C RS232 485 RS485 output	PN	P [2]	pulse ir pulse o	_	left exter	ension mod nsion modu uption	dule XN	fieldbus NET X-NET tion fieldbus NET X-NE			



e 572 KHz high speed pulse output ogram and soft component

25464466	
TIMIT	



ulse output les



#### **Special function extension BD board**





#### left extension module

item	specification
using environment	no corrosive gas
environment temperature	℃ ~ 60°C
storage temperature	-20~70°C
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly
dimension	25mm×100mm×89.0mm
dimension	18mm×100mm×89.0mm



XD series I/O extension module model list

#### right extension module the extension cable length can up to 1.5m

#### I/O extension

if the PLC main unit I/O numbers cannot meet the requirements, please use I/O extension module.

XD series I/O exte	nsion module specification
item	specification
using environment	no corrosive gas
environment temperature	℃ ~ 3°0
storage temperature	-20~70°C
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly
dimension	70.8mm×108mm×89.0mm 108.6mm×108mm×89.0mm

model		
NPN input	PNP input	function
XD-E8X	XD-E8PX	8 channels digital input, DC24V power supply
XD-E8YR	-	8 channels relay output, DC24V power supply
XD-E8YT	-	8 channels transistor output, DC24V power supply
XD-E8X8YR	XD-E8PX8YR	8 channels digital input, 8 channels relay output, DC24V power supply
XD-E8X8YT	XD-E8PX8YT	8 channels digital input, 8 channels transistor output, DC24V power supply
XD-E16X	XD-E16PX	16 channels digital input, DC24V power supply
XD-E16YR	-	16 channels relay output, no need power supply
XD-E16YT		16 channels transistor output, no need power supply
XD-E16X16YR-E/C	XD-E16PX16YR-E/C	16 channels digital input, 16 channels relay output, AC220V or DC24V
XD-E16X16YT-E/C	XD-E16PX16YT-E/C	16 channels digital input, 16 channels transistor output, AC220V or DC24V
XD-E32YR-E/C	-	32 channels relay output, AC220V or DC24V
XD-E32YT-E/C	-	32 channels transistor output, AC220V or DC24V
XD-E32X-E/C	XD-E32PX-E/C	32 channels digital input, AC220V or DC24V

# Input extension module XD-E8X, XD-E8PX 8 input points Rated input voltage is DC24V Response time below 20ms External wiring mode is terminal The wiring method is same to PLC main unit The P in the model name means PNP input

#### output extension module



#### I/O extension module

XD-E8X8YR, XD-E8X8YT, XD-E8PX8YR, XD-E8PX8YT		
a die fan het	8 input points	Rated input voltage is DC24V
	Response time below 20ms	The P in the model name means PNP input
	8 output points	R: relay output T: transistor output
	R response time below 10ms	T response time below 0.2ms
FORDER	R max load: resistance 3A, inductance 80VA	T max load: resistance 0.5A, inductance 12W80VA
	External wiring mode is terminal	The wiring method is same to PLC main unit76

#### analog extension module

transform the analog signal to digital or digital to analog, receive and process temperature sensor signal.		
item	specification	
using environment	no corrosive gas	
environment temperature	℃ ~ 60°C	
storage temperature	-20 ~ 70 °C	
environment humidity	5~95%RH	
storage humidity	5~95%RH	
installation	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly	
dimension	63mm×108mm×89.0mm	











#### DA type





#### mixed type

XD-E4AD2DA		
	XD-E4AD2DA 4 input channels Input voltage 0-5/0-10V Input current 0-20/4-20mA Transforming speed 2ms/channel Resolution 1/16383 Precision ± 1% Filter coefficient 0-255 Frable bil is added	2 output channels output voltage 0-5/0-10V output current 0-20/4-20mA Transforming speed 2ms/channel Resolution 1/4096 Precision ±1% Enable bit is added
	Enable bit is added	

	XD-E4AD2DA-B	
	4 input channels	2 output channels
	Input voltage 0~5/0~10V	output voltage 0~5/0~10V
	Input current 0~20/4~20mA	Transforming speed 2ms/channel
	Transforming speed 2ms/channel	Resolution 1/4096
	Resolution 1/16383	Precision ±1%
and the second se	Precision ±1%	Enable bit is added
Trencent.	Filter coefficient 0~255	
the first fi	Enable bit is added	

#### weighing extension module

transform the weighing signal to digital value

nalog input range	DC -39.06 ~ 39.06mV
esolution	1/16777216(24Bit)
tegrated precision	±0.1%
ansformation speed	0~255 times/second
ower supply	DC24V±10%,100mA
ensor excitation power supply	5VDC/120mA, can connect 4 350Ω weighing sensor in parallel
stallation mode	fix with M3 screw or install on the DIN46277(width 35mm) rail directly
imension	63mm×108mm×89.0mm
sing environment	no corrosive gas
	℃ ~ 60°C
nvironment humidity	5 ~ 95%



#### MA series remote extension module

MA series modules include digital input and output, analog input and output, temperature control. It uses RS485 port and based on Modbus protocol, can connect PLC, HMI, PLC&HMI integrated controller, and other devices supporting Modbus protocol. It is fit for temperature, flow, liquid level, pressure control, can extend up to 16 modules.

#### digital I/O

I/O extension module MA-nXnY		
model	notes	
MA-8X8YR	8 channels digital input, 8 channels digital output (relay output)	
MA-8X8YT	8 channels digital input, 8 channels digital output (transistor output)	
MA-16X	16 channels digital input	
MA-16YR	16 channels digital output (relay output)	
MA-16YT	16 channels digital output (transistor output)	

output extension module			
	MA-16YR, MA-16Y	Т	
2412523	16 output points	R: relay output T: transistor output	
81-67-5 37	The wiring method is same to PLC main unit	R max load: resistance 3A, inductance 80VA	
	External wiring mode is terminal	T response time below 0.2ms	
******** ******	R response time below 10ms	T max load: resistance 0.5A, inductance 12W80VA	

#### temperature control extension module

Pt100 thermal resistor or thermocouple temperature measurement, PID control inside.

#### Pt100 thermal resistor

#### analog extension module XD-E6PT-P general specification

item	specification
using environment	no corrosive gas
environment temperature	℃~ 60℃
storage temperature	−20 ~ 70°C
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277(width 35mm) rail directly
dimension	63mm×108mm×89.0mm

#### analog extension module XD-E6PT-P general specification

item	specification
analog input	Pt100 thermal resistor
Temperature range	−100°C ~ 500°C
Digital output range	-1000~5000, 16-bit signed value, binary
Control precision	±0.5°C
Resolution	0.1°C
Integrated precision	1% (relative max value)
Transformation speed	20ms/channel
Power supply for analog	DC24V±10%, 50mA

XD-E6PT-P		
	6 temperature input channels	Control the heating and cooling
ARE STOLEN	Self-study function	Optional sampling period
	Temperature range -100~500°C	Control precision ±0.5°C
	Resolution 0.1°C	Integrated precision ±1%
and the second se	Channel transformation speed 20ms/channel	
Tennent		I

#### TC thermocouple

#### analog extension module XD-E6TC-P general specification

item	specification
using environment	no corrosive gas
environment temperature	0°C ~ 60°C
storage temperature	-20~70°C
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277(width 35mm) rail directly
dimension	63mm×108mm×89.0mm

#### analog extension module XD-E6TC-P performance specification

item	specification		
analog input	thermocouple K, S, E, N, B, T, J, R		
Temperature range	24 0~1300℃ (type K)		
Digital output range	25 0~13000, signed 16-bit value, binary		
Control precision	±0.5℃		
Resolution	0.1°C		
Integrated precision	1% (relative max value)		
Transformation speed	20ms/channel		
Power supply for analog	DC24V±10%, 50mA		

XD-E6TCA-P				
a constant				
E Mar No. So to Mar Kar M	6 temperature input channels	Control the heating and cooling		
and the second sec	Self-study function	Optional sampling period		
	Temperature range 0~1300°C	Control precision ±0.5°C		
	Resolution 0.1°C	Integrated precision ±1%		
armenter the	Channel transformation speed 20ms/channel			



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#### XD-E2WT-A

2 weighing channels
AD transformation speed 0~255 times/second
Internal resolution 1/16777216
Display resolution 1/20000
Nonlinear error 0.01% F.S
Time drift 0.005% F.S
Integrated precision ±0.1%

annels
ation speed 0~255 times/second
ution 1/16777216
ition 1/20000
or 0.01% F.S
95% F.S
cision ±0.1%

#### XD-E1WT-A



Integrated precision ±0.1%

#### digital I/O module general specification

item	specification	
input power supply voltage	DC24V±10%	
Using environment	no corrosive gas	
Environment temperature	0°C ~ 60°C	
Environment humidity	5~95%	
Installation	fix with M3 screw or install on the DIN46277(width 35mm) rail directly	
Dimension	63mm×102mm×73.3mm	



#### input extension module



A	A-16X, MA-16PX		
	16 input points		
	Rated input voltage DC24V		
	Response time below 20ms		
	External wiring mode is terminal		
	The wiring method is same to PLC main unit		
	The P in the model name means PNP input		

#### I/O extension module

#### MA-8X8YR, MA-8PX8YR, MA-8X8YT, MA-8PX8YT



8 input points	R response time below 10ms
Rated input voltage DC24V	T response time below 0.2ms
Response time below 20ms	R max load: resistance 3A, inductance 80VA
The P in the model name means PNP input	T max load: resistance 0.5A, inductance 12W80VA
8 output points	External wiring mode is terminal
R: relay output T: transistor output	The wiring method is same to PLC main unit

#### analog I/O

LELEEL

#### analog input module MA-nAD model notes MA-4AD 4 channels, 12-bit high precision analog input (voltage/current), each channel has PID f MA-8AD-A 8 channels, 12-bit high precision analog input (current), each channel has PID function MA-8AD-V 8 channels, 12-bit high precision analog input (voltage), each channel has PID function

analog	I/O moc	lule MA-	nADmDA

Precision +0.8%

	model	notes
function	MA-2DA	2 channels, 10-bit high precision analog output (voltage/current)
	MA-4DA	4 channels, 10-bit high precision analog output (voltage/current)

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analog output module MA-nDA

nalog I/O m	odule MA-NADMDA			
model	notes			
MA-4AD2DA	4 channels, 12-bit high precisio	n analog input (voltage/current), each char	inel has PID function; 2 channels, 10	0-bit high precision analog output (voltage/curre
D type				
	MA-4AD	MA-8AD-A		MA-8AD-V
				2222
2222525	4 input channels	8 input channels	1222	8 input channels
	Input voltage 0~5/0~10V	Input current 0~20		Input voltage 0~5/0~10V
1000 and 100	Input current 0~20/4~20mA	Transformation sp	eed 20ms/channel	Transformation speed 20ms/channel
-	Transformation speed 20ms/channel	Resolution 1/4096		Resolution 1/4096
the second se				

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	MA-2DA		MA-4DA		MA-4AD2DA	
1115675	2 output channels		4 output channels		4 input channels	2 output channels
	output voltage 0~5/0~10V	And a local division of the	output voltage 0~5/0~10V	A DESCRIPTION OF	Input voltage 0~5/0~10V	output voltage 0~5/0~10V
1/1 2/2 2/2	output current 0~20/4~20mA	置	output current 0~20/4~20mA	1	Input current 0~20/4~20mA	output current 0~20/4~20mA
	Transformation speed 3ms/channel	-	Transformation speed 3ms/channel	-	Transformation speed 20ms/channel	Transformation speed 3ms/c
CONTRACTOR OF THE	Resolution 1/1024	A CONTRACTOR OF	Resolution 1/1024	ALCOLOGICAL PROPERTY OF	Resolution 1/4096	Resolution 1/1024
	Precision ±0.8%	PARARRE CLEEKE	Precision ±0.8%	CARABBE GEREESE	Precision ±0.8%	Precision ±0.8%

#### temperature control

PT100 therma	l resistor		TC thermoco	uple	
	MA-6PT-P			MA-6TCA-P	
	6 temperature input channels Self-study function Temperature range -100-50 <sup>0*C</sup> Resolution 0.1*C Transformation speed 20ms/channel	Heating and cooling control Optional sampling period Control precision ±0.1°C Integrated precision ±0.8%		6 temperature input channels Self-study function Temperature range 0-1300°C Resolution 0.1°C Transformation speed 20ms/channel	Heating and cooling control Optional sampling period Control precision ±0.1°C Integrated precision ±0.8%

# **XD** series product specifications

#### General specification of basic unit

Item	Specification
Insulation voltage	Up DC500V 2Mohm
anti-noise	Noise voltage 1000 Vp-p 1us pulse 1 minute
Air	No corrosive and flammable gas
Environment temperature	0°C~60°C
Environment humidity	5%RH~95%RH (no condensation)
Com 1	RS232, connect to upper device, HMI to debug and programming
Com 2	RS485, connect to smart meter and VFD
Installation	fix with M3 screw or install on the rail directly
Ground	The third ground (cannot connect the ground with high voltage system

- All the basic units have com1 for programming and debug.
- The rail specification is DIN46277, the width is 35mm.
- The ground is better to use single ground or sharing ground, cannot use public ground.



lte	ems	Specifications					
Program exe	cution mode	scan round mode					
Program mode		Instructions, ladder chart, C language					
Processing speed		0.05us					
Power off ret	entive	FlashROM and Li-battery (3V button battery)					
Users' program capacity**		256KB					
	Total I/O numbers	16 points					
I/O points <sup>#2</sup>	Input numbers	8 points X0~X7					
	Output numbers	8 points Y0~Y7					
Internal Coil:	s(X) <sup>®3</sup>	1280 points: X	0~X77, X10000~X11777, X20000~X20277				
Internal Coi	ls(Y) <sup>≝₄</sup>	1280 points: Y	0~Y77, Y10000~Y11777, Y20000~Y20277				
Internal Coils(M, HM)		11008 points	M0~M7999 [ HM0~HM959 ] *s				
			For Special Use SM0~SM2047				
Procedure(S)		1152 points	S0~S1023 [HS0~HS127]				
	points	672 points	T0~T575 [HT0~HT95]				
		100mS timer: set time 0.1~3276.7s					
Timer(T)	Specification	10mS timer: set time 0.01~327.67s					
		1mS timer: set time 0.001~32.767s					
	points	672 points	C0~C575 [ HC0~HC95 ]				
Counter(T)	On a sife still a	16 bits counte	r: set value K0~32,767				
	Specification	32 bits counter: set value -2147483648~+2147483647					
Data Registe	(D)	11048 words	D0~D7999 [ HD0~HD999 ] **				
Data Registe	si(D)	11046 W0105	For Special Use ** SD0~SD2047				
		5120 words	FD0~FD5119				
FlashROM F	legister (FD)	5120 WordS	For Special Use ** SFD0~SFD1999				
High speed	processing ability	High speed co	unter, pulse output, external interruption				
Password P	rotection	6 bits ASCII					
Self-diagnos	se Function	Power on self-	check, monitor timer, grammar check				

1: The users' program capacity means the maximum program capacity when encrypted downloading.
 2: I/O points mean terminal number that users can connect from outside.
 3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.
 4: Y stands for the internal output relays and can be used as middle relay when output points are exceeded.
 5: [] means the default power off retentive area, this area can't be changed.
 6: For special use means special usage registers that are occupied by system, can't be applied for other usage.

#### XD5 series basic unit performance specifications

lte	Items		Specifications						
Program exe	ecution mode	scan round mode							
Program mo	de	Instructions, ladder chart, C language							
Processing	speed	0.05us							
Power off re	tentive	FlashROM and Li-battery (3V button battery)							
Users' progr	am capacity <sup>#1</sup>	384KB							
	Total I/O numbers	24 points		32 points	48 points	60 points			
I/O points *2	Input numbers	14 points X0~X	15	18 points X0~X21	28 points X0~33	36 points X0~X43			
[	Output numbers	10 points Y0~Y	11	14 points Y0~Y15	20 points Y0~Y23	24 points Y0~Y27			
Internal Coil	s(X) <sup>⊛3</sup>	1280 points: X0	)~X77	, X10000~X11777, X20	)000~X20277				
Internal Co	ils(Y) <sup>#4</sup>	1280 points: YO	1280 points: Y0~Y77, Y10000~Y11777, Y20000~Y20277						
Internal Coils(M, HM)			MO	M0~M74999 [HM0~HM11999] **					
		92000 points	For	For Special Use SM0~SM4999					
Procedure(S)		9000 points	S0~S7999 [ HS0~HS999 ]						
	points	7000 points	T0~T4999 [HT0~HT1999]						
		100mS timer: set time 0.1~3276.7s							
Timer(T)	Specification	10mS timer: set time 0.01~327.67s							
		1mS timer: set	1mS timer: set time 0.001~32.767s						
	points	7000 points	7000 points C0~C4999 [HC0~HC1999]						
Counter(T)	One offeredian	16 bits counter	set v	set value K0~32,767					
	Specification	32 bits counter: set value -2147483648~+2147483647							
Data Dataist	(D)		D0~D69999 [HD0~HD24999] *5						
Data Regist	er(D)	100000 words	For	Special Use <sup>**</sup> SD0~SD	4999				
			FD0	~FD8191					
FlashROM	Register (FD)	14192 words	For	For Special Use SFD0~SFD5999					
High speed	processing ability	High speed cou	inter,	pulse output, external i	nterruption				
Password P	rotection	6 bits ASCII							
Self-diagno	se Function	Power on self-o	check,	monitor timer, gramma	ar check				

\*1: The users' program capacity means the maximum program capacity when encrypted downloading. #2: I/O points mean terminal number that users can connect from outside.

#3: X stands for the internal input relays and can be used as middle relay when input points are exceeded

\*4: Y stands for the internal output relays and can be used as multiple to the internal output points are exceeded.
\*5: [ ] means the default power off retentive area, this area can't be changed.
\*6: For special use means special usage registers that are occupied by system, can't be applied for other usage.



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#### XD2 series basic unit performance specifications XD3 series basic unit performance specifications

116	ems	Specifications								
Program exe	cution mode	scan round mo	de							
Program mod	ie	Instructions, ladder chart, C language								
Processing s	peed	0.05us								
Power off rete	Power off retentive		FlashROM and Li-battery (3V button battery)							
Users' progra	Users' program capacity <sup>®1</sup>		256KB							
	Total I/O numbers	16 points	24 points	32 points	48 points	60 points				
I/O points **2	Input numbers	8 points X0~X7	14 points X0~X15	18 points X0~X21	28 points X0~33	36 points X0~X43				
	Output numbers	8 pointsY0~Y7	10 points Y0~Y11	14 points Y0~Y15	20 points Y0~Y23	24 points Y0~Y27				
Internal Coils	s(X) <sup>*3</sup>	1280 points: X0	~X77, X10000~X11	777, X20000~X202	77					
Internal Coil	ls(Y) <sup>⊛4</sup>	1280 points: Y0	~Y77, Y10000~Y11	777, Y20000~Y202	77					
Internal Call	(M HM)	11008 points	M0~M7999 [ HM0~HM959 ] <sup>%s</sup>							
Internal Cons	Internal Coils(M, HM)		For Special Use ** SM0~SM2047							
Procedure(S)		1152 points	S0~S1023 [HS0~HS127]							
	points	672 points	T0~T575 [HT0~HT95]							
		100mS timer: set time 0.1~3276.7s								
Timer(T)	Specification	10mS timer: set time 0.01~327.67s								
		1mS timer: set time 0.001~32.767s								
	points	672 points	C0~C575 [HC0~HC95]							
Counter(T)	Specification	16 bits counte	r: set value K0~32,1	767						
	Specification	32 bits counter: set value -2147483648~+2147483647								
Data Registe	(D)	11048 words	D0~D7999 [ HD0~HD999 ] 👫							
Data Registe	si(D)	11048 Words	For Special Use <sup>≪</sup> SD0~SD2047							
		5120 words	FD0~FD5119							
FlashROMR	tegister (FD)	5120 Words	For Special Use <sup>∰6</sup> SFD0~SFD1999							
High speed p	processing ability	High speed co	unter, pulse output	, external interruption	on					
Password Pr	rotection	6 bits ASCII								
Self-diagnos	se Function	Power on self-	check, monitor time	er, grammar check						

#1: The users' program capacity means the maximum program capacity when encrypted downloading.
#2: I/O points mean terminal number that users can connect from outside.
#3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.
#4: Y stands for the internal output relays and can be used as middle relay when output points are exceeded.
#5: [ ] means the default power off retentive area, this area can't be changed.
#6: For special use means special usage registers that are occupied by system, can't be applied for other usage.

#### XDM series basic unit performance specifications

Items		Specifications					
Program exe	cution mode	scan round mode					
Program mo	de	Instructions, ladder chart, C language					
Processing s	speed	0.05us					
Power off ret	tentive	FlashROM and Li-battery (3V button battery)					
Users' progra	am capacity <sup>®1</sup>	384KB					
	Total I/O numbers	24 points		32 points	60 points		
I/O points 82	Input numbers	14 points X0~X	(15	18 points X0~X21	36 points X0~X43		
	Output numbers	10 points Y0~Y	′11	14 points Y0~Y15	24 points Y0~Y27		
Internal Coil:	s(X) <sup>₩3</sup>	1280 points: X0	0~X77, X1	0000~X11777, X20000~X20277	,		
Internal Coi	ls(Y) <sup>**</sup>	1280 points: Y	0~Y77, Y1	0000~Y11777, Y20000~Y20277	,		
Internal Cail	o(M_HM)	92000 points	M0~M74	-M74999 [ HM0~HM11999 ] =5			
Internal Coll	Internal Coils(M, HM)		For Special Use <sup>96</sup> SM0~SM4999				
Procedure(S	Procedure(S)		S0~S7999 [ HS0~HS999 ]				
	points	7000 points	T0~T4999 [HT0~HT1999]				
		100mS timer: set time 0.1~3276.7s					
Timer(T)	Specification	10mS timer: set time 0.01~327.67s					
		1mS timer: set	1mS timer: set time 0.001~32.767s				
	points	7000 points	7000 poin	ts			
Counter(T)	Specification	16 bits counter: set value K0~32,767					
	Specification	32 bits counter: set value -2147483648~+2147483647					
Data Registe	(D)		D0~D69999 [HD0~HD24999] **				
Data Registe	er(D)	100000 words	For Special Use <sup>66</sup> SD0~SD4999				
			FD0~FD	8191			
FlashROM F	Register (FD)	14192 words	For Special Use ** SFD0~SFD5999				
High speed	processing ability	High speed cou	inter, pulse	e output, external interruption			
Password P	rotection	6 bits ASCII					
Self-diagnos	se Function	Power on self-c	check, mor	itor timer, grammar check			

\*1: The users' program capacity means the maximum program capacity when encrypted downloading.
 \*2: I/O points mean terminal number that users can connect from outside.

3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.

\*4: Y stands for the internal output relays and can be used as microle relay men input points are exceeded.
\*5: [ ] means the default power off retentive area, this area can't be changed.
\*6: For special use means special usage registers that are occupied by system, can't be applied for other usage.

#### XDC series basic unit performance specifications

lte	ems	Specifications					
Program exe	ecution mode	scan round mode					
Program mo	de	Instructions, ladd	ler chart, C	language			
Processing	speed	0.05us					
Power off re	tentive	FlashROM and Li-battery (3V button battery)					
Users' progr	am capacity <sup>=1</sup>	384KB					
I/O points <sup>#2</sup>	Total I/O numbers	24 points		32 points	60 points		
	Input numbers	14 points X0~X1	5	18 points X0~X21	36 points X0~X43		
	Output numbers	10 points Y0~Y11	1	14 points Y0~Y15	24 points Y0~Y27		
Internal Coil	s(X) <sup>#3</sup>	1280 points: X0~	X77, X1000	00~X11777, X20000~X20277			
Internal Co	ils(Y)**	1280 points: Y0~	1280 points: Y0~Y77, Y10000~Y11777, Y20000~Y20277				
Internal Coils(M, HM)		92000 points M0~M7		0~M74999 [ HM0~HM11999 ] **			
		92000 points	For Special Use <sup>46</sup> SM0~SM4999				
Procedure(S)		9000 points	S0~S7999 [HS0~HS999]				
	points	7000 points	T0~T4999 [HT0~HT1999]				
		100mS timer: set time 0.1~3276.7s					
Timer(T)	Specification	10mS timer: set time 0.01~327.67s					
		1mS timer: set time 0.001~32.767s					
	points	7000 points	C0~C499	9 [HC0~HC1999]			
Counter(T)	Specification	16 bits counter: s	et value K0	value K0~32,767			
	Specification	32 bits counter: set value -2147483648~+2147483647					
Data Regist	or(D)	100000 words	D0~D699	00~D69999 [ HD0~HD24999 ] *5			
Data Regist	er(D)	100000 Words	For Special Use** SD0~SD4999				
			FD0~FD8	191			
FlashROM F	Register (FD)	14192 words	For Special Use <sup>84</sup> SFD0~SFD5999				
High speed	processing ability	High speed count	ter, pulse ou	utput, external interruption			
Password P	rotection	6 bits ASCII					
Self-diagno	se Function	Power on self-ch	eck, monito	r timer, grammar check			

#1: The users' program capacity means the maximum program capacity when encrypted downloading.
#2: I/O points mean terminal number that users can connect from outside.
#3: X stands for the internal input relays and can be used as middle relay when input points are exceeded
#4: Y stands for the internal output relays and can be used as middle relay when output points are exceeded
#5: [] means the default power off retentive area, this area can't be changed.

\*6: For special use means special usage registers that are occupied by system, can't be applied for other usag

#### Input specification and wiring

#### the Input includes NPN and PNP mode.

#### NPN mode specification



#### ltem Contents

PNP mode specification

#### Output specification and wiring

#### The output includes relay and transistor mode.

#### **Output specification**



#### High speed pulse output

Model	RT or T
High Speed Pulse Output Terminal	Y0, Y1(Y2/Y3)(Y4/Y5~Y10/Y11)
External Power Supply	Below DC5~30V
Action Indicator	LED
Maximum Current	50mA
Max output pulse frequency	200KHZ

## Power supply specification

#### AC power supply

Items	Content
Rated Voltage	AC100V~240V
Allowed Voltage Range	AC90V~265V
Rated Frequency	50/60Hz
Allow momentary power off time	Interruption Time≤0.5 AC cycle, interval≥1s
Impulse Current	Max 40A below 5mS/AC100V max 60A below 5ms/AC200V
Maximum Power Consumption	12W
Power Supply for Sensor	24VDC±10% 16 points max is 200mA ,32 points max is 400mA

#### DC power supply

Items	Content
Rated Voltage	DC24V
Allowed Voltage Range	DC21.6V~26.4V
Input Current (Only for basic unit)	120mADC24V
Allow momentary power off time	10msDC24V
Impulse Current	10ADC26.4V
Maximum Power Consumption	12W
Power Supply for Sensor	24VDC±10% 16 points max is 200 mA, 32 points max is 400mA

Please use the wire cable more than 2mm2 to avoid the decrease of voltage.

 Even power off in 10ms, the PLC can still keep working. But when power is off for long time or voltage abnormally decrease, the PLC will stop working, output will be OFF. When power is on again, the PLC will run automatically.

The grounding terminals on basic units and extensions are connected together, and connected to the ground well (the third kind of ground).



	XD2-16R/T												
	single phase incremental mode								AB phase mode				
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8	
max frequency	10K	10K	10K					5K	5K	5K			
4-time frequency								2/4	2/4	2/4			
Counter interruption	~	1	~					~	~	~			
X000	U							А					
X001								В					
X002													
X003		U							А				
X004									В				
X005			U										
X006										А			
X007										В			

				XD5	-24T/3	32T/48	T/60T					
		sin	gle pha	se incre	ementa	l mode			AB p	hase m	node	
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC
max frequency	80K	80K	80K					50K	50K	50K		
4-time frequency								2/4	2/4	2/4		
Counter interruption	4	~	~					~	~	~		
X000	U							А				
X001								В				
X002												
X003		U							A			
X004									В			
X005												
X006			U							А		
X007										В		
X010												
X011												
X012												
X013												

				XD5-4	48T6/6	60T6						
				ncreme	ntal mo	de		A	B phase			
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10
max frequency	80K	80K	80K	80K	80K	80K	50K	50K	50K	50K	50K	50K
4-time frequency							2/4	2/4	2/4	2/4	2/4	2/4
Counter interruption	~	~	~	~	~	~	~	~	~	~	~	~
X000	U						Α					
X001							В					
X002												
X003		U						А				
X004								В				
X005												
X006			U						А			
X007									В			
X010												
X011				U						A		
X012										В		
X013												
X014					U						A	
X015											В	<u> </u>
X016												
X017												
X020						U						A
X021												В



ordinary transistor output

Resistant load

Lamp load

OFF→ON

cuit insulatio

ax load

ni load

time	ON→OFF	Below 0.2ms
relay drive circuit		Load L DC power supply Load L DC 5-30V DC 5-30V Load

DC5~30V

LED

0.3A

8W/DC24V

DC5V 2mA

Below 0.2ms

1.5W/DC24V

optocoupler in:



8	

	/60T/R/R

		sin	gle pha	se incre	ementa	l mode		AB phase mode					
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8	
max frequency	80K	10K	10K					50K	5K	5K			
4-time frequency								2/4	2/4	2/4			
Counter interruption	~	4	4					~	~	~			
	U							Α					
								В					
X002													
X003		U							A				
X004									В				
X005													
X006			U							A			
X007										В			
X010													

>	8		
		_	
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				Х	D5-24	T4/32	T4					
			phase ii	ncreme	ntal mo	de		AE	3 phase	mode		
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10
max frequency	80K	80K	80K	80K			50K	50K	50K	50K		
4-time frequency							2/4	2/4	2/4	2/4		
Counter interruption	~	~	~	~			4	~	~	~		
X000	U						А					
X001							В					
X002												
X003		U						А				
X004								В				
X005												
X006			U						A			
X007									В			
X010												
X011				U						A		
X012										В		
X013												
X014												
X015												
X016												
X017												
X020												
X021												

		sing	gle pha	se incre	mental	mode		AB phase mode					
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC	
max frequency	80K	80K	80K	80K				50K	50K	50K	50K		
4-time frequency								2/4	2/4	2/4	2/4		
Counter interruption	~	~	~	~				~	~	~	~		
X000	U							А					
X001								В					
X002													
X003		U							А				
X004									В				
X005													
X006			U							A			
X007										В			
X010													
X011													
X012				U							A		
X013											В		

					XDN	1-60T1	0					
				single p	hase in	cremen	tal mod	de				
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC14	HSC16	HSC18	HSC20	HSC22
max frequency	80K	80K	80K	80K	80K	80K	80K	80K	10K	10K		
4-time frequency												
Counter interruption	~	~	~	~	~	~	~	~	~	~		
X000	U											
X001												
X002												
X003		U										
X004												
X005												
X006			U									
X007												
X010												
X011				U								
X012												
X013												
X014					U							
X015												
X016												
X017						U						
X020												
X021												
X022							U					
X023												
X024												
X025								U				
X026												
X027												
X030									U			
X031												
X032												
X033										U		
X034												

					XDN	1-60T1	0					
						ase mo						
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC14	HSC16	HSC18	HSC20	HSC22
max frequency	50K	50K	50K	50K	50K	50K	50K	50K	5К	5К		
4-time frequency												
Counter interruption	~	~	~	~	~	~	~	~	~	~		
X000	A											
X001	В											
X002												
X003		A										
X004		В										
X005												
X006			Α									
X007			В									
X010												
X011				A								
X012				В								
X013												
X014					A							
X015					В							
X016												
X017						Α						
X020						В						
X021												
X022							Α					
X023							В					
X024												
X025								A				
X026								В				
X027												
X030									A			
X031									В			
X032												
X033										A		
X034										В		
X035												

#### Serial port (RS232/RS485) communication parameters

Item	Parameters
Communication mode	Half duplex
Baud rate	9600bps, 19200bps (defaulted), 38400bps, 57600bps, 115200bps
Data type	Data bit: 5, 6, 7, 8(defaulted), 9 Stop bit: 1(defaulted), 1.5, 2 Parity bit: no parity, odd, even(defaulted)
Mode	RTU(defaulted), ASCII, free format, fieldbus X-NET
Station number	1-255 (defaulted is 1)
Before sending delay	1~100ms(defaulted is 3ms)
Reply overtime	1~1000ms(defaulted is 300ms)
Retry times	1~20 times(defaulted is 3 times)

### Instruction list

**Application instruction** 



#### Special instruction

Туре	Instruction	Function	
	PLSR	Multi-segment pulse output	
	PLSF	Variable frequency pulse output	
Pulse output	ZRN	Mechanical return to zero	
	PLSMV	Refresh the pulse number immediately	
	STOP	Stop the pulse	
	DMOV	Read 32 bits high speed counter	
High speed	DMOV	Write 32 bits high speed counter	
counter	CNT (_AB)	100-segment high speed counter interruption	
[	CNT (_AB)	Electronic cam	
	RST	Reset high speed counter	
	COLR	Modbus read coil	
	INPR	Modbus read input coil	
	COLW	Modbus write single coil	
Modbus	MCLW	Modbus write multi coils	
communication	REGR	Modbus read register	
	INRP	Modbus read input register	
	REGW	Modbus write single register	
	MRGW	Modbus write multi registers	
	STR	Precise timing	
Precise timing	DMOV	Read precise timing register	
	STOP	Stop precise timing	
	EI	Enable the interruption	
Interruption	DI	Disable the interruption	
	IRET	Interruption return	
	SBLOCK	Block start	
	SBLOCKE	Block end	
Sequence block	SBSTOP	Stop block	
DIOCK	SBGOON	Continue running the stop block	
	WAIT	Wait	
Write and read	FROM	Read the module	
the module	то	Write in	
	FRQM	Frequency measurement	
046.000	PWM	Pulse width modulation	
Others	PID	PID control	
-	NAME C	C function block	

# PLC

Function
the mean value
ic AND
ic OR
ic XOR
verse
gative
hmetic shift left
hmetic shift right
ic shift left
ic shift right
cle shift left
cle shift right
shift left
shift right
rd shift left
rd shift right
rd integer change to double word integer
bits integer change to floating number
bits integer change to floating number
ating number change to integer
D code change to binary
ary change to BCD code
change to ASCII
CII change to hex
oding
h-bit encoding
v-bit encoding
ary change to gray code
y code change to binary
ating number comparison
ating number range comparison
ating number addition
ating number subtraction
ating number multiplication
ating number division
ating number square
ating number sine
ating number cosine
ating number tangent
ating number arcsine
ating number arccosine
ating number arctangent
ad clock data
te clock data

#### **Basic instruction**

Instruction	Function
LD	Initial logic normally open contactor
LDI	Initial logic normally close contactor
AND	Serial connection normally open contactor
ANI	Serial connection normally close contactor
OR	Parallel connection normally open contactor
ORI	Parallel connection normally close contactor
LDP	Initial logic rising-edge of pulse
LDF	Initial logic falling-edge of pulse
ANDP	Serial connection rising-edge of the pulse
ANDF	Serial connection falling-edge of the pulse
ORP	Parallel connection rising-edge of the pulse
ORF	Parallel connection falling-edge of the pulse
LDD	Read normally open contactor
LDDI	Read normally close contactor
ANDD	Read normally open contactor, serial connection
ANDDI	Read normally close contactor, serial connection
ORD	Read normally open contactor, parallel connection
ORDI	Read normally close contactor, parallel connection
OUT	Coil drive
OUTD	Output to the contactor
ORB	Parallel connection of serial circuit block
ANB	Serial connection of parallel circuit block
MCS	New generatrix start
MCR	Generatrix reset
ALT	Coil reverse
PLS	ON for one scanning period at rising-edge
PLF	ON for one scanning period at falling-edge
SET	Keep the coil ON
RST	Reset the coil
TMR	Timer drive
OUT	Counter drive
RST	Reset the contactor or present value
END	I/O operation and return to step 0
GROUP	Instruction block folding start
GROUPE	Instruction block folding end

# Dimension (unit: mm)

#### XD series basic unit







89.0

#### 177.2 89.9 166.2 0 TYPE DATE SN:00 œ ПП 2-04.3 Suitable model Series I/O numbers XD3 XD5 XDM 48/60points XDC

#### XD3 series right extension module



8X8Y

16X/16Y

All

Analog



# **XD** series extension **BD**



#### XD series left extension module

XD-SBOXT-ED



XD-NES-ED



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#### XD-WBOXT-ED





# XC Series

#### **Special function extension BD board**





#### XC basic unit

XC1 series affordable	• XC2 series basic	● XC3 series standard
O numbers: 10/16/24/32	I/O numbers: 14/16/24/32/42/48/60	I/O numbers: 14/24/32/42/48/60
Compact model fit for general applications, the functions including ogic control, data calculation and other basic functions.	Je The functions include data processing, high speed count, high spee pulse output, communication. The processing speed is 2 times of X series. The register numbers are less than XC3, cannot expand module but can connect expansion BD (except 14/16/42 models).	ad The functions include data processing, high speed count, high speet pulse output, communication, PWM, frequency measurement, precisi timing, interruption. Can connect expansion module and BD(14 I/O cannot support any expansions, 42 I/O cannot support BD).
XC5 series enhanced	• XCM series motion control	• XCC series high performance
O numbers: 24/32/48/60	I/O numbers: 24/32/60 Support motion control instructions, the functions include two-axis	I/O numbers: 24/32
II the functions of XC3 series, 4-axis pulse output (24/32 upport), CANBUS network, can connect expansion modu nd BD, the register numbers are more than XC3.	Support Induit Outloan, following, coordinates transformation (excep li/O 60), 3-10 axes pulse output. Support most functions of XC seri such as PID control, high speed count, interruption. Can connect expansion modules and BD.	
t by I/O numbers 10/14/16points	24/32points 42points	48/60points
xpansion modules XCC series PLC	only can connect XCL series expansion module	
I/O expansion     I/O expansion     XC-E16X     XC-E16X     XC-E8X8YR     XC-E16X     XCL-E8X8YR     XCL-E16X     XCL-E8X8YR     XCL-E16YR XCL-E19YT     XCL-E19YR     XC		
• I/O expansion • I/O	CCLL-EBX8YR CCLL-EBX8YR CCLL-EBX8YR	
● I/O expansion W W W W W W W W W W W W W W W W W W W	C-E32YR      Destination module      C(L)_E8X8YR      C(L)_E8X8YT      C(L)_E16X16YT	<image/> <section-header></section-header>
• I/O expansion (1) + (1)	C-E32YR      Determine module      C(L)_E8X8YR      C(L)_E8X8YR      C(L)_E16X16YR       C(L)_E16X16YR       C(L)_E16X16YR       C(L)_E16X16Y	<image/> <section-header></section-header>

#### Expar



Analog	expansion	1	Tempe	rature c
KC-E4A	D XC-E4D	DA XC-E4AD2DA	XC-E0	
AD, DA tra	insformation, ten	nperature control	Pt100 thern built-in PID	nal resistor ar function
AD model	DA model	mixed model	PT100	Thermocoup
XC-E2AD-H XC-E4AD(-H) XC-E8AD(-H) XC-E8AD-B	XC-E2DA(-H) XC-E4DA(-H) XC-E4DA-B-H XCL-E4DA	XC-E4AD2DA(-H) XC-E4AD2DA-B-H XCL-E4AD2DA	XC-E2PT-H XC-E6PT(-H) XC-E6PT-P(-H)	XC-E2TCA XC(L)-E6T
[				



n		Based on Modbus protocol, can extend up to 16 modules		
nocouple model	Analog and temperature	Digital I/O	Analog I/O	Temperature control
locouple mouel	mixed model	MA-8X8YR, MA-8X8YT	MA-2DA, MA-4DA MA-4AD, MA-8AD-A(V) MA-4AD2DA	MA-6PT-P MA-6TCA-P
KC-E2TCA-P KC(L)-E6TCA-P	XC-E3AD4PT2DA(-H) XC-E2AD2PT2DA	MA-16X MA-16YR, MA-16YT		
		* the model with "H" is photoelectricity isolation for each chann		

#### High speed calculation

Basic instruction 0.2~0.5us, scanning time 10000 steps 5ms, program capacity 32K~256K.

#### **Rich extensions**

In order to meet more application needs, XC series PLC can extend I/O module, analog module, temperature control module. Can extend 7 different modules and 1 BD board.

#### • I/O extension module

- ► To extend I/O numbers, the numbers are 8~32, can extend the basic unit I/O numbers to 540
- ► The output expansion module contains transistor (T) and relay (R).

#### • Analog and temperature extension module

- AD, DA transformation function, fit for process control system such as temperature, flow, liquid level, pressure, etc
- Built-in PID function, wide range of application, high control accuracy
- ► Each channel of XC-E6TCA-P and XC-E2AD2PT2DA can perform PID and auto-tune individually, exchange data with PLC by instruction FROM and TO

#### Larger capacity for soft component



в

#### **Communication function**

• Multi-communication port (max 4 ports), support RS232, RS485, Ethernet. Can communicate with frequency inverter, meter and other devices, easy to build communication network.



#### 24-segment high speed count interruption

• High speed count interruption has good real-time feature

• The high speed count has 24-segment 32 bits preset value, the interruption is produced when the count difference value is equal to the preset value.



#### High speed count

• XC series PLC has 2~6 channels 2 phases 32 bits high speed counter and high speed count comparator, can connect rotary encoder directly and count the encoder signal

• The counting mode includes single phase (incremental mode), pulse and direction mode, AB phase mode (1 time, 4 times). The max frequency is 80KHz

# Count input









#### Enhanced communication and networking function

XC series PLC supports Modbus protocol, free format protocol and other complicated network. The PLC can communicate with printer and meter through free format protocol.

#### Modbus networking

XC series PLC supports Modbus master-slave mode. PLC master station can send requests to other devices, other devices will response it. PLC slave station only can response the master station.



#### Interruption function

The interruption function includes external interruption, timing interruption, 24-segment high speed count interruption. The special operations can be done by calling the interruption. It will not be affected by the PLC scanning period.

#### External interruption

 X terminal is the external interruption input, each X is corresponding to an interruption which is activated by falling or rising edge.

#### • Timing interruption

The timing interruption is very useful when it needs to process special program in long running period main program, or it needs to run special program every certain time in sequence control program. The interruption will not be affected by PLC scanning period. The interruption subprogram will run every N ms

#### C programming function

 Better program privacy, the C program is invisible after encrypted and can be called in the main program.

• Support rich calculation functions: contain all the C functions.

• Save internal space, reduce the workload, programming is more efficient.





#### Extension BD

- ► AD, DA transformation function, fit for process control system such as temperature, flow, liquid level, pressure, etc
- Can install on the PLC directly, not occupy extra space, with wired and wireless communication functions



#### Up to 200KHz pulse output, support 10 channels

XC2/XC3 (I/O 48/60) have 2 channels pulse output. Support multi-mode output with different instructions. The output frequency can up to 200KHz.

- ▶ It needs transistor output PLC to output pulse, such as XC3-14T-E or XC3-60RT-E
- ► XC5 (I/O 24/32) series have 4 channels pulse output (Y0~Y3)
- ► XCC-32T-E has 5 channels pulse output (Y0~Y4)
- ► XCM-60T-E has 10 channels pulse output (Y0~Y11)



#### PWM pulse width modulation

- PWM instruction has pulse width modulation function.
- This function can control the frequency inverter and DC motor.





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#### **PID** control

- XC series PLC has PID control instruction and auto-tune function.
- Users can get the best sampling time and PID parameters by auto-tune function, improve the controlling accuracy.





#### Sequence block

All the instructions run one by one in the sequence block. The next instruction will run after the current instruction ends.

• The block can optimize the programming method of pulse and communication instruction in the program.

Multi-pulse and communication instructions cannot run at the same time in the process which makes the programming method complicated. The block can simplify the program.



#### **Precise timing**

#### • 32 bits instruction STR is precise timing function.

• The precise timer will generate an interruption flag when it reaches the timing value. Each precise timer has corresponding interruption flag.

- The precise timer is a 1ms 32 bits timer.

#### Real-time clock

• Built-in real-time clock, Li-battery power-off retentive.

#### Password protection

• 6 bits ASCII, protect the program security.

#### XC3-19AR-E meets diverse needs

• Has analog I/O without connecting extension module.

Logic control and analog I/O in one unit

- Digital input: 9 (NPN optical-coupler isolation); digital output: 10 (relay) Analog input: 8 (voltage); analog output: 2 (voltage/current)
- bits high precision analog input, 8 bits analog output .
- 2 channels AB phase input, 4 channels high speed count (10KHz).
- 2 channels 32 bits pulse output, cost-effective, save space

#### **Frequency measurement**

• 32 bits instruction FRQM can measure the frequency.

#### Self-diagnosis

• Power-on self-examination, timer monitoring, grammar checking.

#### Small size, easy to install

• Compact structure, improve the utilization, two installation modes.



# **XCPpro software**

#### Support all series of PLC products

XCPpro software is fit for XC series PLC and XMH, XMP, XP series HMI&PLC integrated controller. It can make PLC program and configure the network module, extension module and extension BD.



#### Panel configuration

- Reduce the difficulty of making complicated instructions
  - XCPpro provides easy editing environment for complicated instructions such as multi-pulse output, PID control, 24-segment high speed count interruption.
  - Improve the configuration of pulse instruction
  - New pulse instructions such as PTO are added to XCPpro software, these instructions can be configured in the panel.



#### **Power-off retentive in sections**

User can set the power-off retentive range of ED register

• XCPpro software can set the power-off retentive range of various registers such as timer, counter by changing the value in FD register.



The shaded area is power-off retentive. Area A, B, C, D, E can be set by users

#### Better system compatibility

- Compatible with different OS: Windows2000/XP/7.
- Support 64 bits operation system.

• The programmer can command the program capacity accurately.



#### Enhanced password function

The password can block the program uploading and protect the intellectual property rights of user. The password is also added to program downloading to avoid program damage.

PLC Config     PLC Config     PLC Senal Port     egg BD     egg CAN     egg AD     egg AD	Password: Retype Password: Advanced Characteria Control Contro
· · · ·	

#### Powerful programming ability, better compatibility

• Support ladder chart and instructions, the two modes can be switched. • XCPpro software can make C program, no need change to C programming software.

• The function block can be exported and imported, support source code and passive code. If exporting the passive code, the program cannot be read. The privacy is better.



• C function library contains more C instructions which can be called directly



PLCT - Ladder FuncBlock -CR	c l
Information Export Compile	
1 - Va	
5 FunctionBlock	Name: CRC
B Version:	1.0.0
4 Author:	
E UpdateTime:	2008-1-31 10142:40
<pre>8 UpdateTime: 6 Comment: 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7</pre>	
4	
B VOID CRC ( WORD W	, BIT B )
10 (int 1, j, m, n;	
11 unsigned int crc	
12 for (1=0;1 <w[0];< td=""><td></td></w[0];<>	
18 ( crc_reg^-W[	
14 for(j=0;j<8;	j++)
150 (	
16 if(crc_reg&0x	
	c_reg>>1) ^0xa001;
12 clsc	
19 crc_reg*crc	_reg>>1;

#### Serial port setting

• Enable to configure from com1 to com256.

#### Calculate the program size

#### Download the program online

Online downloading will not clear the data and shut down the output. PLC will auto-run after downloading.

#### Useful simple functions

 Cancel, redo, forward, backward, grammar, checking, instruction prompt.

# Industry Ethernet module T-BOX

#### Open network, enhanced communication ability

• Support Modbus-TCP protocol, connect all the industry devices by T-BOX to form Ethernet control system. It breaks the island state of traditional industry automation, makes the communication more efficient and realizes a wide range of open network.

#### Equipped T-BOX with the PLC brings many advantages

- Flexible distributed automation structure, simplify the system management
- Access Ethernet via RJ45 port and TCP/IP protocol.
- Realize remote programming, monitoring and diagnosing via Ethernet, save time and cost.
- Store and manage the information via Ethernet, simplify the operation of data processing.
- Cost-effective, easy to maintain, friendly diagnosis function
- Modbus communication is one-master multi-slave mode, the speed is very slow.

Multi-station devices can high-speed exchange data between master and slave PLC through T-BOX.

#### Dimension (unit: mm)





# Wireless networking W-BOX

W-BOX can be configured as wireless STA and AP, support 2 wireless interfaces in theory.

• AP mode: PC and mobile phone can search this hot spot and connect the PLC, HMI through virtual serial port of W-BOX.

• STA+AP mode: W-BOX has AP+STA function, STA interface can connect router and server in the network through TCP. PC and mobile phone can connect AP interface to control serial port device and configure the module.

Application	Dimension
Remote device monitoring	
<ul> <li>Application of the internet of things</li> </ul>	
<ul> <li>Industry control</li> </ul>	
Handheld device	

#### **Compatible PLC version and series**

series	W-BOX-T		XD-	WBOXT-ED
XD	×	not support		v3.2 and up
XC	$\sim$	XC2 and up	×	not support



# **Transparent transmission S-BOX**

• Wireless transparent transmission, no protocol. The two modules can communicate with each other when the baud rate (DIP switch), channel (button) settings are same. It makes the communication of HMI, PC, PLC faster and easy. S-BOX includes S-BOX-T and XD-SBOXT-ED, the latter only can be used to left extension module of XD series PLC.



#### Application

- Wireless meter reading, wireless sensor
- Container information management Automation data collection
- Industry control, telemetry
- POS system, asset management
- Building automation and security
- The electric power monitoring of high temperature and high pressure
- Meteorological monitoring and remote sensing

# Wireless data transmission module G-BOX

The G-BOX with XC series PLC can make wireless connection with GPRS or GSM network. It supports Modbus-TCP protocol, fit for distributed system and remote monitoring.

#### **Features**

- Open and transparent data transmission
- Data terminal has TCP/IP protocol stack inside, support TCP, UDP, DNS, PPP, etc.
- Standard industry interface (RS232 or RS485)
- Persistent online mode, with break redial and heartbeat function
- Support SMS sending and receiving
- Support local configuration
- Support GPRS and GSM network communication



#### Wireless upload and download PLC program, real-time monitoring

It is hard to monitor and change the PLC program in remote control system. If XC series PLC is equipped with G-BOX, user can monitor the device, wireless upload/download program via PC though the system is in remote place.

#### Communicate with mobile by SMS

When PLC is equipped with G-BOX, PLC can communicate with user's mobile by SMS. User can remote monitor the PLC state with the mobile. If the PLC has problem, G-BOX will send error code to user's mobile, after user replied the G-BOX, G-BOX will send the user's modification SMS to the PLC to solve the problem.

#### Dimension (unit: mm)







#### (unit: mm)







\*Note: this model is special for left extension module of XD series PLC, the functions are same to S-BOX-T.

#### Dimension (unit: mm)



# MA series data acquisition and control module

MA series module includes digital I/O, analog I/O and temperature control. MA module has RS485 port which based on Modbus protocol, can connect to PLC, HMI, integrated PLC&HMI controller and other devices which support Modbus. It is suitable for process control system such as temperature, flow, level, pressure. Support 16 extension modules.



#### Digital I/O module MA-nXnY

Туре	Explanation
MA-8X8YR	8 channels digital input, 8 channels digital output (relay output)
MA-8X8YT	8 channels digital input, 8 channels digital output (transistor output)
MA-16X	16 channels digital input
MA-16YR	16 channels digital output (relay output)
MA-16YT	16 channels digital output (transistor output)

Analog output module MA-nDA	

Туре	Explanation
MA-2DA	2 channels 10 bits high precision analog output (voltage/current)
MA-4DA	4 channels 10 bits high precision analog output (voltage/current)

#### Analog input module MA-nAD

Туре	Explanation
MA-4AD	4 channels 12 bits high precision analog input (voltage/current), each channel has PID control
MA-8AD-A	8 channels 12 bits high precision analog input (current), each channel has PID control
MA-8AD-V	8 channels 12 bits high precision analog input (voltage), each channel has PID control

#### Analog I/O module MA-nADmDA

Туре	Explanation
MA-4AD2DA	4 channels 12 bits high precision analog input (voltage/current), each channel has PID control. 2 channels 10 bits high precision analog output (voltage/current).

#### Temperature control module MA-nPT-P/MA-nTCA-P

Туре	Explanation
MA-6PT-P	6 channels PT100 input, each channel has PID control; 6 channels output. 1mA constant current output will not be affected by external environment.
MA-6TCA-P	6 channels thermocouple input, each channel has PID control; 6 channels output. 1mA constant current output will not be affected by external environment.

#### Specifications of basic unit

General spe	General specification					
Item	Specification					
Insulation voltage	Above DC500V 2MΩ					
Noise immunity	Noise voltage 1000Vp-p 1µs					
Air	No corrosive, flammable gas					
Ambient temperature	℃ 0°C ~ 0°C					
Ambient humidity	5RH%~95RH% (no condensation)					
COM1	RS232, connect with PC, HMI to program and debug					
COM2	RS232/RS485, connect with network, meters, inverter					
COM3	Extension port of BD board, RS232/RS485					
Installation	Fix with M3 screw or install on the rail directly					
Ground	Third ground (cannot ground with strong power system)					

#### • Performance specification

lt					Speci	ficatior	1					
Series		×	(C1	XC2		XC3		XC5	ХСМ	хсс		
I/O numbers		10/16 24/32			24/32/42	48/60	14	24/32/42	48/60	24/32	60	24/32
Program runnin	g mode						Cycli	cscan				
Programming m	ode					Ins	truction,	ladder chart				
Processing spe	ed						0.5	ius				
Power-off reten	tive	Flas	hROM				F	ashROM and I	i-battery			
User program ca	apacity	32	2KB			128	KB			96KB	128KB	256KB
I/O numbers 5/5 12/12 5/8 16/16		8/6 8/8	14/10 18/14 24/18	28/20 36/24	8/6	14/10 18/14 24/18	28/20 36/24	14/10 18/14	36/24	14/10 18/14		
Internal coil		4	48		1			8768	3			
	Numbers		80					640				
Timer (T)	Specification	100MS TIMER: 0.1~3276.7S 10MS TIMER: 0.01~327.67S 1MS TIMER: 0.001~32.767S										
	Numbers	4	18	640								
Counter (C)	Specification		16 BITS COUNTER: 0~32767 32 BITS COUNTER: -2147483648~2147483647									
Sequence (S)		:	32		1024			1024		1024	1024	1024
Data register (D	)	1	50	2000			8000		8000	4000	8000	
FlashROM regis	ster (FD)	4	12		128		3072			7168	1536	1024
Extension interr	nal register (ED)		-	- 16384				36864	36864	36864		
High speed counter -		max 6 channels, 80KHz, 3 kinds of high speed counting mode (singl				ode (singl	gle phase, pulse&direction, AB phase is 50KF					
Pulse output			-		:	2channels				4chnnels	10channels	5channels
External interru	ption		-		2 kinds of external interruption (rising edge, falling edge)							
Password							6 bits	ASCII				
Self-diagnosis					power-	on self-test	monitori	ng timer, gram	mar check	ing		

#### • XC3-19AR-E specification

lá a se	Analog input (AD)	Analog output (DA)			
ltem	Voltage input	Voltage output	Current output		
Analog input range	0~10V	-	-		
Max input range	DC ± 18V	-	-		
Analog output range	log output range –		DC4~20mA (external load resistor less than 500Ω)		
Digital input range	-	8 bits (0~255)			
Digital output range	12 bits (0~4095)	its (0~4095) -			
Resolution	1/4095 (Bit) 1/255 (8Bit)		(8Bit)		
Integrated precision		0.8%			
Transformation speed	d 15ms/channel 2ms/channel				
Power for analog	DC24V ± 10%,100mA				

#### XC series model list

Model								
	AC power supply DC power supply						Input numbers	Output number
	Relay output	Transistor output	Relay&transistor mixed output	Relay output	Transistor output	Relay&transistor mixed output	Input numbers (DC24V)	(R,T)
	XC1-10R-E	XC1-10T-E	-	XC1-10R-C	XC1-10T-C	-	5	5
N P	XC1-16R-E	XC1-16T-E	-	XC1-16R-C	XC1-16T-C	-	8	8
N	XC1-24R-E	XC1-24T-E	-	XC1-24R-C	XC1-24T-C	-	12	12
	XC1-32R-E	XC1-32T-E	-	XC1-32R-C	XC1-32T-C	-	16	16
_	XC1-10PR-E	XC1-10PT-E	-	XC1-10PR-C	XC1-10PT-C	-	5	5
P N	XC1-16PR-E	XC1-16PT-E	-	XC1-16PR-C	XC1-16PT-C	-	8	8
P	XC1-24PR-E	XC1-24PT-E	-	XC1-24PR-C	XC1-24PT-C	-	12	12
	XC1-32PR-E	XC1-32PT-E	-	XC1-32PR-C	XC1-32PT-C	-	16	16
	XC2-14R-E	XC2-14T-E	XC2-14RT-E	XC2-14R-C	XC2-14T-C	XC2-14RT-C	8	6
	XC2-16R-E	XC2-16T-E	XC2-16RT-E	XC2-16R-C	XC2-16T-C	XC2-16RT-C	8	8
Ν	XC2-24R-E	XC2-24T-E	XC2-24RT-E	XC2-24R-C	XC2-24T-C	XC2-24RT-C	14	10
P N	XC2-32R-E	XC2-32T-E	XC2-32RT-E	XC2-32R-C	XC2-32T-C	XC2-32RT-C	18	14
IN	XC2-42R-E	XC2-42T-E	XC2-42RT-E	XC2-42R-C	XC2-42T-C	XC2-42RT-C	24	18
	XC2-48R-E	XC2-48T-E	XC2-48RT-E	XC2-48R-C	XC2-48T-C	XC2-48RT-C	28	20
	XC2-60R-E	XC2-60T-E	XC2-60RT-E	XC2-60R-C	XC2-60T-C	XC2-60RT-C	36	24
	XC2-14PR-E	XC2-14PT-E	XC2-14PRT-E	XC2-14PR-C	XC2-14PT-C	XC2-14PRT-C	8	6
	XC2-16PR-E	XC2-16PT-E	XC2-16PRT-E	XC2-16PR-C	XC2-16PT-C	XC2-16PRT-C	8	8
Р	XC2-24PR-E	XC2-24PT-E	XC2-24PRT-E	XC2-24PR-C	XC2-24PT-C	XC2-24PRT-C	14	10
N P	XC2-32PR-E	XC2-32PT-E	XC2-32PRT-E	XC2-32PR-C	XC2-32PT-C	XC2-32PRT-C	18	14
Р	XC2-42PR-E	XC2-42T-E	XC2-42RT-E	XC2-42R-C	XC2-42PT-C	XC2-42RT-C	24	18
	XC2-48PR-E	XC2-48PT-E	XC2-48PRT-E	XC2-48PR-C	XC2-48PT-C	XC2-48PRT-C	28	20
	XC2-60PR-E	XC2-60PT-E	XC2-60PRT-E	XC2-60PR-C	XC2-60PT-C	XC2-60PRT-C	36	24
	XC3-14R-E	XC3-14T-E	XC3-14RT-E	XC3-14R-C	XC3-14T-C	XC3-14RT-C	8	6
	XC3-24R-E	XC3-24T-E	XC3-24RT-E	XC3-24R-C	XC3-24T-C	XC3-24RT-C	14	10
N P	XC3-32R-E	XC3-32T-E	XC3-32RT-E	XC3-32R-C	XC3-32T-C	XC3-32RT-C	18	14
N	XC3-42R-E	XC3-42T-E	XC3-42RT-E	XC3-42R-C	XC3-42T-C	XC3-42RT-C	24	18
	XC3-48R-E	XC3-48T-E	XC3-48RT-E	XC3-48R-C	XC3-48T-C	XC3-48RT-C	28	20
	XC3-60R-E	XC3-60T-E	XC3-60RT-E	XC3-60R-C	XC3-60T-C	XC3-60RT-C	36	24
	XC3-14PR-E	XC3-14PT-E	XC3-14PRT-E	XC3-14PR-C	XC3-14PT-C	XC3-14PRT-C	8	6
	XC3-24PR-E	XC3-24PT-E	XC3-24PRT-E	XC3-24PR-C	XC3-24PT-C	XC3-24PRT-C	14	10
Р	XC3-32PR-E	XC3-32PT-E	XC3-32PRT-E	XC3-32PR-C	XC3-32PT-C	XC3-32PRT-C	18	14
N P	XC3-42PR-E	XC3-42PT-E	XC3-42PRT-E	XC3-42PR-C	XC3-42PT-C	XC3-42PRT-C	24	18
•	XC3-48PR-E	XC3-48PT-E	XC3-48PRT-E	XC3-48PR-C	XC3-48PT-C	XC3-48PRT-C	28	20
	XC3-60PR-E	XC3-60PT-E	XC3-60PRT-E	XC3-60PR-C	XC3-60PT-C	XC3-60PRT-C	36	24
	-	XC5-24T-E	XC5-24RT-E	-	XC5-24T-C	XC5-24RT-C	14	10
NPN	-	XC5-32T-E	XC5-32RT-E	-	XC5-32T-C	XC5-32RT-C	18	14
	-	XC5-24PT-E	XC5-24PRT-E	-	XC5-24PT-C	XC5-24PRT-C	14	10
PNP	-	XC5-32PT-E	XC5-32PRT-E	-	XC5-32PT-C	XC5-32PRT-C	14	14
NPN	-	XCM-60T-E	-	-	XCM-60T-C	-	36	24
PNP	-	XCM-60PT-E	-	-	XCM-60PT-C	-	36	24
	-	XCC-24T-E	-	-	XCC-24T-C	-	14	10
NPN	_	XCC-32T-E	-	-	XCC-32T-C	-	14	14
	-	XCC-321-E XCC-24PT-E	-	-	XCC-24PT-C	-	10	14
PNP	-	XCC-32PT-E	-	-	XCC-32PT-C	-	14	10

#### I/O extension

		Model				
		0ι	ıtput	I/O numbers	Input numbers (DC24V)	Output numbers (R,T)
	Input	Relay output	Transistor output		(00244)	(13,17)
	XC(L)-E8X	-	-	8	8	-
	-	XC(L)-E8YR	XC(L)-E8YT	8	-	8
	-	XC(L)-E8X8YR	XC(L)-E8X8YT	16	8	8
	XC(L)-E16X	-	-	16	16	-
NPN	-	XC(L)-E16YR	XC(L)-E16YT	16	-	16
	-	XC(L)-E16X16YR-E	XC(L)-E16X16YT-E	32	16	16
	-	XC-E16X16YR-C	XC(L)-E16X16YT-C	32	16	16
	XC(L)-E32X-E	-	-	32	32	-
	XC-E32X-C	-	-	32	32	-
	-	XC(L)-E32YR-E	XC(L)-E32YT-E	32	-	32
	-	XC-E32YR-C	XC(L)-E32YT-C	32	-	32
	XC-E8PX	-	-	8	8	-
	-	XC-E8PX8YR	XC-E8PX8YT	16	8	8
PNP	XC-E16PX	-	-	16	16	-
	-	XC(L)-E16PX16YR-E	-	32	16	16
	-	XC-E16PX16YR-C	-	32	16	16
	XC-E32PX-E	-	-	32	32	-

#### Analog and temperature extension modules

Model		Description					
	XC-E2AD(-H)	2 channels analog input					
	XC-E4AD(-H)	4 channels analog input					
Analog input	XC-E8AD(-H)	8 channels analog input (first 4 channels are voltage input, last 4 channels are current input)					
, manog mpar	XC-E8AD-B	first 4 channels are voltage input (-10~10V/-5~5V), last 4 channels are current input (-20~20mA)					
	XC(L)-E4AD2DA(-H)	4 channels analog input, 2 channels analog output					
	XC-E4AD2DA-B-H	4 channels analog input (voltage/current), 2 channels voltage output (-10~10V/-5~5V)					
Analog output	XC-E2DA(-H)	2 channels analog output					
	XC-E4DA(-H)	4 channels analog output					
Analog output	XCL-E4DA	- + Chaimers analog output					
	XC-E4DA-B-H	4 channels voltage output (-10~10V/-5~5V)					
	XC-E2PT(-H)	2 channels PT100 input					
	XC-E6PT(-H)	6 channels PT100 input					
Temperature measurement	XC-E6PT-P(-H)	6 channels PT100 input, with PID control function					
measurement	XC(L)-E6TCA-P	6 channels K, S, E, N, J, T, R thermocouple input, each channel has PID function					
	XC-E2TCA-P	2 channels K, S, E, N, J, T, R thermocouple input, each channel has PID function					
	XC-E3AD4PT2DA	3 channels analog input, 4 channels PT100 input, 2 channels analog output					
	XC-E2AD2PT2DA	2 channels analog input, 2 channels PT100 input, each channel has PID function, 2 channels analog output					

#### Extension BD board model list

	Model	Description
Temperature measurement	XC-2AD2PT-BD	2 channels analog input, 2 channels PT100 input
Communication	XC-COM(-H)-BD	RS232/485 communication
SD card	XC-SD-BD	Extend the XC PLC data capacity
Analog I/O	XC-2AD2DA-BD	2 channels analog input, 2 channels analog output
Ethernet	XC-TBOX-BD	Connect to the Ethernet
Optical fiber communication	XC-OFC-BD	Connect PLC and make optical fiber communication
Analog input	XC-4AD-BD	2 channels voltage input, 2 channels current input

#### Connection accessory model list

	Model	
USB convertor	USB-COM	PLC connect to PC via USB port
Bluetooth	COM-BLT	Short distance wireless connection betwee

\* Note: NPN and PNP are for input terminal.



\* Note: NPN and PNP are for input terminal.

 $\ensuremath{^*\text{Note:}}$  the model with H is photoelectric isolation for each channel.

#### Description

een PLC and PC

#### **Basic instructions**

Instruction	Function
LD	Initial logic normally open contactor
LDI	Initial logic normally close contactor
AND	Serial connection normally open contactor
ANI	Serial connection normally close contactor
OR	Parallel connection normally open contactor
ORI	Parallel connection normally close contactor
LDP	Initial logic rising-edge of pulse
LDF	Initial logic falling-edge of pulse
ANDP	Serial connection rising-edge of the pulse
ANDF	Serial connection falling-edge of the pulse
ORP	Parallel connection rising-edge of the pulse
ORF	Parallel connection falling-edge of the pulse
LDD	Read normally open contactor
LDDI	Read normally close contactor
ANDD	Read normally open contactor, serial connection
ANDDI	Read normally close contactor, serial connection
ORD	Read normally open contactor, parallel connection
ORDI	Read normally close contactor, parallel connection
OUT	Coil drive
OUTD	Output to the contactor
ORB	Parallel connection of serial circuit block
ANB	Serial connection of parallel circuit block
MCS	New generatrix start
MCR	Generatrix reset
ALT	Coil reverse
PLS	ON for one scanning period at rising-edge
PLF	ON for one scanning period at falling-edge
SET	Keep the coil ON
RST	Reset the coil
TMR	Timer drive
OUT	Counter drive
RST	Reset the contactor or present value
END	I/O operation and return to step 0
GROUP	Instruction block folding start
GROUPE	Instruction block folding end

#### Motion control instruction

Instruction	Function
ABS	Absolute address
CCW	Arc anticlockwise interpolation
CHK	Servo checking
CW	Arc clockwise interpolation
DRV	High speed positioning
DRVR	Electrical back to zero
DRVZ	Mechanical back to zero
FOLLOW	Follow
INC	Incremental address
LIN	Linear interpolation
PLAN	Plane or space choice
TIM	Stable time
SETR	Set the electrical zero
SETP	Set the coordinate system

#### **Application instruction**

Type II

Free format communication

Туре	Instruction	Function	Туре	Instruction	Function
	CJ	Condition jump	p	MEAN	Get the mean value
_	CALL	Call the subprogram	Data	WAND	Logic AND
Program process	SRET	Subprogram return	calculation	WOR	Logic OR
gra	STL	Process start	cul	WXOR	Logic XOR
З	STLE	Process end	atic	CML	Reverse
oroc	SET	Open assigned process, close present process	š	NEG	Negative
es	ST	Open assigned process, not close present process		SHL	Arithmetic shift left
S	FOR	Cycle start		SHR	Arithmetic shift right
	NEXT	Cycle end		LSL	Logic shift left
	FEND	Main program end	Data	LSR	Logic shift right
	LD =	Initial logic ON when (S1)=(S2)	Data shifi	ROL	Cycle shift left
	LD>	Initial logic ON when (S1)>(S2)	ŧ	ROR	Cycle shift right
	LD<	Initial logic ON when (S1)<(S2)		SFTL	Bit shift left
	LD<>	Initial logic ON when (S1)≠(S2)		SFTR	Bit shift right
	LD>=	Initial logic ON when (S1)≥(S2)		WSFL	Word shift left
	LD<=	Initial logic ON when (S1)≤(S2)		WSFR	Word shift right
Data comparison	AND =	Serial connection ON when (S1)=(S2)		WTD	Word integer change to double word integer
cor	AND >	Serial connection ON when (S1)>(S2)		FLT	16 bits integer change to floating number
adu	AND <	Serial connection ON when (S1)<(S2)		FLTD	64 bits integer change to floating number
aris	AND <>	Serial connection ON when (S1)≠(S2)	0	INT	Floating number change to integer
on	AND >=	Serial connection ON when (S1)≥(S2)	ata	BIN	BCD code change to binary
	AND <=	Serial connection ON when (S1)≤(S2)	trar	BCD	Binary change to BCD code
	OR =	Parallel connection ON when (S1)=(S2)	Data transformation	ASCI	Hex change to ASCII
	OR >	Parallel connection ON when (S1)>(S2)		HEX	ASCII change to hex
	OR <	Parallel connection ON when (S1)<(S2)		DECO	Decoding
	OR <>	Parallel connection ON when (S1)≠(S2)		ENCO	High-bit encoding
	OR >=	Parallel connection ON when (S1)≥(S2)		ENCOL	Low-bit encoding
	OR <=	Parallel connection ON when (S1)≤(S2)		GRY	Binary change to gray code
	CMP	Data comparison		GBIN	Gray code change to binary
	ZCP	Data range comparison		ECMP	Floating number comparison
Dat	MOV	Transmission		EZCP	Floating number range comparison
Data transmission	BMOV	Data block transmission		EADD	Floating number addition
ran	FMOV	Multi-point repeat transmission	끈	ESUB	Floating number subtraction
smi	FWRT	Write in FlashROM	oati	EMUL	Floating number multiplication
ss	MSET	Batch set on	ng	EDIV	Floating number division
on	ZRST	Batch reset	ca	ESQR	Floating number square
	SWAP	Exchange the high byte and low byte	cul	SIN	Floating number sine
	XCH	Exchange the data	Floating calculation	COS	Floating number cosine
Data calculation	ADD			TAN	Floating number tangent
ac	SUB	Subtraction		ASIN	Floating number arcsine
alc	MUL Multiplication				·
ula	DIV	Division		ACOS	Floating number arccosine
tio	INC	Increase by one		ATAN	Floating number arctangent
5	DEC	Decrease by one	Clock	TRD	Read clock data
			č	TWR	Write clock data

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Dimension of basic unit





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Suitable model		
Series	I/O numbers	
XC2	42	
XC3	42	

#### Dimension of extension module

#### • No.1 diagram



Suitable model				
Series	I/O numbers			
I/O	8, 16			
Analog	All			
Temperature	All			
Mixed	All			

#### **Special instruction**

Туре	Instruction	Function
	PLSY	Single-segment pulse output without acceleration and deceleration
	PLSA	Absolute position multi-segment pulse output
	PLSR	Relative position multi-segment pulse output
	PLSF	Variable frequency pulse output
-	PLSNEXT/PLSNT	Pulse segment changing
Pulse output	DRVA	Absolute position single segment pulse control
ë	DRVI	Relative position single segment pulse control
utp	PLSMV	Store the pulse numbers in the register
Ħ	STOP	Stop the pulse
	ZRN	Mechanical return to zero
	PTO	Relative multi-segment pulse output
	PTOA	Absolute multi-segment pulse output
	PSTOP	Pulse stop
	PTF	Variable frequency pulse output

nstruction	Function		Туре	Type Instruction
HSCR	Read 32 bits high speed counter			STR
HSCW	Write 32 bits high speed counter		Precise timing	Precise timing STRR
OUT	24-segment high speed count interruption			STRS
RST	Reset high speed counter			EI
COLR	Modbus read coil		Interruption	Interruption DI
INPR	Modbus read input coil			IRET
COLW	Modbus write single coil			SBLOCK
MCLW	Modbus write multi coils		Convence	SBLOCKE
REGR	Modbus read register		Sequence block	block BSTOP
INRR	Modbus read input register			BGOON
REGW	Modbus write single register			WAIT
MRGW	Modbus write multi registers		Write and read	Write and read FROM
0510	Free format data send		the module	the module TO
SEND	Pree format data send			FRQM
RCV	Free format data receive		Others	Others PWM
nuv	Free format data receive			PID
		•		NAME_C



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Suitable model		
Series	I/O numbers	
XC1	24/32	
XC2	24/32	
XC3	24/32	
XC5	24/32	
XCC	24/32	



Suitable model				
Series	I/O numbers			
XC2	48/60			
XC3	48/60			
XCM	60			

#### • No.2 diagram



Suitable model				
Series	I/O numbers			
I/O	32			
Analog	-			
Temperature	-			
Mixed	-			