## XINJE

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# XINJE



www.xinje.com 2017

PLC XG1<sup>NEW</sup> XL3<sup>NEW</sup> XD<sup>NEW</sup> XC

# XG1 NEW series middle-sized PLC



# XL3 NEW series ultrathin PLC



#### Middle-sized PLC

#### XG1 series

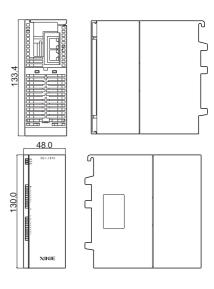
#### New light appearance

#### **Features**

- $\blacksquare$  Ethernet communication port, fast speed and powerful functions
- Motion control function
- Total improved CPU processing speed
- More reliable



#### Dimension (unit: mm)



#### **Ultrathin PLC**

#### **XL3 Series**

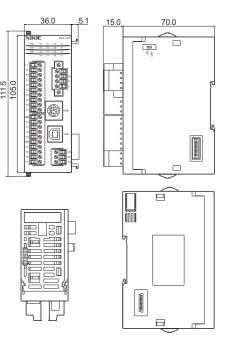
#### Small size, powerful function

#### **Features**

- Ultrathin appearance, compact and practical, fit for different environment
- Good compatibility
- Support max 10 extension modules
- Outstanding cost performance
- Save installation sapce



#### Dimension (unit: mm)

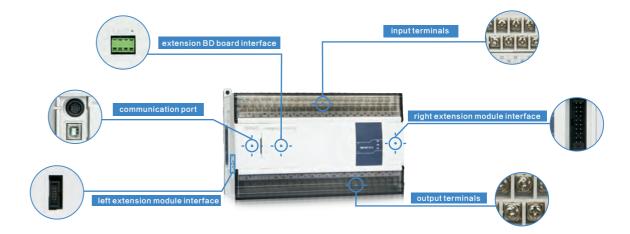




XD2 series XD3 series XD5 series **XDM series** XDC series

- Faster processing speed
- Rich expansion modules
- Stable performance, meet different needs





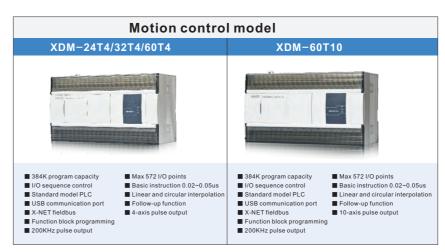


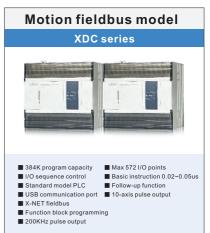
After XC series PLC, XINJE company developped XD series PLC which has faster speed, better performance and fit for various requirments.





		Enhance	d model		
XD5-24	/32/48/60	XD5-24T4	1/32T4	XD5-48	T6/60T6
1000 mm. in		N2007		NSE made and	
■ 384K program capacity ■ I/O sequence control ■ USB communication port ■ 200KHz pulse output	■ X-NET fieldbus ■ Max 572 I/O points ■ Basic instruction 0.02~0.05us ■ 2-axis pulse output	■ 384K program capacity ■ I/O sequence control ■ USB communication port ■ 200KHz pulse output	■ X-NET fieldbus ■ Max 544 I/O points ■ Basic instruction 0.02~0.05us ■ 4-axis pulse output	■ 384K program capacity ■ I/O sequence control ■ USB communication port ■ 200KHz pulse output	■ X-NET fieldbus ■ Max 572 I/O points ■ Basic instruction 0.02~0.05us ■ 6-axis pulse output

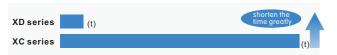


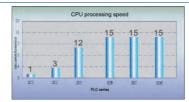




#### High speed processing

Basic instruction processing speed is  $0.02 \sim 0.05 \mu s$ , scanning time is 0.5 m s for 10000 steps, program capacity is  $256 K \sim 384 K$ , the integrated speed is  $12 \sim 15$  times of XC series.





#### Rich extensions

XD series PLC has rich I/O modules, analog I/O modules, temperature modules, BD board, left extension modules. The PLC unit can connect 10~16 modules, 1~2 BD board, 1 left extension module.



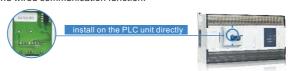
Series	Туре	Left extension module	BD board	Right extension module
XD2	16 points	1	0	0
	16 points	1	0	10
XD3	24/32 points	1	1	10
	48/60 points	1	2	10
	24/32/24T4/32T4 points	1	1	16
XD5	48/60 points	1	2	16
	48T6/60T6 points	1	2	16
XDM	24T4/32T4 points	1	1	16
ADIVI	60T4/T10 points	1	2	16
XDC	24/32 points	1	1	16
ADC	60 points	1	2	16

#### ● I/O extension module

- ▶ To extend the I/O numbers, 8~32 points, the PLC can extend to 572 points.
- ► Output extension module has two types which are transistor and relay.

#### Extension BD board

► The small card can install on the PLC directly, save space, with wireless and wired communication function.



#### • Left extension module

 PLC can transfer the data through WIFI, RS232 or RS485 with the left extension ED module.

#### Analog and temperature extension module

- ► D/A and A/D transformation function. Apply to process control system including temperature, flow, liquid level, pressure.
- PID function, only four parameters to set. Fit for various applications, flexible using, high control accuracy.
- ➤ XD-E6TC-P, XD-E6PT-P have PID control for each channel, with auto-tune function, transfer data with PLC by instruction FROM and TO.

#### XD3 series

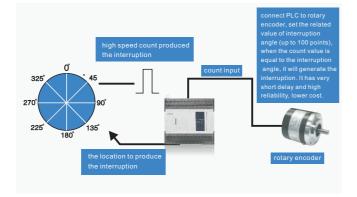


#### Faster data exchange speed between extension module and main PLC

• The data exchange between extension module and main PLC of XD series is SPI serial communication instead of parallel communication which used by XC series, the speed is faster (µs).

#### 100-segment high speed count interruption function

- High speed count interruption, good real time performance.
- XD series high speed counter has 100 segments of 32 bits preset value. The interruption is produced when the count value difference of each segment is equal to the preset value.



#### Communication function

• Multi-communication ports (up to 5), support RS232, RS485, motion fieldbus, X-NET fieldbus, Ethernet, can connect VFD, meter and other devices, networking freely.



#### Subdivided soft component

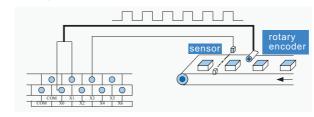
- Subdivided soft component makes the ladder chart more visually.
- Normal soft component, power-off retentive and special soft component is different from each other by writing format.
- Single phase and AB phase of high speed count also can be distinguished by writing format.

Type    Symbol   Notes   Remark				
	X Input terminal Y Output terminal N Internal coil S Process coil SM Special internal coil T Timer coil ET Precise timer coil C Counter coil HM Power-off retentive internal coil S Power-off retentive process coil Similar to power-off retentive process coil of XC series PLC C Gunter coil HM Power-off retentive internal coil Similar to power-off retentive internal coil of XC series PLC, default is S512 to S1023 HT Power-off retentive process coil HT Power-off retentive inter coil HC Power-off retentive counter coil of XC series PLC, XD series PLC conly have single phase and AB phase mode, AB phase has 2-time frequency and 4-time frequency  SEM BLOCK WAIT instruction special coil T The wait coil of XC series PLC can be anyone, in XD series it only can be SEM  D register TD Timer register ETD Precise timer register ETD Precise timer register SD Special register ID Analog sampling register UD Analog sampling register HD Power-off retentive cimer register HD Power-off retentive register			
		Υ	Output terminal	
		M	Internal coil	
		S	Process coil	
		SM	Special internal coil	similar to the special auxiliary register after M8000 of XC series PLC
			Timer coil	
	Bit object	ET	Precise timer coil	Similar to T600 to T618 of XC series PLC
		С	Counter coil	
		HM	Power-off retentive internal coil	Similar to power-off retentive internal coil of XC series PLC, default is M3000 to M7999
		HS	Power-off retentive process coil	Similar to power-off retentive process coil of XC series PLC, default is S512 to S1023
			Power-off retentive timer coil	New soft component, the timer value and state will be kept even the PLC power is off
		HC	Power-off retentive counter coil	Similar to power-off retentive counter coil of XC series PLC, default is C320 to C630
		HSC	High speed counter coil	
		SEM	BLOCK WAIT instruction special coil	The wait coil of XC series PLC can be anyone, in XD series it only can be SEM
		TD	Timer register	
		ETD	3	
		CD	Ŭ .	
<b>\$</b>	RAM	SD	Special register	
ā		ID		
윤				
ect			Ŭ .	
		HTD		
			3	
	ELVOR		Ŭ .	protect the customer's intellectual property
	FLASH	SFD	Special flash register	

#### High speed count

 XD series PLC can configure 2 to 10 channels of 32-bit high speed count, the max frequency can up to 80KHz, it can connect the rotary encoder and count its value directly.

#### ► count input

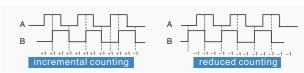


► Multi-counting mode



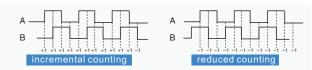
• There are two counting modes including single phase (incremental mode, max frequency 80KHz) and AB phase (2-time/4-time frequency, max frequency 50KHz).

#### ► 2-time frequency mode



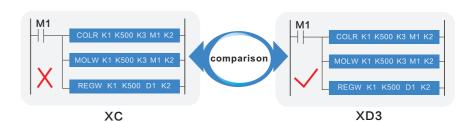
► 4-time frequency mode

AB phase counting has 4-time frequency mode



#### **Optimized Modbus instruction**

More than one modbus instruction can be triggered by one condition in the main program, these instructions will be executed one by one as the protocol station request. It will not run two instructions at the same time and cause error.



#### Powerful pulse instruction

XD series PLC get rid of the disadvantages of XC pulse function too simple and too many pulse instructions. XD integrated the XC pulse instruction PLSR, PTO, PLSF in one, make the function powerful.

simplify the instruction

flexible configuration

if the interruption comes after the pulse outputting, PLC

pulse edge trid of the disadvantages of XC pulse functions. XD integrated the XC pulse instruction PLSR, PTO, PLSF in one, make the function powerful.

if the interruption comes after the pulse outputting, PLC has fast response speed, no scanning period effect, no need external interruption

#### Powerful communication and networking function

XD series PLC communication port not only support Modbus protocol, but also support other complicated network. Users can make free format protocol to communicate with printer and meters.

#### Modbus network

XD series PLC support Modbus (RTU and ASCII) protocol master and slave mode. When PLC is master station, it will send requests to other devices which respond it. When PLC is slave station, it will answer the master station.



#### 200KHz 10 channels pulse output

XD2/XD3/XDC have 2 channels of pulse output, XD5 has 2 to 6 channels of pulse output, XDM has 4 to 10 channels pulse output. Multi-mode output by different instructions. The frequency can up to 200KHz.

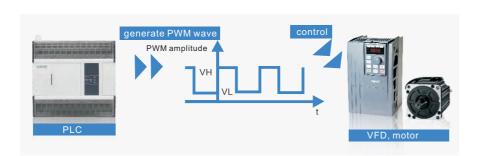


- It needs transistor output PLC for pulse output, such as XD3-16T-E, XD3-60RT-E.
- XD5-24T4/32T4 have 4 channels of pulse output (Y0, Y1, Y2, Y3).
- XD5-48T6/60T6 have 6 channels of pulse output (Y0, Y1, Y2....Y5).
- XDM series PLC has 4 to 10 channels pulse output (Y0, Y1, Y2...... Y11).

series	model	pulse output channel	pulse output terminal
XD2	16T	2	Y0/Y1
XD3	all the transistor output model	2	Y0/Y1
	24T/32T/48T/60T	2	Y0/Y1
XD5	48T6/60T6	6	Y0/Y1/Y2/Y3/Y4/Y5
	24T4/32T4	4	Y0/Y1/Y2/Y3
	24T4/32T4 and 60T4	4	Y0/Y1/Y2/Y3
XDM	60T10	10	Y0/Y1/Y2/Y3/Y4/Y5/
	00110	10	Y6/Y7/Y10/Y11
XDC	24T/32T	2	Y0/Y1
ADC	48T/60T	2	Y0/Y1

#### PWM pulse width modulation

- PWM instruction can modulate the pulse width
- The subdivision accuracy is 128 times of XC series PLC, up to 1/65536
- The output frequency is higher than XC series PLC, up to 200KHz
- Control the inverter and DC motor by this function



#### Interruption

XD series PLC interruption function includes external interruption, timing interruption, 100 segments high speed counter interruption. It can do some special operation by calling the interruption without PLC scanning period influence.

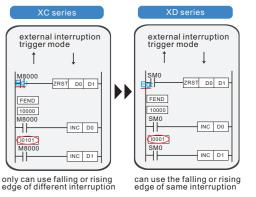


#### Timing interruption

- ► To run appointed program when the main program is long; to run the program every certain time. The timing interruption is useful for these occasions. It is not affected by PLC scanning period. It will run the subprogram every n ms.
- ▶ XD series PLC have 20 channels timing interruption, it is 2 times of XC series PLC.

#### External interruption

- ▶ The input terminal X is the input of interruption. Each terminal corresponds to an interruption which is activated by falling or rising edge.
- ▶ XD series PLC have more interruption terminals than XC series.
- ► The falling edge and rising edge can be used at the same time for XD series external interruption.

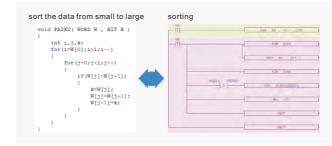


#### Support C programming (the pioneer in the industry)

- Better program security: call the C program module directly, the C program is encrypted and invisible
- Support all the C functions
- Support local variable and global variable
- Save the program capacity, reduce the workload, improve the programming efficiency

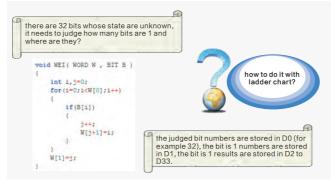


#### C application I

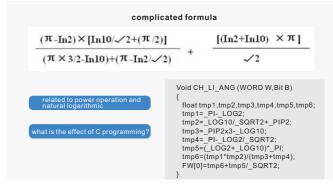


# simplify the programming, improve the efficiency C function advantages program can be encrypted call the program anywhere call the program anywhere accord to standard C programming rule

#### C application II

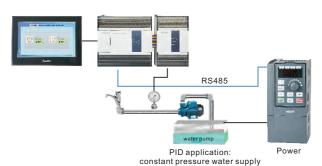


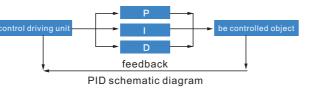
#### C application III

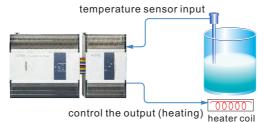


#### PID control

- XD series PLC support PID control instruction and auto-tune function
- User can get the best sampling time and PID parameters via auto-tune to improve the control accuracy
- Two control methods: step-response and critical oscillation, applied to more occasions

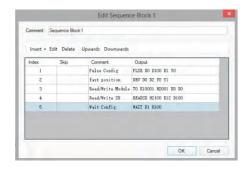






#### Sequence block

- All the instructions in the sequence block will run one by one. The next instruction will run after the present instruction completed
- The sequence block can optimize the program



#### Real time clock

- XD series PLC all have RTC inside
- Built-in clock, Li-battery power loss retentive
- XD-CLOCK-BD can apply to high precise clock occasions
- Clock protection function: the PLC clock cannot be changed through communication when secret downloading program in advanced mode



#### Frequency measurement

• 32 bits instruction FRQM can measure the frequency



#### Self-diagnosis

• Power on self-diagnosis, monitor the timer, grammar checking

#### Precise timing

- 32-bit instruction STR can do precise timing
- The precise timer will generate an interruption when it reaches the timer value, each precise timer has related interruption flag
- The precise timer is 1ms 32 bits timer

#### Password protection

- 6 bits ASCII code, protect the program security
- The soft component FS can protect the intellectual property right of customers

#### Compact size, easy to installation

- Compact size, two installation methods
- Easy to change the Li-battery of XD series PLC without opening the PLC cover

#### XD2 basic type

#### I/O numbers: 16

Data processing function, high speed count, high speed pulse output, communication, real time clock, pulse width modulation (PWM), frequency measurement, precise timing, interruption and so on. The processing speed is 12 times of XC series. Cannot extend modules or BD. ED board.



- 32-bit CPU.
- XD2 provides 16 points I/O, is fit for basic
- application
- 2 RS232 ports and 1 RS485 port, support Modbus, free format and X-NET communication.
- Program capacity: 256KB.
- The CPU processing speed is 12 times of
- XC series. ■ Basic instructions: 0.02~0.05us, 6000 steps
- of instruction only need 0.1~0.2ms.
- 2-axis 200KHz pulse output. ■ Powerful password function, protect the
- intellectual property right of customers.

E	Built-in high s <sub>l</sub>	peed co	unter
inci	remental mode	AB ph	nase mode
count ID	max frequency	count ID	max frequency
2	10KHz	2	5KHz

#### XD5 enhanced type

#### I/O numbers: 24/32, 48/60

The same functions to XD3. The processing speed is 15 times of XC series. Larger internal space. With serial port and one USB download port. All the models can connect 16 extension modules, 1 or 2 BD boards, 1 left extension module.



- 32-bit CPU.
- XD5 provides 24/32/48/60 points I/O, is fit
- for various applications. ■ USB port makes the downloading and
- mmunication very fast.
- Program capacity: 25K steps/data register ID: 70K words.
- The CPU processing speed is 15 times of
- XC3 series.
- Basic instructions: 0.02~0.05us, 6000 steps of instruction only need 0.1~0.2ms.
- 2-axis to 6-axis 200KHz pulse output.
- Powerful password function, protect the
- intellectual property right of customers.

В	uilt-in high s	speed c	ounter
incre	emental mode	AB p	hase mode
ounter	max frequency	counter	max frequency
3/4/6	80KHz	3/4/6	50KHz

#### XD3 standard type

#### I/O numbers: 16, 24/32, 48/60

Data processing function, high speed count, electronic cam, real time clock, communication (Modbus RTU/ASC II ), pulse width modulation (PWM), frequency measurement, precise timing, interruption and so on. The processing speed is 12 times of XC series. All the models can connect 10 extension modules, 1 or 2 BD



- 32-bit CPU
- XD3 provides 16/24/32/48/60 points I/O, is fit for
- various applications
- USB port makes the downloading and communication very fast
- Program capacity: 10K steps/data register ID: 1K
- The CPU processing speed is 12 times of XC3 series.
- Basic instructions: 0.02~0.05us, 6000 steps of
- instruction only need 0.1~0.2ms. 2-axis 200KHz pulse output.
- 16 points I/O model also can extend modules.
- Powerful password function, protect the intellectual property right of customers.

	Built-in high s	speed counter
in	cremental mode	AB phase mode

Built-in high s	speed c	ounter
cremental mode	ABp	hase mode
max frequency	count ID	max frequency
80KHz/10KHz	2/3	50KHz/5KHz
	max frequency	max frequency count ID

#### XDM motion control type

#### I/O numbers: 24/32, 48/60

Support basic motion control instructions, 2-axis linkage motion, interpolation, follow-up, 4-axis separate pulse output, up to 10-axis pulse output, all the functions of XD series such as high speed count, interruption, PID control, the processing speed is 15 times of XC series, support SD card for data storage, with 1 serial port and 1 USB download port (high speed downloading, monitoring, speed up to 12M). All the models can connect 16 extension modules, 1 or 2 BD boards, 1 left extension module.



- 32-bit CPU.
- XDM provides 24/32/48/60 points I/O, is fit for various applications.
- USB port makes the downloading and
- unication very fast. ■ Program capacity: 25K steps/data register
- ID: 70K words.
- The CPU processing speed is 15 times of XC3 series, 6000 steps of instruction only need 0.1~0.2ms
- 4-axis to 10-axis 200KHz pulse output.
- Linear or circular interpolation instructions.
- Follow-up control instructions.
- Powerful password function, protect the intellectual property right of customers

Built-in high s	speed counter
incremental mode	AR phase me

counter max frequency counter max frequency 4/10 80KHz/10KHz 4/10 50KHz/5KHz

#### XDC motion control fieldbus type

#### I/O numbers: 24/32, 48/60

The processing speed is 15 times of XC series. Support floating-point calculation, 2 channels pulse output, 4 channels AB phase high speed count, and all the functions of XD series such as interruption, PID. All the models can connect 16 extension modules, 1 or 2 BD boards, 1 left extension module, Support SD card for data storage, with 2 serial ports, support motion control fieldbus, control 20-axis motions at the same



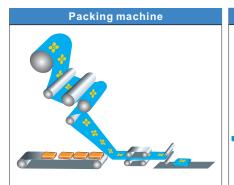
- 32-bit CPU.
- XDC provides 24/32/48/60 points I/O, is fit for various applications.
- Program capacity: 25K steps/data register ID: 70K words.
- The CPU processing speed is 15 times of XC3 series, 6000 steps of instruction only need 0.1~0.2ms.
- 2-axis 200KHz pulse output.
- 1-axis to 20-axis fieldbus control.
- Powerful password function, protect the intellectual property right of customers.

	Built-in nigh s	peea coun	ter		
incre	mental mode	AB phase mode			
counter	max frequency	counter	max frequency		
4	80KHz/10KHz	4	50KHz/5KHz		

#### XDM series motion control structure diagram

#### Multi-axis independent control structure diagram





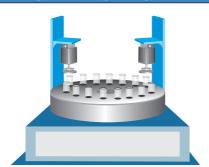
The packing machine can pack the product, the process includes filling, packing, sealing and before and after procedures such as cleaning, stacking, removing. Besides, it also includes counting and printing on the product. The packing machine can improve the production efficiency and reduce labor intensity, be suitable for mass production.

#### Lid tightener



The lid tightener has fast tightening speed, high qualification rate, be suitable for different type of bottle caps such as food, pharmacy, daily chemical, pesticide, cosmetics, etc. The machine has intelligent mechanical torque controlling, easy to adjusting and operation. The worker only needs to put the cap on the bottle, the caps will be auto-tightened by three groups of twisting wheels when the bottle is moving forward. It is fit for single production or attachment production.

#### The glass bottle grinding machine

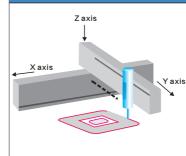


The machine can polish many glass cup-mouths at the same time. It used servo system to improve the precision, product consistency and production efficiency.

#### Multi-axis linkage motion control structure diagram







The coating machine can control the fluid sealant and smear it on and inside the product. It can precise find the position, control the sealant accurately, no wire drawing, no sealant leak through. It can be applied to the figure of point, line, arc and circular. It is fit for the product process of injection, coating, point, drop. It is easy to operate, fast and accurately.

# This machine can heat the pouring object, then control 2-axis or 3-axis path position through linear or circular interpolation function and pour the object onto the product for splicing and sealing.

#### Edge grinding machine



The machine can grind different size and shape of metal edge through linear and circular interpolation function. It contains the coarse grinding, fine grinding, polishing in one process. It has long service life and high efficiency, the shaping is ruled.

#### Glass cutting machine



This machine can control
2-axis or 3-axis path position
through linear or circular
interpolation function. The
laser machine which is
processing the organic glass
has fast cutting speed, high
precision, accurate
positioning. It can produce
artware, model toys, panel
lens case, advertising light
box, packing box, etc.



#### XDC series motion fieldbus controller

#### X-NET motion control fieldbus

The motion fieldbus mode replaces the pulse control mode. makes the system processing speed faster, performance more reliable and stable. It makes the wiring simple and is able to control 20-axis synchronous motion.

- The I/O numbers: 24 points (14/10), 32 points (18/14), 48 points (28/20), 60 points (36/24).
- The I/O can up to 292 input terminals and 280 output terminals through extension modules.
- Support 2 channels of pulse output.
- Support motion control instructions.
- Synchronous period up to 10-axis 4ms, 4-axis 2ms.
- The advanced algorithm makes the control precision higher.

X-NET	motion fieldbus accessories	
model	name	features
XD-NE-BD	PLC communication extension board	PLC communication extension board
JA-NE-L	servo fieldbus extension board	easy to wiring and operate

# XDC system control structure diagram

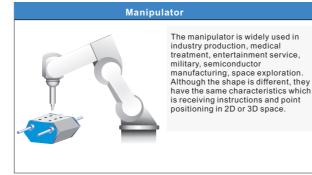
RS232, RS485, X-NET motion fieldbus.

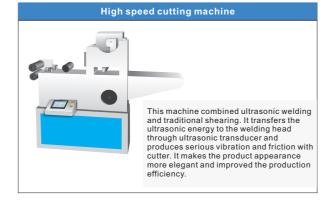
## The left side of XD PLC can

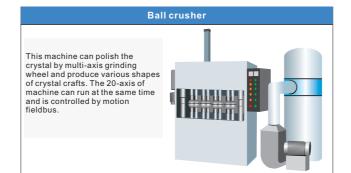
modules including

The right side of XD PLC can connect right extension modules including I/O, AD, DA, TC, PT, weighing.

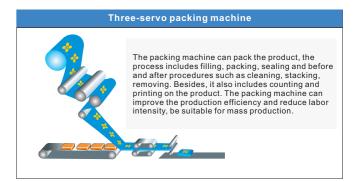
# communication, AD/DA/PT/TC.













CNC lathe is one of the automatic lathe installed with program control system which can process the special program and code then translate to digital code and input to CNC device. The CNC device will process the information and output various signals to control the lathe motion to produce the parts as the drawing. The CNC lathe is fit for complicated, accurate and different type of parts, is one type of flexible high-performance lathe

#### X-NET fieldbus control system

#### X-NET fieldbus

The fieldhus replaced the traditional Modbus and free format communication makes the system faster and reliable. The wiring also become easy. The nodes can up to 32 in single network, different network can communicate with each other

- XD2, XD3, XD5, XDM, XDC all support X-NET fieldbus.
- I/O numbers can up to 292 inputs and 280 outputs through the extension modules.
- X-NET fieldbus is token ring structure.
- Any node in the network who got the token can send message to other node.
- The speed can up to 3Mbps.



Factory monitoring network, token structure, real-time multi-master station system. Multi-control, configuration or visual system can operate with each other on the same bus. Any node in the network has access right (token), no need external requests to send and receive data.

#### Communication speed and distance

The field bus communication speed and medium is related to the site environment The communication distance has limit as the field bus transferring signal is electricity. The distance is 100m at 3Mbps speed and using XINJE cable. The distance can be 1000m at 192kbps speed. The communication speed can up to 600bit~3Mbit

The shield cable of field bus X-NET must connect to the ground. If the high frequency is serious, it can multi-point-capacitance connect to the ground, cannot directly connect to the ground to avoid ground return current. The shield twin-core cable no need shield but it needs to shield under strong electromagnetism emission environment (automobile industry) to improve the compatibility of electromagnetism. The shielding line and foil must connect the both ends to the ground and cover with large area of shielding wiring to keep good conductivity. The data line must isolate with the high voltage line.

#### **Product introduction**

#### ● Isolation

The electrical signal of field bus X-NET is electrical isolated with the equipment. If the high voltage input in the network, all the equipment bus transceiver will damage. If there is no isolation, all the equipment circuits will damage.

#### Intelligent and autonomous

The fieldbus X-NET can process various parameters, running state and error information. It has high intelligence. It can auto-control the system, diagnosis the running status and send the error information to the control center, decrease the maintenance workload, improve the system reliability. Users can check the device running status, the maintenance information, find the error reason and solve the problem earlier. Finally it can save the cost.

#### Improve the accuracy and reliability

Compared with the analog signal, fieldbus device is intelligent, digitization. It improves the accuracy and reliability of whole system, reduces the transmission error. The system structure is simple, devices and wiring decreased, field meter function enhanced, signal transmission decreased. As the device standardization and function modularization, the system design and rebuilding is easy.

#### Powerful system expansion

The fieldbus can auto-identify the device reduction or addition, no need to connect new cable and cut the power supply.

#### Open system

XD series PLC, TN series HMI, DS3E and DS5 series servo drive and frequency inverter have fieldbus X-NET function which can meet most customers' requirements. XINJE company will cooperate with other instrument manufacturers, different devices can interchange information. XINJE products can match more products.

#### More communication stations

There can be 127 station numbers in the field bus X-NET system.

#### Save the installation cost

The field bus wiring is very simple. One pair of twisted pair cable can connect multi-devices, save the cables, terminals, slot box, bridges, decrease the workload of wiring design and joint proofreading. It saves the installation and maintenance cost. The system structure is simple, support linear and ring topology, save the time of project design, drafting, cable laying and hardware manage files.

#### Cable option

The transmission is affected by electromagnetic environment. XINJE cable is shield twin-core or optical fiber which can reach the standard speed and distance. (0.3mm2 and larger multi-strand copper shielded wire is recommended)

#### Connector

PLC terminal (A, B), extension BD board XD-NE-BD, XD-NO-BD make the connection faster, improve the working efficiency, easy to maintenance.

#### Terminal matching

The field bus X-NET has reflection phenomenon just like all the electromagnetic signal. Both ends of bus network segment must use resistor ( $120\Omega$ ) to absorb the radiation, make the correct voltage and ensure the communication.

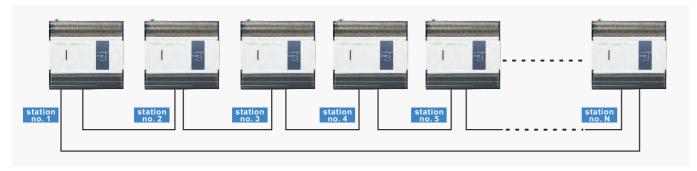
#### Outstanding cost performance

Users have to spend lots of money for the fieldbus project in nowadays industrial control industry. The XINJE products all have fieldbus X-NET inside, it no needs extra costs. It will not limit by product brand.

#### Flexible network topology

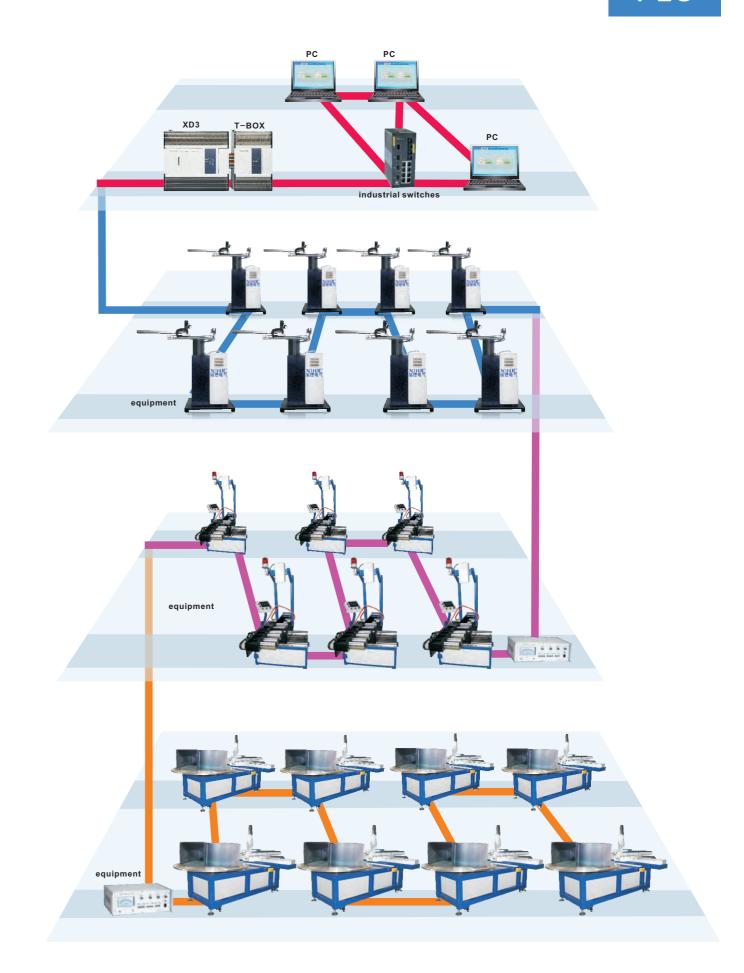
Support various network topology structures including star, line, star and line integrated, ring.

#### the ring topology

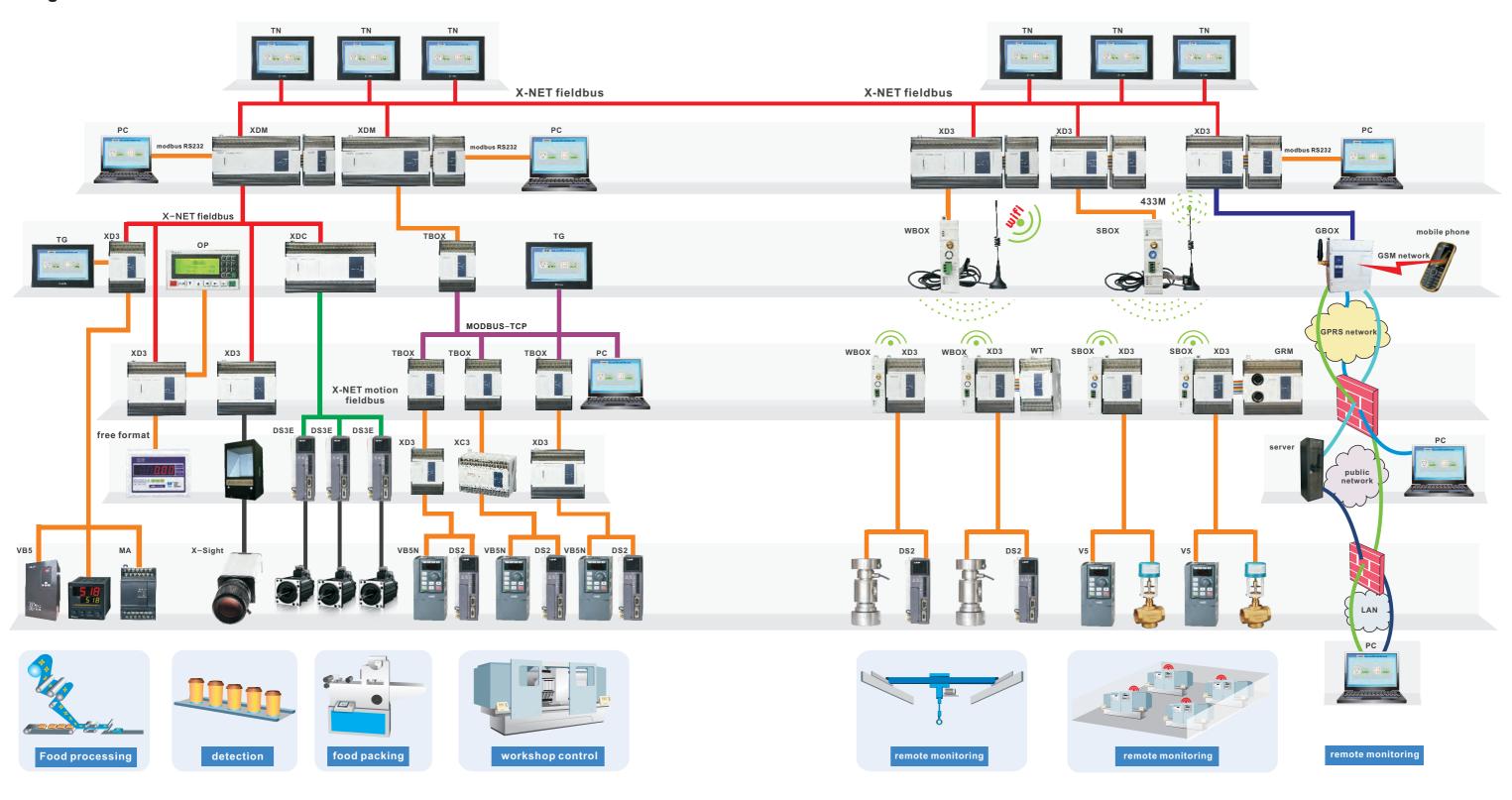


#### Multi-network structure





#### Integrated network structure



#### X-NET fieldbus

XINJE XD all series of PLC support X-NET fieldbus, which has the features of intelligent, digital and strong stability. The max speed can up to 3M, the wiring and design is easy, reconsitution is simple.

#### X-NET motion fieldbus

XINJE XD all series of PLC support X-NET motion fieldbus, which can high speed connect servo system, be fit for multi-axis control, high speed and complicated motion applications. The max axis can up to 20, the max speed can up to 3Mbps.

#### MODBUS

Support standard Modbus serial port communication, easy to connect other brand of products. It contains RS232, RS485 and free format communication which can be selected as actual applications.

#### GPRS

Support Modbus-TCP protocol, use together with XC series PLC to connect automation system with GPRS or GSM network. It is fit for distributed system and remote monitoring.

#### WIFI/433M

WIFI provides the wifi network that other nodes can access and high-speed wireless monitor the device in it. 433M means decreasing the frequency to improve the penetration and tranferring distance, get better wireless communication effect.

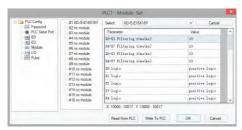
#### MODBUS-TCP

Support Modbus-TCP protocol, the automation devices connect to each other via the Ethernet. It has better communication performance and makes a widely range of open network.

#### XD/EPPro edit tool

#### Support XD all series of products

 XD/EPPro software is suitable for XD, XE series PLC, make PLC program, configure the network module, extension module, extension BD and left extension module.



#### Enhanced password function

 The password can block the program uploading, protect the intellectual property right of user. The password is added to the program downloading to avoid program damage.



 $\ensuremath{\bullet}$  new function advanced save can encrypt the program notes.



#### Panel configuration

- Easy to write the complicated instruction
- ► XD/EPPro software provides easy editing platform for the complicated instructions including PID, 100-segment high speed counter interruption, electronic cam and so on.



#### • Easy to configure the pulse instruction

► XD/EPPro software has PLSR pulse instruction configuration interface which can configure all the pulse functions.



#### • pulse configuration guide

The guide will help user to set the pulse parameters.



#### Powerful programming language

- $\bullet$  Support ladder chart and instruction, the two modes can switch to each other
- •Support C programming in XD/EPPro, no need to use C programming software
- The function block can be imported and exported, support active code and passive code. The program in the function block is invisible after exporting, the privacy is better



- C library contains more C instructions which can be called directly.
  - CAMPUS Peterson, CAM faction block filty utlang follow cotting, CAMP
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#### Good compatibility

• XC series PLC program can be transformed to XD program through XD/EPPro software.



#### XD/EPPro serial port

- Can configure the serial port from COM1 to COM256
- Support Modbus-RTU and Modbus-ASCII protocol
- Support free format communication

#### Program capacity calculation

• Programmer can know the program capacity accurately.

#### Rich downloading function

• The data will not be reset, I/O will not be OFF when downloading online, the PLC will auto-run after downloading. User can choosethe downloading data type.

#### **XD2** series PLC

#### Basic small PLC

- 7 inputs, 8 outputs
- 2 channels 200KHz high speed pulse output
- Faster processing speed
- $\blacksquare$  Cannot support extension module, BD and ED



model				spec	ificatio	n						
XD2-16R-E	_AC	8	⊕ 85 20	485 RS232 CC XCC	®⇒	<b></b>	<u>_</u>		<b>≯</b> 20	<b>&gt;</b> 6	fieldbus XNET	
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XD2-16T-E	AC- 8	8	♣ 50	485 RS232 CC XCC	<b>○</b> >	<b></b>	→ n3n	<b>12</b>	<del>}</del> 20	<b>&gt;</b> 6	fieldbus XNET	
XD2-16T-C	-DC- 8	8	⊕ <sup>88</sup>	485 RS232 CC XCC	<b>○</b> >	<b></b>	<u>_</u>		<b>3</b> 20	<b>&gt;</b> 6	fieldbus XNET	
AC power supply	input	<b>○&gt;</b> tra	ansistor outp	ıt 🔀 RS232 RS232	NPN		pulse inpu	i <u></u> 10	right exten	sion module	fieldbus XNET X-NET	fieldbus
DC power supply	output	<b>®⇒</b> re	lay output	RS485 RS485	PNP	<b>121</b> ,	_ pulse outp	ut 1	left extensi	on module	motion fieldbus XNET X-NE	Γ motion
BD board	real-time clock	tr	ansistor and I	elay output	₹20 time	er interru	intion 🔀	0 extern	al interruntio	nn.		

#### **XD3** series PLC

#### Economical small PLC

- max I/O numbers are 380
- 2 channels 200KHz high speed pulse output
- 16 points model cannot support right extension module
   Faster instruction processing speed
- Rich extension functions



model								spe	cificati	on						
XD3-16R-E	—AC	8	8	$\oplus$	RS485	RS232	€	•	-131			<b></b> 10	1	<b>7</b> 20	<b>&gt;</b> 6	fieldbus XNET
XD3-16R-C	—DC—	<b>3</b>	8	<b>(</b>	RS485	RS232	€		<b>₽</b> 131			<b>≋</b> 10	1	<b>7</b> 20	<b>&gt;</b> 6	fieldbus XNET
XD3-16T-E	—AC	8	8	<b>(</b>	RS485	RS232	<b>()</b>		<b>→</b> 131			<b>≋</b> 10	1	<b>3</b> 20	<b>&gt;</b> 6	fieldbus XNET
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XD3-16RT-C	-DC-	8	<b>A</b>	<b>(</b>	RS485	R\$232	⊕>	<b></b>	<b>_</b>	<b>2</b> ,		<b>≋</b> 10	1	<b>7</b> 20	<b>&gt;</b> 6	fieldbus XNET
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XD3-24PRT-C	—DC—	14	10	<b>(</b>	RS485	R\$232	<b>⊕</b>	<b></b>	<b>_</b>	<b>12</b>	1	<b></b> 10	1	<b>≯</b> 20	<b>¥</b> 10	fieldbus XNET
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XD3-32R-C	—DC—	18	14	<b>(</b>	RS485	R\$232 XXX	<b>®</b>	•	<b>_</b>		1	<b></b> 10	1	<b>&gt;</b> 20	<b>¥</b> 10	fieldbus XNET
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#### **Product introduction**

model							5	peci	fication							
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XD3-48R-E	—AC—	28	20	<b>(</b>	R\$485	RS232	€	•	<u>_</u>		2	<b>≋</b> 10	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
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XD3-60R-E	AC-	36	24	<b>(</b>	RS485	RS232	€	•			2	<b>≋</b> 10	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
XD3-60R-C	—DC—	36	24	<b>(</b>	RS485	RS232	€	•			2	<b>≋</b> 10	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD3-60T-E	AC-	36	24	<b>(</b>	RS485	RS232	<b>○</b>	•			2	<b>≋</b> 10	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD3-60T-C	—DC—	<b>36</b> ▼	24	<b>(</b>	RS485	RS232	<b>○</b>	<b></b>			2	<b>≋</b> 10	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
XD3-60RT-E	—AC—	36	24	<b>(</b>	RS485	RS232	<b>⊕</b>	<b></b>			2	<b>≋</b> 10	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
XD3-60RT-C	—DC—	<b>36</b> ▼	24	<b>(</b>	RS485	RS232	<b>⊕</b> >	<b></b>			2	<b>≋</b> 10	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD3-60PR-E	AC-	36 V	24	<b>(</b>	RS485	RS232	€	<b></b>	<u>. []</u>		2	<b>≋</b> 10	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD3-60PR-C	—DC—	<b>36</b> ▼	24	(1)	RS485	RS232	₿	<b></b>			2	<b></b> 10	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD3-60PT-E	AC-	36 *	24	<b>(</b>	RS485	RS232	<b>&gt;</b>	<b></b>	<b>3</b>		2	<b>≋</b> 10	1	<b>&gt;</b> 20	<b>×</b> 10	fieldbus XNET
XD3-60PT-C	—DC—	<b>36</b> ▼	24	$\odot$	RS485	RS232	<b>○</b> >	<b></b>	<b>₽</b>		2	<b>≋</b> 10	1	<b>&gt;</b> 20	<b>×</b> 10	fieldbus XNET
XD3-60PRT-E	AC-	<b>36</b> ▼	24	<b>(</b>	RS485	RS232	<b>⊕</b>	<b></b>	<b>↓</b>		2	<b>≋</b> 10	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
XD3-60PRT-C	—DC—	36 ▼	24	<b>(</b>	RS485	RS232	<b>⊕</b>	<b></b>			2	<b>10</b>	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD3-20T3TC-E	—AC—	<b>8</b> ▼	12	<b>(</b>		RS232	<u>()</u> ⇒	<b></b>	<u></u>	₽				<b>3</b> 20	<b>&gt;</b> 6	
XD3-20T3TC-E(S)	AC-	8	12	<b>(</b>	RS485	RS232	<b>○</b> >	<b></b>	-12	<b>12</b>				<b>3</b> 20	<b>&gt;</b> 6	
AC power supply	input	t	<b>()</b>	• transisto	routput 🎗	S232 RS232	NPN	<u>, 131</u>	pulse input	<mark>≋</mark> 10 right	extensio	n module		IET fieldbus		
DC power supply	outp	ut	₿	relay out	put 🕺	RS485	PNP		pulse output	1≋ left e	extension	module	XNET X-I	us NET motion	fieldbus	
BD board	real-	time clock	<b>()</b>	transisto	r and relay	output	₹20 time	er interru	uption 🔀 10	external inte	erruption					

#### **XDM** series PLC

Powerful motion control PLC

- Max I/O numbers are 572
- 4/10 channels 200KHz high speed pulse output
- Support 16 right extension modules
- Support linear, circular interpolation
- Faster processing speed



model							s	peci	ficatio	n						
KDM-24T4-E	—AC—	14	10	<b>(</b>	RS485	RS232	<b>○</b> >	•	<u>,4</u>	<u></u>	1	<b>≋</b> 16	1	<del>7</del> 20	<b>¥</b> 10	fieldbus XNET
(DM-24T4-C	—DC—	14	10	<b>(3)</b>	RS485	R\$232	<b>○</b> >	<b></b>	.4	<b>1</b>	1	<b>≋</b> 16	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
DM-32T4-E	—AC	18 V	14	$\odot$	RS485	RS232	<b>()</b>	<b></b>	<u></u>	<u></u>	1	<b>≋</b> 16	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
(DM-32T4-C	—DC—	18	14	<b>(</b>	RS485	R\$232	<b>()</b>	<b></b>	-4	4	1	<b>≋</b> 16	1	<b>≯</b> 20	<b>¥</b> 10	fieldbus XNET
(DM-60T4-E	AC-	36 V	24	$\odot$	RS485	RS232	<b>()</b>	•	<u></u>	4	2	<b>≋</b> 16	1	<b>7</b> 20	<b>×</b> 10	fieldbus XNET
(DM-60T4-C	—DC	36 V	24	<b>(</b>	RS485	RS232	<b>()&gt;</b>	<b></b>	-4	141	2	<b>16</b>	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
CDM-60T10-E	—AC	36 V	24	<b>(</b>	RS485	R\$232 XXX	<b>()</b>	•	<b>, 101</b>	111	2	<b>≋</b> 16	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
KDM-60T10-C	DC_	36 Ÿ	24	<b>(</b>	RS485	RS232	<b>○</b> >	<b></b>		111	2	<b>≋</b> 16	1	<b>₹</b> 20	<b>×</b> 10	fieldbus XNET
— AC power supply	input		<b>()</b> ⇒	transistor	output RS2	32 RS232	NPN	<u>, 131</u>	pulse inp	ut <u>§</u> 10	right exte	ension module	fie XNE	eldbus T X-NET fi	ieldbus	
DC power supply	outpu	t	<b>®</b> ⇒	relay outp	out RS4	85 RS485	PNP	<u> </u>	pulse out	put 1≋	left exten	sion module	motio XNE	n fieldbus T X-NET	motion fieldb	us
BD board	real-ti	me clock		transistor	and relay o	utput	₹20 time	er interru	ption 3	10 externa	al interrun	tion				

#### XD5 series PLC

#### XD3 soft component updated PLC

- Max I/O numbers are 572
- 2 to 6 channels 200KHz high speed pulse output
- Large capacity of program and soft component
- Faster processing speed
- Rich extension function



model								spe	cificat	ion						
XD5-24R-E	AC-	14	10	<b>(</b>	RS485	R\$232	₿	<b></b>	<b>₽</b> 31		1	<b>≋</b> 16	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
XD5-24R-C	—DC—	14	10	<b>(</b>	RS485	RS232	₿	<b></b>	<u>_</u>		1	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-24T-E	AC-	14	10	<b>(</b>	RS485	RS232	<b>()</b>	<b></b>	<u> </u>	<b>121</b>	1	<b>≋</b> 16	1	<b>&gt;</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-24T4-E	AC-	14	10	<b>(</b>	RS485	RS232	<u></u>	<b></b>	-4	<u>141</u>	1	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-24T-C	—DC—	14	10	<b>(</b>	RS485	RS232	<b>()</b>	<b></b>	<u>, 131</u>		1	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-24T4-C	—DC—	14	10	<b>(</b>	RS485	R\$232	<b>()</b>	<b></b>	<u>, 141</u>	<u>141</u>	1	<b>≋</b> 16	1	<b>7</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-32R-E	—AC—	18	14	<b>(</b>	RS485	RS232	€	<b></b>	<b>₽</b>		1	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-32R-C	—DC—	18	14	<b>(</b>	RS485	RS232	₿	<b></b>	<u>, 131</u>		1	<b><u>≋</u>16</b>	1 ≋	<b>3</b> 20	<b>×</b> 10	fieldbus XNET
XD5-32T-E	AC-	18	14	<b>(</b>	RS485	RS232	<u></u>	<b></b>	<b>₽</b>	<b>12</b>	1	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-32T4-E	AC-	18	14	<b>(</b>	RS485	RS232	<u></u>	<b></b>	<b>4</b>	4	1	<b>≋</b> 16	1	<del>7</del> 20	<b>×</b> 10	fieldbus XNET
XD5-32T-C	-DC-	18	14	(1)	RS485	RS232	<u>()</u>	<b></b>		<b>121</b>	1	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-32T4-C	—DC—	18	14	<b>(</b>	RS485	RS232	<u></u>	<b></b>	<u>, 4</u>		1	<b><u>≋</u>16</b>	1	<b>5</b> 20	<b>×</b> 10	fieldbus XNET
XD5-48R-E	—AC	28	20	<b>(</b>	RS485	R\$232	€	<b></b>	<b>_</b> 131		2	<b>≋</b> 16	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-48R-C	—DC—	28	20	<b>(</b>	RS485	RS232	₿	<b></b>	<b>13</b> 1		2	<b>≋</b> 16	1	<b>3</b> 20	<b>※</b> 10	fieldbus XNET
XD5-48T-E	—AC—	28	20	<b>(</b>	RS485	R\$232	<b>()</b>	<b></b>	<u></u>	<b>12</b>	2	<b>≋</b> 16	1	<b>&gt;</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-48T-C	-DC-	28	20	<b>(</b>	RS485	R\$232	<u></u>	•	<b>↓</b> 131		2	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>※</b> 10	fieldbus XNET
XD5-48T6-E	—AC—	28	20	<b>(</b>	RS485	R\$232	<u></u>	<b></b>	<b>₽</b> 60	<u> </u>	2	<b>≋</b> 16	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-48T6-C	-DC-	28 *	20	<b>(</b>	RS485	R\$232	<u>()</u>	<b></b>	<b>√161</b>	<b>©</b>	2	<b>≋</b> 16	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-60R-E	AC-	36 V	24	<b>(</b>	RS485	R\$232	®⇒	<b></b>	<u>, 131</u>		2	<b>≋</b> 16	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-60R-C	—DC—	36	24	<b>(</b>	RS485	R\$232	₿	<b></b>	<b>3</b>		2	<b>≋</b> 16	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-60T-E	AC-	36	24	<b>(</b>	RS485	RS232	<b>()</b>	<b></b>	<u>, 131</u>		2	<b>≋</b> 16	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET
XD5-60T-C	-DC-	36	<u> </u>	<b>(</b>	RS485	RS232	<u></u>	•	<u>, 131</u>	121,	2	<b>≋</b> 16	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-60T6-E	AC-	36	24	<b>(</b> )	RS485	RS232	<u></u>	•	, Cin	ren_	2	<b><u>≋</u>16</b>	1	<b>3</b> 20	<b>X</b> 10	fieldbus XNET
XD5-60T6-C	-DC-	36	24	<b>(</b>	RS485	RS232	<u></u>	•	<b>_6</b>	real contract of the contract	2	<b>≋</b> 16	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET

relay output RS485 PNP pulse output relative textension module NNET X-NET motion fieldbus

#### **XDC** series PLC

—DC power supply output

Powerful motion fieldbus PLC

■ Max I/O numbers are 572

- 2 channels 200KHz high speed pulse output
- Support 16 right extension modules
   Support motion fieldbus X-NET
- Faster processing speed



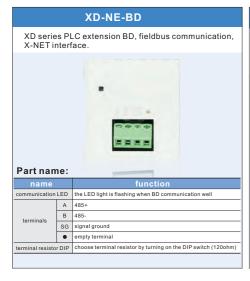
	model								spec	ification	on							
	XDC-24T-E	AC-	14	10	<b>(</b>	RS485	RS232	<b>()</b>	<b></b>	-4	<b>121</b>	1	<b>≋</b> 16	1	<b>7</b> 20	<b>×</b> 10	fieldbus XNET	motion fieldbus XNET
ĺ	XDC-24T-C	—DC—	14	10	<b>(</b>	RS485	R\$232	<u></u>	<b></b>	-41		1	<b>≋</b> 16	1	<del>7</del> 20	<b>×</b> 10	fieldbus XNET	motion fieldbus XNET
	XDC-32T-E	AC-	18	14	<b>(</b>	RS485	RS232	<u></u>	<b>*</b>	-141	<b>121</b>	1	<b>≋</b> 16	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET	motion fieldbus XNET
	XDC-32T-C	—DC	18	14	<b>(</b>	RS485	R\$232	<b>○</b> >	<b></b>	-41		1	<b>≋</b> 16	1	<b>3</b> 20	<b>×</b> 10	fieldbus XNET	motion fieldbus XNET
	XDC-60T-E	AC-	36 V	24	<b>(</b>	RS485	RS232	<b>○</b> >	•	-41	<u>121</u> ,	2	<b>≋</b> 16	1	<b>3</b> 20	<b>¥</b> 10	fieldbus XNET	motion fieldbus XNET
	XDC-60T-C	—DC	36 V	24	<b>(</b>	RS485	RS232	<u></u>	<b></b>	-141		2	<b>≋</b> 16	1	<b>7</b> 20	<b>¥</b> 10	fieldbus XNET	motion fieldbus XNET
		_													fieldb			
-	AC power supply	input 🙀		<b></b>	transist	oroutput 🕺	S232 RS232	NP	N 🚚	nulse in	nput ∭ <mark>10</mark>	right ext	ension mo	dule XN	fieldbus IET X-NET	T fieldbus		

DC power supply output Frelay output RS485 RS485 PNP PNP pulse output left extension module NET X-NET motion fieldbus BD board real-time clock transistor and relay output  $\frac{1}{20}$  timer interruption  $\frac{1}{20}$  external interruption

#### Special function extension BD board

XD series extension communication BD board

installation mode	install inside the XD PLC directly
dimension	40mm×42mm×14mm
using environment	no corrosive gas
environment temperature	0℃ ~ 60℃
environment humidity	5~95%







#### left extension module

item	specification
using environment	no corrosive gas
environment temperature	0°C ~ 60°C
storage temperature	−20 ~ 70°C
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly
dimension	25mm×100mm×89.0mm
dimension	18mm×100mm×89.0mm







#### right extension module the extension cable length can up to 1.5m

#### I/O extension

if the PLC main unit I/O numbers cannot meet the requirements, please use I/O extension module.

#### XD series I/O extension module specification

item	specification
using environment	no corrosive gas
environment temperature	0°C ~ 60°C
storage temperature	-20 ~ 70°C
environment humidity	5 ~ 95%RH
storage humidity	5 ~ 95%RH
installation	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly
dimension	70.8mm×108mm×89.0mm 108.6mm×108mm×89.0mm

#### XD series I/O extension module model list

	model	
NPN input	PNP input	function
XD-E8X	XD-E8PX	8 channels digital input, DC24V power supply
XD-E8YR	-	8 channels relay output, DC24V power supply
XD-E8YT	-	8 channels transistor output, DC24V power supply
XD-E8X8YR	XD-E8PX8YR	8 channels digital input, 8 channels relay output, DC24V power supply
XD-E8X8YT	XD-E8PX8YT	8 channels digital input, 8 channels transistor output, DC24V power supply
XD-E16X	XD-E16PX	16 channels digital input, DC24V power supply
XD-E16YR	-	16 channels relay output, no need power supply
XD-E16YT	-	16 channels transistor output, no need power supply
XD-E16X16YR-E/C	XD-E16PX16YR-E/C	16 channels digital input, 16 channels relay output, AC220V or DC24V
XD-E16X16YT-E/C	XD-E16PX16YT-E/C	16 channels digital input, 16 channels transistor output, AC220V or DC24V
XD-E32YR-E/C	-	32 channels relay output, AC220V or DC24V
XD-E32YT-E/C	-	32 channels transistor output, AC220V or DC24V
XD-E32X-E/C	XD-E32PX-E/C	32 channels digital input, AC220V or DC24V

#### Input extension module



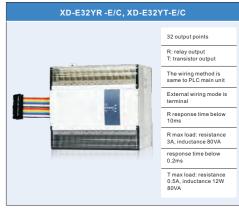




#### output extension module







#### I/O extension module





#### analog extension module

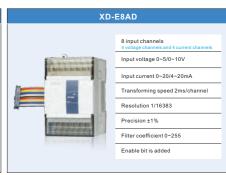
transform the analog signal to digital or digital to analog, receive and process temperature sensor signal.

#### analog extension module specification

item	specification
using environment	no corrosive gas
environment temperature	0°C ~ 60°C
storage temperature	-20 ~ 70℃
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly
dimension	63mm×108mm×89.0mm





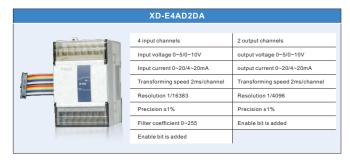


#### DA type





#### mixed type





#### temperature control extension module

Pt100 thermal resistor or thermocouple temperature measurement, PID control inside.

#### Pt100 thermal resistor

#### analog extension module XD-E6PT-P general specification

item	specification
using environment	no corrosive gas
environment temperature	0℃~60℃
storage temperature	-20 ~ 70℃
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277(width 35mm) rail directly
dimension	63mm×108mm×89.0mm

#### analog extension module XD-E6PT-P general specification

item	specification
analog input	Pt100 thermal resistor
Temperature range	-100°C ~ 500°C
Digital output range	−1000~5000, 16-bit signed value, binary
Control precision	±0.5℃
Resolution	0.1℃
Integrated precision	1% (relative max value)
Transformation speed	20ms/channel
Power supply for analog	DC24V±10%, 50mA



#### TC thermocouple

#### analog extension module XD-E6TC-P general specification

item	specification
using environment	no corrosive gas
environment temperature	0°C ~ 60°C
storage temperature	-20 ~ 70°C
environment humidity	5~95%RH
storage humidity	5~95%RH
installation	fix with M3 screw or install on the DIN46277(width 35mm) rail directly
dimension	63mm×108mm×89.0mm

#### analog extension module XD-E6TC-P performance specification

item	specification
analog input	thermocouple K, S, E, N, B, T, J, R
Temperature range	24 0~1300°C (type K)
Digital output range	25 0~13000, signed 16-bit value, binary
Control precision	±0.5℃
Resolution	0.1°C
Integrated precision	1% (relative max value)
Transformation speed	20ms/channel
Power supply for analog	DC24V±10%, 50mA

	XD-E6TCA-P	
B. Separate		
inspense.	6 temperature input channels	Control the heating and cooling
1000	Self-study function	Optional sampling period
	Temperature range 0~1300°C	Control precision ±0.5°C
	Resolution 0.1°C	Integrated precision ±1%
RESESSES.	Channel transformation speed 20ms/channel	

#### weighing extension module

transform the weighing signal to digital value

analog input range	DC -39.06 ~ 39.06mV	
Resolution	1/16777216(24Bit)	
Integrated precision	±0.1%	
Transformation speed	0~255 times/second	
Power supply	DC24V±10%,100mA	
Sensor excitation power supply	5VDC/120mA, can connect 4 350Ω weighing sensor in parallel	
Installation mode	fix with M3 screw or install on the DIN46277 (width 35mm) rail directly	
Dimension	63mm×108mm×89.0mm	
Using environment	no corrosive gas	
Environment temperature	0°0 ~ 00 ~ 00 0	
Environment humidity	5~95%	







#### MA series remote extension module

MA series modules include digital input and output, analog input and output, temperature control. It uses RS485 port and based on Modbus protocol, can connect PLC, HMI, PLC&HMI integrated controller, and other devices supporting Modbus protocol. It is fit for temperature, flow, liquid level, pressure control, can extend up to 16 modules.

digital I/O module general specification		
item specification		
input power supply voltage	DC24V±10%	
Using environment	no corrosive gas	
Environment temperature	0°C ~ 60°C	
Environment humidity	5~95%	
Installation	fix with M3 screw or install on the DIN46277(width 35mm) rail directly	
Dimension	63mm×102mm×73.3mm	

#### digital I/O

#### I/O extension module MA-nXnY

model	notes
MA-8X8YR	8 channels digital input, 8 channels digital output (relay output)
MA-8X8YT	8 channels digital input, 8 channels digital output (transistor output)
MA-16X	16 channels digital input
MA-16YR	16 channels digital output (relay output)
MA-16YT	16 channels digital output (transistor output)



#### output extension module



#### I/O extension module

MA-8X8YR, MA-8PX8YR, MA-8X8YT, MA-8PX8YT			
*****	8 input points	R response time below 10ms	
- A A	Rated input voltage DC24V	T response time below 0.2ms	
2/	Response time below 20ms	R max load: resistance 3A, inductance 80VA	
	The P in the model name means PNP input	T max load: resistance 0.5A, inductance 12W80VA	
THE PROPERTY OF	8 output points	External wiring mode is terminal	
· 克克克克克克克	R: relay output T: transistor output	The wiring method is same to PLC main unit	
255555 25555			



#### analog I/O

analog input module MA-nAD		
model	notes	
MA-4AD	4 channels, 12-bit high precision analog input (voltage/current), each channel has PID function	
MA-8AD-A	8 channels, 12-bit high precision analog input (current), each channel has PID function	
MA-8AD-V	8 channels, 12-bit high precision analog input (voltage), each channel has PID function	

analog output module MA-nDA		
notes		
2 channels, 10-bit high precision analog output (voltage/current)		
4 channels, 10-bit high precision analog output (voltage/current)		

#### analog I/O module MA-nADmDA

model	notes
MA-4AD2DA	4 channels, 12-bit high precision analog input (voltage/current), each channel has PID function; 2 channels, 10-bit high precision analog output (voltage/current)

#### AD type







output voltage 0~5/0~10V

Precision ±0.8%

#### DA type



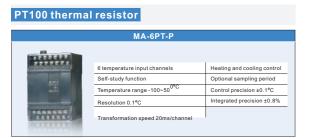






AD/DA mixed type

#### temperature control



	MA-6TCA-P	
12244		
******	6 temperature input channels	Heating and cooling contro
	Self-study function	Optional sampling period
正	Temperature range 0~1300°C	Control precision ±0.1°C
	Resolution 0.1°C	Integrated precision ±0.8%
400000	Transformation speed 20ms/channel	

#### **XD** series product specifications

#### General specification of basic unit

Item	Specification
Insulation voltage	Up DC500V 2Mohm
anti-noise	Noise voltage 1000 Vp-p 1us pulse 1 minute
Air	No corrosive and flammable gas
Environment temperature	0°C~60°C
Environment humidity	5%RH~95%RH (no condensation)
Com 1	RS232, connect to upper device, HMI to debug and programming
Com 2	RS485, connect to smart meter and VFD
Installation	fix with M3 screw or install on the rail directly
Ground	The third ground (cannot connect the ground with high voltage system

- All the basic units have com1 for programming and debug.
- The rail specification is DIN46277, the width is 35mm.
- The ground is better to use single ground or sharing ground, cannot use public ground.



Ite	ems		Specifications						
Program exe	cution mode	scan round mo	ode						
Program mo	de	Instructions, la	adder chart, C language						
Processing s	peed	0.05us							
Power off ret	entive	FlashROM and	d Li-battery (3V button battery)						
Users' progr	am capacity*1	256KB							
Total I/O numbers		16 points							
I/O points 1/O points		8 points X0~X	7						
Output numbers		8 points Y0~Y	7						
Internal Coil	s(X) <sup>83</sup>	1280 points: X	0~X77, X10000~X11777, X20000~X20277						
Internal Coi	ls(Y) <sup>∰4</sup>	1280 points: Y	0~Y77,Y10000~Y11777,Y20000~Y20277						
Internal Cail	o/M HM)	11008 points	M0~M7999 [ HM0~HM959 ] **s						
Internal Coils(M, HM)		11006 points	For Special Use 85 SM0~SM2047						
Procedure(S	;)	1152 points	S0~S1023 [HS0~HS127]						
	points	672 points	T0~T575 [HT0~HT95]						
		100mS timer:	set time 0.1~3276.7s						
Timer(T)	Specification	10mS timer: se	et time 0.01~327.67s						
		1mS timer: set	S timer: set time 0.001~32.767s						
	points	672 points	C0~C575 [ HC0~HC95 ]						
Counter(T)	Specification	16 bits counte	r: set value K0~32,767						
	Specification	32 bits counte	r: set value -2147483648~+2147483647						
Data Regist	or(D)	11048 words	D0~D7999 [HD0~HD999] **						
Data Regist	si(D)	11046 Wolus	For Special Use ** SD0~SD2047						
		5120 words	FD0~FD5119						
FlashROM F	Register (FD)	J120 WOIUS	For Special Use SFD0~SFD1999						
High speed	processing ability	High speed co	ounter, pulse output, external interruption						
Password P	rotection	6 bits ASCII							
Self-diagno	se Function	Power on self-	check, monitor timer, grammar check						

- #1: The users' program capacity means the maximum program capacity when encrypted downloading.

  #2: UP points mean terminal number that users can connect from outside.

  #3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.

  #4: Y stands for the internal output relays and can be used as middle relay when output points are exceeded.

  #5: [ ] means the default power off retentive area, this area can't be changed. \*6: For special use means special usage registers that are occupied by system, can't be applied for other usage.

#### XD2 series basic unit performance specifications XD3 series basic unit performance specifications

It	ems		Spe	cification	ıs						
Program exe	ecution mode	scan round mode									
Program mo	de	Instructions, la	dder chart, C langu	age							
Processing s	speed	0.05us									
Power off re	tentive	FlashROM and	Li-battery (3V butte	on battery)							
Users' progr	am capacity*1	256KB									
	Total I/O numbers	16 points	24 points	32 points	48 points	60 points					
I/O points **2	Input numbers	8 points X0~X7	14 points X0~X15	18 points X0~X21	28 points X0~33	36 points X0~X43					
	Output numbers	8 pointsY0~Y7	10 points Y0~Y11	24 points Y0~Y27							
Internal Coils(X) <sup>#3</sup>		1280 points: X0	1280 points: X0~X77, X10000~X11777, X20000~X20277								
Internal Coi	ils(Y) <sup>®4</sup>	1280 points: Y0	280 points: Y0~Y77, Y10000~Y11777, Y20000~Y20277								
I-4I O-11	-/4 1100		M0~M7999 [ HM	0~HM959] **s							
Internal Coils(M, HM)		11008 points	For Special Use	SM0~SM2047							
Procedure(S	5)	1152 points	S0~S1023 [ HS0	~HS127]							
	points	672 points	T0~T575 [HT0~	HT95]							
		100mS timer: set time 0.1~3276.7s									
Timer(T)	Specification	10mS timer: set time 0.01~327.67s									
		1mS timer: set time 0.001~32.767s									
	points	672 points	C0~C575 [ HC0-	-HC95]							
Counter(T)	0 10 11	16 bits counte	r: set value K0~32,	767							
	Specification	32 bits counte	r: set value -214748	33648~+21474836	647						
Data Daniet	(D)	11048 words	D0~D7999 [ HD	0~HD999] **							
Data Regist	er(D)	11048 words	For Special Use	** SD0~SD2047							
		5120 words	FD0~FD5119								
FlashROM F	Register (FD)	5120 Words	For Special Use	** SFD0~SFD1999	1						
High speed	processing ability	High speed co	unter, pulse output	, external interrupti	on						
Password P	rotection	6 bits ASCII									
Self-diagno	se Function	Power on self-	-check, monitor tim	er, grammar check							

- ## 1: The users' program capacity means the maximum program capacity when encrypted downloading.

  ## 2: I/O points mean terminal number that users can connect from outside.

  ## 3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.

  ## 4: Y stands for the internal output relays and can be used as middle relay when output points are exceeded.

  ## 5: [ ] means the default power of referentive area, this area can't be changed.

  ## 6: For special use means special usage registers that are occupied by system, can't be applied for other usage.

#### XD5 series basic unit performance specifications XDM series basic unit performance specifications

It	ems			Specifications							
Program ex	ecution mode	scan round mode									
Program mo	ode	Instructions, la	dder	chart, C language							
Processing	speed	0.05us									
Power off re	tentive	FlashROM and	Li-ba	ttery (3V button batter)	()						
Users' progr	ram capacity <sup>61</sup>	384KB									
	Total I/O numbers	24 points		32 points	48 points	60 points					
I/O points **2	Input numbers	14 points X0~X	15	18 points X0~X21	28 points X0~33	36 points X0~X43					
	Output numbers	10 points Y0~Y	11	14 points Y0~Y15	20 points Y0~Y23	24 points Y0~Y27					
Internal Coi	Is(X) <sup>®3</sup>	1280 points: X0~X77, X10000~X11777, X20000~X20277									
Internal Coils(Y)**		1280 points: Y0	1280 points: Y0~Y77, Y10000~Y11777, Y20000~Y20277								
Internal Coils(M, HM)		92000 points		M0~M74999 [ HM0~HM11999 ] *5							
internal Colls(M, HM)		92000 points	For	r Special Use SM0~	SM4999						
Procedure(	S)	9000 points	S0	~S7999 [ HS0~HS999	1						
	points	7000 points	T0-	~T4999 [HT0~HT199	9]						
		100mS timer: set time 0.1~3276.7s									
Timer(T)	Specification	10mS timer: set time 0.01~327.67s									
		1mS timer: set time 0.001~32.767s									
	points	7000 points	C0~	C4999 [ HC0~HC199	9]						
Counter(T)	Specification	16 bits counter	set v	alue K0~32,767							
	Opecinication	32 bits counter	set v	alue -2147483648~+2	147483647						
Data Regist	tor(D)	100000 words	D0~	D69999 [ HD0~HD249	99] **						
Data Regist	ler(D)	100000 words	For	Special Use SD0~SI	04999						
E	(50)	44400	FD0	~FD8191							
FlashROM	Register (FD)	14192 words	For	Special Use SFD0~S	FD5999						
High speed	processing ability	High speed cou	inter,	pulse output, external	interruption						
Password F	Protection	6 bits ASCII									
Self-diagno	se Function	Power on self-o	heck,	, monitor timer, gramm	ar check						

- #2: I/O points mean terminal number that users can connect from outside. \*3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.
- 4:4 Y stands for the internal output relays and can be used as middle relay when output points are exceeded.

  45: [ ] means the default power off retentive area, this area can't be changed.

  66: For special use means special usage registers that are occupied by system, can't be applied for other usage.

lte	ems			<b>Specifications</b>				
Program exe	cution mode	scan round mo	de					
Program mo	de	Instructions, la	dder char	t, C language				
Processing s	speed	0.05us						
Power off ret	tentive	FlashROM and	d Li-battery	(3V button battery)				
Users' progr	am capacity*1	384KB						
	Total I/O numbers	24 points		32 points	60 points			
I/O points <sup>®2</sup>	Input numbers	14 points X0~X	(15	18 points X0~X21	36 points X0~X43			
Output numbers		10 points Y0~Y	′11	14 points Y0~Y15	24 points Y0~Y27			
Internal Coils(X)*3		1280 points: X	0~X77, X1	0000~X11777, X20000~X20277				
Internal Coi	Internal Coils(Y)**4		0~Y77, Y1	0000~Y11777, Y20000~Y20277				
			M0~M74	M74999 [ HM0~HM11999 ] **				
Internal Coils(M, HM)		92000 points	For Spe	cial Use SM0~SM4999				
Procedure(S)		9000 points	S0~S79	99 [ HS0~HS999 ]				
	points	7000 points	T0~T49	99 [HT0~HT1999]				
		100mS timer: set time 0.1~3276.7s						
Timer(T)	Specification	10mS timer: set time 0.01~327.67s						
		1mS timer: set time 0.001~32.767s						
	points	7000 points	7000 poir	nts				
Counter(T)	Specification	16 bits counter	r: set value	K0~32,767				
	Specification	32 bits counter	r: set value	-2147483648~+2147483647				
	(5)		D0~D699	999 [ HD0~HD24999 ] **				
Data Regist	er(D)	100000 words	For Spec	ial Use SD0~SD4999				
			FD0~FD	8191				
FlashROM F	Register (FD)	14192 words	For Spec	ial Use SFD0~SFD5999				
High speed	processing ability	High speed cou	ınter, pulsı	output, external interruption				
Password P	rotection	6 bits ASCII						
Self-diagno	se Function	Power on self-o	heck mor	nitor timer, grammar check				

- \*2: I/O points mean terminal number that users can connect from outside
- \*3: X stands for the internal input relays and can be used as middle relay when input points are exceeded.
- 44: Y stands for the internal output relays and can be used as middle relay when output points are exceeded.

  55: [ ] means the default power off retentive area, this area can't be changed.

  66: For special use means special usage registers that are occupied by system, can't be applied for other usage.

#### XDC series basic unit performance specifications

Ite	ems		S	pecifications					
Program ex	ecution mode	scan round mode							
Program mo	de	Instructions, ladd	ler chart, C	language					
Processing:	speed	0.05us							
Power off re	tentive	FlashROM and Li-battery (3V button battery)							
Users' progr	am capacity <sup>11</sup>	384KB							
	Total I/O numbers	24 points		32 points	60 points				
I/O points <sup>#2</sup>	Input numbers	14 points X0~X15	5	18 points X0~X21	36 points X0~X43				
	Output numbers	10 points Y0~Y11	ı	14 points Y0~Y15	24 points Y0~Y27				
Internal Coil	s(X) <sup>#3</sup>	1280 points: X0~	X77, X1000	0~X11777, X20000~X20277					
Internal Co	ils(Y)**	1280 points: Y0~	1280 points: Y0~Y77, Y10000~Y11777, Y20000~Y20277						
l-4   0-11	-(14 1114)	92000 points	M0~M74	999 [ HM0~HM11999 ] "5					
Internal Coil	s(M, FM)	92000 points	For Spec	cial Use SM0~SM4999					
Procedure(S	3)	9000 points	S0~S7999 [ HS0~HS999 ]						
	points	7000 points	T0~T499	9 [HT0~HT1999]					
		100mS timer: set time 0.1~3276.7s							
Timer(T)	Specification	10mS timer: set t	ime 0.01~3	27.67s					
		1mS timer: set time 0.001~32.767s							
	points	7000 points	C0~C499	9 [ HC0~HC1999 ]					
Counter(T)	0 15 11	16 bits counter: s	et value K0	~32,767					
	Specification	32 bits counter: s	et value -21	47483648~+2147483647					
Data Davida	(D)	100000 words	D0~D699	99 [ HD0~HD24999 ] **					
Data Regist	er(D)	100000 words	For Specia	al Use SD0~SD4999					
			FD0~FD8	191					
FlashROM F	Register (FD)	14192 words	For Specia	al Use SFD0~SFD5999					
High speed	processing ability	High speed count	ter, pulse ou	utput, external interruption					
Password P	rotection	6 bits ASCII							
Self-diagno	se Function	Power on self-ch	eck, monito	r timer, grammar check					

- #1: The users' program capacity means the maximum program capacity when encrypted downloading.
  #2: I/O points mean terminal number that users can connect from outside.
  #3: X stands for the internal input relays and can be used as middle relay when input points are exceeded
  #4: Y stands for the internal output relays and can be used as middle relay when output points are exceed
  #5: [ ] means the default power off retentive area, this area can't be changed.
- \*6: For special use means special usage registers that are occupied by system, can't be applied for other usage

#### Power supply specification

#### AC power supply

Items	Content
Rated Voltage	AC100V~240V
Allowed Voltage Range	AC90V~265V
Rated Frequency	50/60Hz
Allow momentary power off time	Interruption Time ≤ 0.5 AC cycle, interval ≥ 1s
Impulse Current	Max 40A below 5mS/AC100V max 60A below 5ms/AC200V
Maximum Power Consumption	12W
Power Supply for Sensor	24VDC±10% 16 points max is 200mA ,32 points max is 400mA

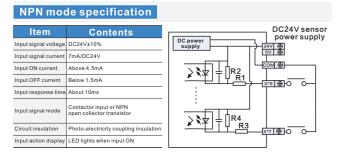
#### DC power supply

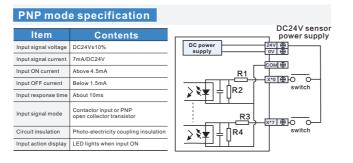
Items	Content
Rated Voltage	DC24V
Allowed Voltage Range	DC21.6V~26.4V
Input Current (Only for basic unit)	120mADC24V
Allow momentary power off time	10msDC24V
Impulse Current	10ADC26.4V
Maximum Power Consumption	12W
Power Supply for Sensor	24VDC±10% 16 points max is 200 mA, 32 points max is 400mA

- Please use the wire cable more than 2mm2 to avoid the decrease of
- Even power off in 10ms, the PLC can still keep working. But when power is off for long time or voltage abnormally decrease, the PLC will stop working, output will be OFF. When power is on again, the PLC will run automatically.
- The grounding terminals on basic units and extensions are connected together, and connected to the ground well (the third kind of ground).

#### Input specification and wiring

the Input includes NPN and PNP mode.





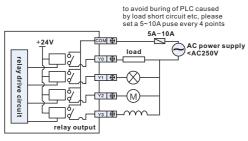
#### Output specification and wiring

The output includes relay and transistor mode.

#### **Output specification**

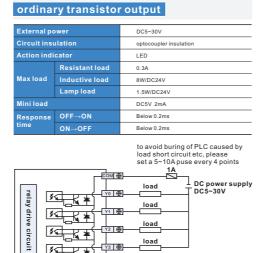
Max output pulse frequency





#### High speed pulse output RT or T External Power Supply Below DC5~30V

200KHZ



#### High speed counter configuration table

		XD2-16R/T											
		single phase incremental mode AB phase mode											
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8	
max frequency	10K	10K	10K					5K	5K	5K			
4-time frequency								2/4	2/4	2/4			
Counter interruption	4	√	4					4	4	√			
X000	U							Α					
X001								В					
X002													
X003		U							А				
X004									В				
X005			U										
X006										Α			
X007										В			

				XD5	-24T/3	32T/48	T/60T					
		sin	gle pha	se incre	ementa	l mode		AB phase mode				
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8
max frequency	80K	80K	80K					50K	50K	50K		
4-time frequency								2/4	2/4	2/4		
Counter interruption	4	4	√					4	√	4		
X000	U							Α				
X001								В				
X002												
X003		U							Α			
X004									В			
X005												
X006			U							Α		
X007										В		
X010												
X011												
X012												
X013												

single phase incremental mo

	A	B phase	e mode		
HSC0	HSC2	HSC4	HSC6	HSC8	HSC10
50K	50K	50K	50K	50K	50K
2/4	2/4	2/4	2/4	2/4	2/4
4	4	√	4	4	4
Α					
В					
	Α				
	В				
		Α			
		В			
			A B		
			-		
				A	
1		1	1	1	1

			XE	3-16/	24/32/	48/60	T/R/R	Ī				
		sin	gle pha	se incre	emental		AB phase mode					
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8
max frequency	80K	10K	10K					50K	5K	5K		
4-time frequency								2/4	2/4	2/4		
Counter interruption	4	1	4					4	4	4		
X000	U							Α				
								В				
X003		U							А			
X004									В			
X005												
X006			U							Α		
										В		
X010												

				Х	D5-24	T4/32	T4					
		single	ohase ii		ntal mo			AE	3 phase	mode		
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10
max frequency	80K	80K	80K	80K			50K	50K	50K	50K		
4-time frequency							2/4	2/4	2/4	2/4		
Counter interruption	<b>√</b>	4	√	√			4	√	4	√		
X000	U						Α					
X001							В					
X002												
X003		U						А				
X004								В				
X005												
X006			U						Α			
X007									В			
X010												
X011				U						Α		
X012										В		
X013												
X014												
X015												
X016												
X017												
X020												
X021												

		single phase incremental mode							AB p	AB phase mode			
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8	
max frequency	80K	80K	80K	80K				50K	50K	50K	50K		
4-time frequency								2/4	2/4	2/4	2/4		
Counter interruption	√	4	√	√				4	√	4	4		
X000	U							Α					
X001								В					
X002													
X003		U							Α				
X004									В				
X005													
X006			U							Α			
X007										В			
X010													
X011													
X012				U							Α		
X013											В		

30

X010

X014 X015 X016



					XDI	1-60T1	0					
				single p		cremen		le				
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC14	HSC16	HSC18	HSC20	HSC22
max frequency	80K	80K	80K	80K	80K	80K	80K	80K	10K	10K		
4-time frequency												
Counter interruption	4	4	4	√	<b>4</b>	√	4	4	4	4		
X000	U											
X001												
X002												
X003		U										
X004												
X005												
X006			U									
X007												
X010												
X011				U								
X012												
X013												
X014					U							
X015												
X016												
X017						U						
X020												
X021												
X022							U					
X023												
X024												
X025								U				
X026												
X027												
X030									U			
X031												
X032												
X033										U		
X034												

					XDN	1-60T1						
					AB ph	ase mo	de					
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC14	HSC16	HSC18	HSC20	HSC22
max frequency	50K	50K	50K	50K	50K	50K	50K	50K	5K	5K		
4-time frequency												
Counter interruption	√	4	4	√	4	4	4	4	4	4		
X000	Α											
X001	В											
X002												
X003		А										
X004		В										
X005												
X006			Α									
X007			В									
X010												
X011				А								
X012				В								
X013												
X014					Α							
X015					В							
X016												
X017						A						
X020						В						
X021												
X022							А					
X023							В					
X024												
X025								А				
X026								В				
X027												
X030									А			
X031									В			
X032												
X033										А		
X034										В		
X035												

#### Serial port (RS232/RS485) communication parameters

Item	Parameters
Communication mode	Half duplex
Baud rate	9600bps, 19200bps (defaulted), 38400bps, 57600bps, 115200bps
Data type	Data bit: 5, 6, 7, 8(defaulted), 9 Stop bit: 1(defaulted), 1.5, 2 Parity bit: no parity, odd, even(defaulted)
Mode	RTU(defaulted), ASCII, free format, fieldbus X-NET
Station number	1~255 (defaulted is 1)
Before sending delay	1~100ms(defaulted is 3ms)
Reply overtime	1~1000ms(defaulted is 300ms)
Retry times	1~20 times(defaulted is 3 times)

#### Instruction list

#### **Application instruction**

Type	Instruction	Function
	CJ	Condition jump
- □	CALL	Call the subprogram
5	SRET	Subprogram return
g l	STL	Process start
3	STLE	Process end
힏	SET	Open assigned process, close present process
0	ST	Open assigned process, not close present process
es	FOR	Cycle start
s	NEXT	Cycle end
	FEND	Main program end
	LD=	Initial logic ON when (S1)=(S2)
	LD>	Initial logic ON when (S1)>(S2)
	LD<	Initial logic ON when (S1)<(S2)
	LD<>	Initial logic ON when (S1)≠(S2)
	LD>=	Initial logic ON when (S1)≥(S2)
,	LD<=	Initial logic ON when (S1)≤(S2)
2	AND=	Serial connection ON when (S1)=(S2)
Ö	AND>	Serial connection ON when (S1)>(S2)
9	AND<	Serial connection ON when (S1)<(S2)
ğ	AND<>	Serial connection ON when (S1)≠(S2)
5	AND>=	Serial connection ON when (S1) ≥ (S2)
0	AND<=	Serial connection ON when (S1)≤(S2)
-	OR=	Parallel connection ON when (S1)=(S2)
	OR>	Parallel connection ON when (S1)>(S2)
	OR<	Parallel connection ON when (S1)<(S2)
	OR<>	Parallel connection ON when (S1)≠(S2)
	OR>=	Parallel connection ON when (S1) ≥ (S2)
	OR<=	Parallel connection ON when (S1)≤(S2)
	CMP	Data comparison
0	ZCP	Data range comparison
at	MOV	Transmission
Ŧ	BMOV	Data block transmission
an	FMOV	Multi-point repeat transmission
sn	FWRT	Write in FlashROM
<u>1</u> .	MSET	Batch set on
<u>s</u> .	ZRST	Batch reset
š	SWAP	Exchange the high byte and low byte
	XCH	Exchange the data
0 🗆	ADD	Addition
a at	SUB	Subtraction
u a	MUL	Multiplication
a	DIV	Division
0	INC	Increase by one
_	DEC	Decrease by one
	Program process Data comparison Data transmission Calculation	CJ

Туре	Instruction	Function
D	MEAN	Get the mean value
ata	WAND	Logic AND
Data calculation	WOR	Logic OR
드	WXOR	Logic XOR
2	CML	Reverse
š	NEG	Negative
	SHL	Arithmetic shift left
	SHR	Arithmetic shift right
	LSL	Logic shift left
D	LSR	Logic shift right
ä	ROL	Cycle shift left
Data shift	ROR	Cycle shift right
≟	SFTL	Bit shift left
-	SFTR	Bit shift right
	WSFL	Word shift left
	WSFR	Word shift right
	WTD	Word integer change to double word integ
	FLT	16 bits integer change to floating number
Ď	FLTD	64 bits integer change to floating number
ä	INT	Floating number change to integer
=	BIN	BCD code change to binary
Data transformation	BCD	Binary change to BCD code
S <sub>C</sub>	ASCI	Hex change to ASCII
à	HEX	ASCII change to hex
a	DECO	Decoding
<u>ō</u> .	ENCO	High-bit encoding
_	ENCOL	Low-bit encoding
	GRY	Binary change to gray code
	GBIN	Gray code change to binary
	ECMP	Floating number comparison
	EZCP	Floating number range comparison
Ξ.	EADD	Floating number addition
oa	ESUB	Floating number subtraction
<b>÷</b>	EMUL	Floating number multiplication
g	EDIV	Floating number division
<u>8</u>	ESQR	Floating number square
Floating calculation	SIN	Floating number sine
	cos	Floating number cosine
	TAN	Floating number tangent
	ASIN	Floating number arcsine
	ACOS	Floating number arccosine
	ATAN	Floating number arctangent
Clock	TRD	Read clock data
CIOCK	TWR	Write clock data

#### **Basic instruction**

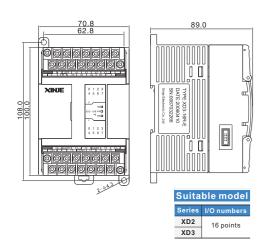
Instruction	Function
LD	Initial logic normally open contactor
LDI	Initial logic normally close contactor
AND	Serial connection normally open contactor
ANI	Serial connection normally close contactor
OR	Parallel connection normally open contactor
ORI	Parallel connection normally close contactor
LDP	Initial logic rising-edge of pulse
LDF	Initial logic falling-edge of pulse
ANDP	Serial connection rising-edge of the pulse
ANDF	Serial connection falling-edge of the pulse
ORP	Parallel connection rising-edge of the pulse
ORF	Parallel connection falling-edge of the pulse
LDD	Read normally open contactor
LDDI	Read normally close contactor
ANDD	Read normally open contactor, serial connection
ANDDI	Read normally close contactor, serial connection
ORD	Read normally open contactor, parallel connection
ORDI	Read normally close contactor, parallel connection
OUT	Coil drive
OUTD	Output to the contactor
ORB	Parallel connection of serial circuit block
ANB	Serial connection of parallel circuit block
MCS	New generatrix start
MCR	Generatrix reset
ALT	Coil reverse
PLS	ON for one scanning period at rising-edge
PLF	ON for one scanning period at falling-edge
SET	Keep the coil ON
RST	Reset the coil
TMR	Timer drive
OUT	Counter drive
RST	Reset the contactor or present value
END	I/O operation and return to step 0
GROUP	Instruction block folding start
GROUPE	Instruction block folding end

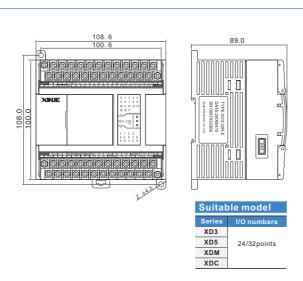
#### Special instruction

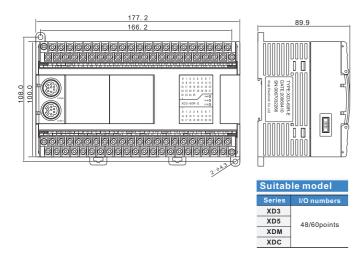
Type	Instruction	Function		
	PLSR	Multi-segment pulse output		
	PLSF	Variable frequency pulse output		
Pulse output	ZRN	Mechanical return to zero		
	PLSMV	Refresh the pulse number immediately		
	STOP	Stop the pulse		
	DMOV	Read 32 bits high speed counter		
High speed	DMOV	Write 32 bits high speed counter		
counter	CNT (_AB)	100-segment high speed counter interruption		
	CNT (_AB)	Electronic cam		
	RST	Reset high speed counter		
	COLR	Modbus read coil		
	INPR	Modbus read input coil		
	COLW	Modbus write single coil		
Modbus communication	MCLW	Modbus write multi coils		
communication	REGR	Modbus read register		
	INRP	Modbus read input register		
	REGW	Modbus write single register		
	MRGW	Modbus write multi registers		
	STR	Precise timing		
Precise timing	DMOV	Read precise timing register		
	STOP	Stop precise timing		
	EI	Enable the interruption		
Interruption	DI	Disable the interruption		
	IRET	Interruption return		
	SBLOCK	Block start		
_	SBLOCKE	Block end		
Sequence block	SBSTOP	Stop block		
DIOCK	SBGOON	Continue running the stop block		
	WAIT	Wait		
Write and read	FROM	Read the module		
the module	TO	Write in		
	FRQM	Frequency measurement		
Others	PWM	Pulse width modulation		
Cincis	PID	PID control		
	NAME C	C function block		

#### Dimension (unit: mm)

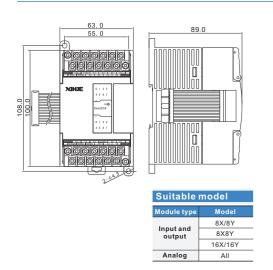
#### XD series basic unit

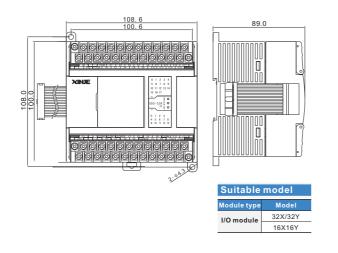




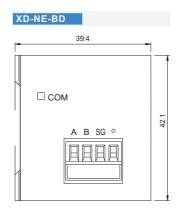


#### XD3 series right extension module

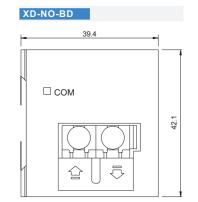




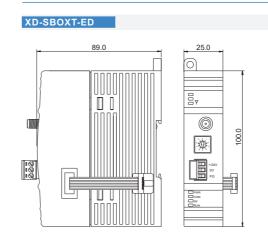
#### XD series extension BD

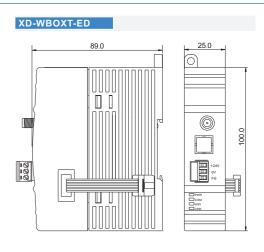


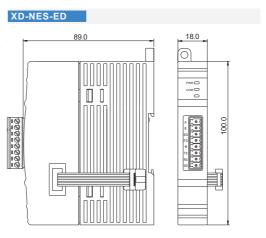




#### XD series left extension module







## XC Series

#### Special function extension BD board



channels 14 bits high precise input(voltage), channels PT100 temperature input, with PID

# XC-2AD2PT-H-BD

hannels 14 bits high precise input(voltage), nnels PT100 temperature input, with PID ction. Electrical isolation with PLC main unit nanced protection for AD input.

Connect the PLC with the Ethernet, the function the same to T-BOX.

















2 channels analog voltage input, 2 channe analog current input.



Connect to PLC for RS485 optical fiber comm

2 channels analog voltage input, 2 channels analog current input. Electrical isolation with PLC main unit, enhanced protection for AD input.

#### Special PLC









#### Peripheral equipment















#### XC basic unit

#### XC1 series affordable

Compact model fit for general applications, the functions include logic control, data calculation and other basic functions

#### • XC5 series enhanced

All the functions of XC3 series, 4-axis pulse output (24/32 support), CANBUS network, can connect expansion module and BD, the register numbers are more than XC3.

#### XC2 series basic

The functions include data processing, high speed count, high speed pulse output, communication. The processing speed is 2 times of XC1 series. The register numbers are less than XC3, cannot expand module but can connect expansion BD (except 14/16/42 models).

#### XCM series motion control

upport motion control instructions, the functions include two-axis linkage, interpolation, following, coordinates transformation (except I/O 60), 3-10 axes pulse output. Support most functions of XC series such as PID control, high speed count, interruption. Can connect expansion modules and BD.

#### XC3 series standard

The functions include data processing, high speed count, high speed pulse output, communication, PWM, frequency measurement, precise timing, interruption. Can connect expansion module and BD(14 I/O cannot support any expansions, 42 I/O cannot support BD).

#### • XCC series high performance

Faster processing speed, support 5 channels pulse output, 5 channels AB phase high speed count, motion control instructions, 2-axis linkage, interpolation, following, coordinates transformation, most functions of XC series such as high speed count, high speed pulse output, interruption, PID control. Can connect expansion modules and BD.





#### Expansion modules XCC series PLC only can connect XCL series expansion module







XC-E2DA(-H) XC-E4DA(-H) XC-E4DA-B-H XCL-E4DA

XC-E2AD-H XC-E4AD(-H) XC-E8AD(-H) XC-E8AD-B



Pt100 thermal resistor and K/E thermocouple signal input,

PT100	Thermocouple model	Analog and temperatur mixed model		
XC-E2PT-H XC-E6PT(-H) XC-E6PT-P(-H)	XC-E2TCA-P XC(L)-E6TCA-P	XC-E3AD4PT2DA(-H) XC-E2AD2PT2DA		







Based on Modbus protocol, can extend up to 16 modules

MA-8X8YR, MA-8X8YT MA-16X MA-16YR, MA-16YT	MA-2DA, MA-4DA MA-4AD, MA-8AD-A(V) MA-4AD2DA	MA-6PT-P MA-6TCA-P

\* the model with "H" is photoelectricity isolation for each chann

#### High speed calculation

Basic instruction 0.2~0.5us, scanning time 10000 steps 5ms, program capacity 32K~256K.

#### Rich extensions

In order to meet more application needs, XC series PLC can extend I/O module, analog module, temperature control module. Can extend 7 different modules and 1 BD board.

#### ● I/O extension module

- ► To extend I/O numbers, the numbers are 8~32, can extend the basic unit I/O numbers to 540
- ► The output expansion module contains transistor (T) and relay (R).

#### Analog and temperature extension module

- ► AD, DA transformation function, fit for process control system such as temperature, flow, liquid level, pressure, etc
- ► Built-in PID function, wide range of application, high control accuracy
- ► Each channel of XC-E6TCA-P and XC-E2AD2PT2DA can perform PID and auto-tune individually, exchange data with PLC by instruction FROM and TO



#### Extension BD

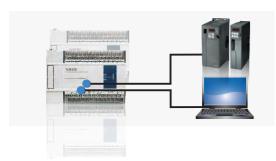
- AD, DA transformation function, fit for process control system such as temperature, flow, liquid level, pressure, etc
- Can install on the PLC directly, not occupy extra space, with wired and wireless communication functions

#### Larger capacity for soft component



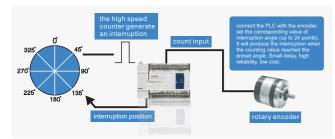
#### **Communication function**

Multi-communication port (max 4 ports), support RS232, RS485, Ethernet. Can communicate with frequency inverter, meter and other devices, easy to build communication network.



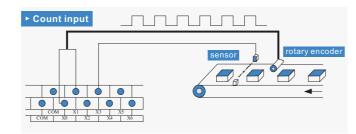
#### 24-segment high speed count interruption

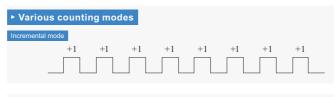
- High speed count interruption has good real-time feature
- $\bullet$  The high speed count has 24-segment 32 bits preset value, the interruption is produced when the count difference value is equal to the preset value.

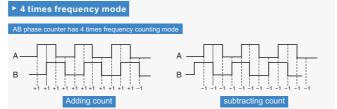


#### High speed count

- XC series PLC has 2-6 channels 2 phases 32 bits high speed counter and high speed count comparator, can connect rotary encoder directly and count the encoder signal
- The counting mode includes single phase (incremental mode), pulse and direction mode, AB phase mode (1 time, 4 times). The max frequency is 80KHz





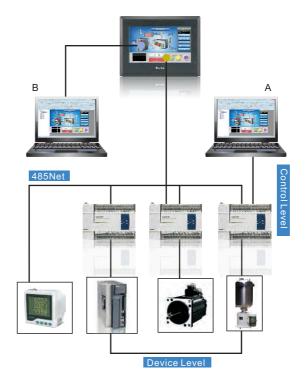


#### Enhanced communication and networking function

XC series PLC supports Modbus protocol, free format protocol and other complicated network. The PLC can communicate with printer and meter through free format protocol.

#### Modbus networking

XC series PLC supports Modbus master-slave mode. PLC master station can send requests to other devices, other devices will response it. PLC slave station only can response the master station.



#### Up to 200KHz pulse output, support 10 channels

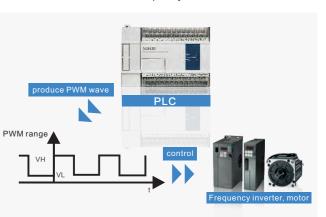
XC2/XC3 (I/O 48/60) have 2 channels pulse output. Support multi-mode output with different instructions. The output frequency can up to 200KHz.

- ▶ It needs transistor output PLC to output pulse, such as XC3-14T-E or XC3-60RT-E
- ► XC5 (I/O 24/32) series have 4 channels pulse output (Y0~Y3)
- ► XCC-32T-E has 5 channels pulse output (Y0~Y4)
- ➤ XCM-60T-E has 10 channels pulse output (Y0~Y11)



#### PWM pulse width modulation

- PWM instruction has pulse width modulation function.
- This function can control the frequency inverter and DC motor.



#### Interruption function

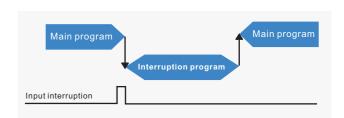
The interruption function includes external interruption, timing interruption, 24-segment high speed count interruption. The special operations can be done by calling the interruption. It will not be affected by the PLC scanning period.

#### External interruption

► X terminal is the external interruption input, each X is corresponding to an interruption which is activated by falling or rising edge.

#### Timing interruption

▶ The timing interruption is very useful when it needs to process special program in long running period main program, or it needs to run special program every certain time in sequence control program. The interruption will not be affected by PLC scanning period. The interruption subprogram will run every N ms



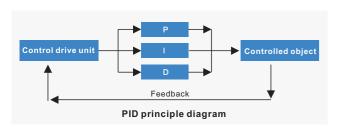
#### C programming function

- $\bullet$  Better program privacy, the C program is invisible after encrypted and can be called in the main program.
- Support rich calculation functions: contain all the C functions.
- Save internal space, reduce the workload, programming is more efficient.



#### PID control

- XC series PLC has PID control instruction and auto-tune function.
- Users can get the best sampling time and PID parameters by auto-tune function, improve the controlling accuracy.





#### Sequence block

All the instructions run one by one in the sequence block. The next instruction will run after the current instruction ends.

• The block can optimize the programming method of pulse and communication instruction in the program.

Multi-pulse and communication instructions cannot run at the same time in the process which makes the programming method complicated. The block can simplify the program.

#### **Precise timing**

- 32 bits instruction STR is precise timing function.
- The precise timer will generate an interruption flag when it reaches the timing value. Each precise timer has corresponding interruption flag.
- The precise timer is a 1ms 32 bits timer.

#### Real-time clock

• Built-in real-time clock, Li-battery power-off retentive.

#### Password protection

• 6 bits ASCII, protect the program security

# SBLOCK sequence block n User program Pulse Communication Inverter configuration Wait Command list SBLOCKE BLOCK START All the instructions run in the block one by one

#### Frequency measurement

32 bits instruction FRQM can measure the frequency.

#### Self-diagnosis

 Power-on self-examination, timer monitoring, grammar checking.

#### Small size, easy to install

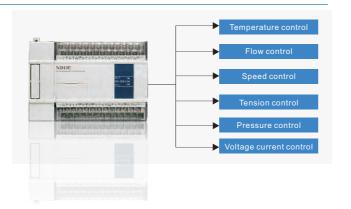
• Compact structure, improve the utilization, two installation modes.

#### XC3-19AR-E meets diverse needs

- Has analog I/O without connecting extension module
- ► Logic control and analog I/O in one unit

  Digital input: 9 (NPN optical-coupler isolation); digital output: 10 (relay)

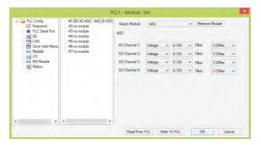
  Analog input: 8 (voltage); analog output: 2 (voltage/current)
- bits high precision analog input, 8 bits analog output
- ullet 2 channels AB phase input, 4 channels high speed count (10KHz).
- $\bullet$  2 channels 32 bits pulse output, cost-effective, save space



#### XCPpro software

#### Support all series of PLC products

XCPpro software is fit for XC series PLC and XMH, XMP, XP series HMI&PLC integrated controller. It can make PLC program and configure the network module extension module and extension BD.



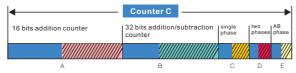
#### Panel configuration

- Reduce the difficulty of making complicated instructions
- XCPpro provides easy editing environment for complicated instructions such as multi-pulse output, PID control, 24-segment high speed count interruption.
- Improve the configuration of pulse instruction
- New pulse instructions such as PTO are added to XCPpro software, these instructions can be configured in the panel.



#### Power-off retentive in sections

- User can set the power-off retentive range of ED register
- XCPpro software can set the power-off retentive range of various registers such as timer, counter by changing the value in FD register.



The shaded area is power-off retentive. Area A, B, C, D, E can be set by users

#### **Enhanced password function**

The password can block the program uploading and protect the intellectual property rights of user. The password is also added to program downloading to avoid program damage.



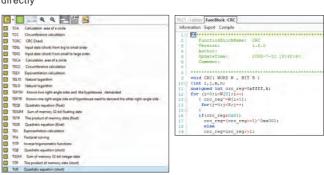
#### Powerful programming ability, better compatibility

programming software.

- Support ladder chart and instructions, the two modes can be switched.
   XCPpro software can make C program, no need change to C
- The function block can be exported and imported, support source code and passive code. If exporting the passive code, the program cannot be read. The privacy is better.



C function library contains more C instructions which can be called directly



#### Serial port setting

#### Enable to configure from com1 to com256.

#### Download the program online

com1 • Online downloading will not clear the data and shut down the output. PLC will auto-run after downloading.

#### Better system compatibility

- Compatible with different OS: Windows2000/XP/7.
- Support 64 bits operation system.

#### Calculate the program size

• The programmer can command the program capacity accurately.

#### Useful simple functions

Cancel, redo, forward, backward, grammar, checking, instruction prompt.



#### **Industry Ethernet module T-BOX**

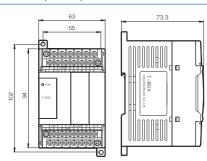
#### Open network, enhanced communication ability

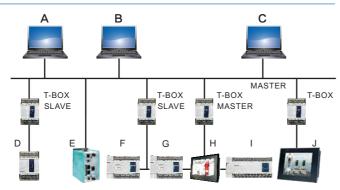
• Support Modbus-TCP protocol, connect all the industry devices by T-BOX to form Ethernet control system. It breaks the island state of traditional industry automation, makes the communication more efficient and realizes a wide range of open network.

#### Equipped T-BOX with the PLC brings many advantages

- Flexible distributed automation structure, simplify the system management
- Access Ethernet via RJ45 port and TCP/IP protocol.
- Realize remote programming, monitoring and diagnosing via Ethernet, save time and cost.
- Store and manage the information via Ethernet, simplify the operation of data processing.
- Cost-effective, easy to maintain, friendly diagnosis function
- Modbus communication is one-master multi-slave mode, the speed is very slow.
   Multi-station devices can high-speed exchange data between master and slave PLC through T-BOX.

#### Dimension (unit: mm)





#### Wireless data transmission module G-BOX

The G-BOX with XC series PLC can make wireless connection with GPRS or GSM network. It supports Modbus-TCP protocol, fit for distributed system and remote monitoring.

#### **Features**

- Open and transparent data transmission
- Data terminal has TCP/IP protocol stack inside, support TCP, UDP, DNS,
   DRP etc.
- Standard industry interface (RS232 or RS485)
- Persistent online mode, with break redial and heartbeat function
- Support SMS sending and receiving
- Support local configuration
- Support GPRS and GSM network communication



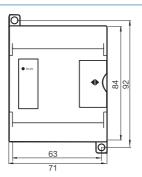
### Wireless upload and download PLC program, real-time monitoring

It is hard to monitor and change the PLC program in remote control system. If XC series PLC is equipped with G-BOX, user can monitor the device, wireless upload/download program via PC though the system is in remote place.

#### Communicate with mobile by SMS

When PLC is equipped with G-BOX, PLC can communicate with user's mobile by SMS. User can remote monitor the PLC state with the mobile. If the PLC has problem, G-BOX will send error code to user's mobile, after user replied the G-BOX, G-BOX will send the user's modification SMS to the PLC to solve the problem.

#### Dimension (unit: mm)



#### Wireless networking W-BOX

W-BOX can be configured as wireless STA and AP, support 2 wireless interfaces in theory.

- AP mode: PC and mobile phone can search this hot spot and connect the PLC, HMI through virtual serial port of W-BOX.
- STA+AP mode: W-BOX has AP+STA function, STA interface can connect router and server in the network through TCP. PC and mobile phone can connect AP interface to control serial port device and configure the module.

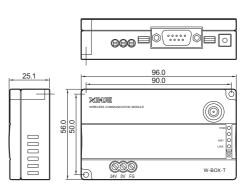
#### **Application**

- Remote device monitoring
- Application of the internet of things
- Industry control
- Handheld device

#### Compatible PLC version and series

series	V	<b>/</b> -ВОХ-Т	XD-	WBOXT-ED
XD	×	not support	V	v3.2 and up
XC	V	XC2 and up	×	not support

#### Dimension (unit: mm)





#### **Transparent transmission S-BOX**

- Wireless transparent transmission, no protocol. The two modules can communicate with each other when the baud rate (DIP switch), channel (button) settings are same. It makes the communication of HMI, PC, PLC faster and easy.
- S-BOX includes S-BOX-T and XD-SBOXT-ED, the latter only can be used to left extension module of XD series PLC.



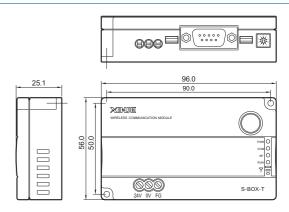


# XD-SBOXT-ED XD-SBOXT-ED connect to XD series PLC

#### **Application**

- Wireless meter reading, wireless sensor
- Container information management
- Automation data collection
- Industry control, telemetry
- POS system, asset management
- Building automation and security
- The electric power monitoring of high temperature and high pressure
- Meteorological monitoring and remote sensing

#### Dimension (unit: mm)



<sup>\*</sup>Note: this model is special for left extension module of XD series PLC, the functions are same to S-BOX-T.

# MA series data acquisition and control module

MA series module includes digital I/O, analog I/O and temperature control. MA module has RS485 port which based on Modbus protocol, can connect to PLC, HMI, integrated PLC&HMI controller and other devices which support Modbus. It is suitable for process control system such as temperature, flow, level, pressure. Support 16 extension modules.



#### Digital I/O module MA-nXnY

Туре	Explanation
MA-8X8YR	8 channels digital input, 8 channels digital output (relay output)
MA-8X8YT	8 channels digital input, 8 channels digital output (transistor output)
MA-16X	16 channels digital input
MA-16YR	16 channels digital output (relay output)
MA-16YT 16 channels digital output (transistor output)	

#### Analog output module MA-nDA

Type	Explanation
MA-2DA	2 channels 10 bits high precision analog output (voltage/current)
MA-4DA	4 channels 10 bits high precision analog output (voltage/current)

#### Analog input module MA-nAD

Туре	Explanation					
MA-4AD	4 channels 12 bits high precision analog input (voltage/current), each channel has PID control					
MA-8AD-A	8 channels 12 bits high precision analog input (current), each channel has PID control					
MA-8AD-V	8 channels 12 bits high precision analog input (voltage), each channel has PID control					

#### Analog I/O module MA-nADmDA

Type	Explanation
MA-4AD2DA	4 channels 12 bits high precision analog input (voltage/current), each channel has PID control. 2 channels 10 bits high precision analog output (voltage/current).

#### Temperature control module MA-nPT-P/MA-nTCA-P

Type	Explanation
MA-6PT-P	6 channels PT100 input, each channel has PID control; 6 channels output. 1mA constant current output will not be affected by external environment.
MA-6TCA-P	6 channels thermocouple input, each channel has PID control; 6 channels output. 1mA constant current output will not be affected by external environment.

#### Specifications of basic unit

#### General specification

Item	Specification
Insulation voltage	Above DC500V 2MΩ
Noise immunity	Noise voltage 1000Vp-p 1µs
Air	No corrosive, flammable gas
Ambient temperature	200 ~ 30
Ambient humidity	5RH%~95RH% (no condensation)
COM1	RS232, connect with PC, HMI to program and debug
COM2	RS232/RS485, connect with network, meters, inverter
COM3	Extension port of BD board, RS232/RS485
Installation	Fix with M3 screw or install on the rail directly
Ground	Third ground (cannot ground with strong power system)

#### XC3-19AR-E specification

Item	Analog input (AD)	Analog output (DA)				
Item	Voltage input	Voltage output	Current output			
Analog input range	0 ~ 10V	_				
Max input range	DC ± 18V	-	-			
Analog output range	-	DC 0~10V (external load resistor 2KΩ~1MΩ)	DC4~20mA (external load resistor less than 500Ω)			
Digital input range	-	8 bits (	0~255)			
Digital output range	12 bits (0~4095)	-	-			
Resolution	1/4095 (Bit)	1/255	(8Bit)			
Integrated precision		0.8%				
Transformation speed	15ms/channel	2ms/channel				
Power for analog	DC24	V±10%,100mA				

#### Performance specification

It	em					Speci	ficatior							
Series		×	(C1	1 XC2 XC3		XC5	XCM	XCC						
I/O numbers		10/16	24/32	14/16	24/32/42	48/60	14	24/32/42	48/60	24/32	60	24/32		
Program runnin	g mode						Cyclic	scan						
Programming m	node					Ins	truction,	ladder chart						
Processing spe	ed						0.5	us						
Power-off reten	tive	Flas	hROM				F	ashROM and I	Li-battery					
User program c	apacity	32	2KB			128	ΚB			96KB	128KB	256KB		
I/O numbers		5/5 5/8	12/12 16/16	8/6 8/8	14/10 18/14 24/18	28/20 36/24	8/6	14/10 18/14 24/18	28/20 36/24	14/10 18/14	36/24	14/10 18/14		
Internal coil		4	48					876	8					
Numbers			80		640									
Timer (T)	Specification		100MS TIMER: 0.1~3276.7S 10MS TIMER: 0.01~327.67S 1MS TIMER: 0.001~32.767S											
	Numbers	4	18	640										
Counter (C)	Specification	16 BITS COUNTER: 0~32767 32 BITS COUNTER: -2147483648~2147483647												
Sequence (S)		:	32		1024			1024		1024	1024	1024		
Data register (D	))	1	50	2000			8000		8000	4000	8000			
FlashROM regis	ster (FD)	4	12		128		3072			7168	1536	1024		
Extension inter	nal register (ED)		-		-		16384		36864	36864	36864			
High speed cou	nter		-	max 6 channels, 80KHz, 3 kinds of high speed counting mode (single phase, pulse&direction, AB ph					B phase is 50Kl					
Pulse output			-		:	2channels				4chnnels	10channels	5channels		
External interru	ption		-			2 kind	ls of exte	rnal interruption	on (rising e	dge, falling e	dge)			
Password							6 bits	ASCII						
Self-diagnosis					power-	on self-test,	monitori	power-on self-test, monitoring timer, grammar checking						

#### XC series model list

			Мо	del				
	AC power supply DC power supply							
	Relay output	Transistor output	Relay&transistor mixed output	Relay output	Transistor output	Relay&transistor mixed output	Input numbers (DC24V)	Output numbers (R,T)
	XC1-10R-E	XC1-10T-E	-	XC1-10R-C	XC1-10T-C	-	5	5
N P	XC1-16R-E	XC1-16T-E	-	XC1-16R-C	XC1-16T-C	-	8	8
N	XC1-24R-E	XC1-24T-E	-	XC1-24R-C	XC1-24T-C	-	12	12
	XC1-32R-E	XC1-32T-E	-	XC1-32R-C	XC1-32T-C	-	16	16
	XC1-10PR-E	XC1-10PT-E	-	XC1-10PR-C	XC1-10PT-C	-	5	5
P N	XC1-16PR-E	XC1-16PT-E	-	XC1-16PR-C	XC1-16PT-C	-	8	8
P	XC1-24PR-E	XC1-24PT-E	-	XC1-24PR-C	XC1-24PT-C	-	12	12
	XC1-32PR-E	XC1-32PT-E	-	XC1-32PR-C	XC1-32PT-C	-	16	16
	XC2-14R-E	XC2-14T-E	XC2-14RT-E	XC2-14R-C	XC2-14T-C	XC2-14RT-C	8	6
	XC2-16R-E	XC2-16T-E	XC2-16RT-E	XC2-16R-C	XC2-16T-C	XC2-16RT-C	8	8
N	XC2-24R-E	XC2-24T-E	XC2-24RT-E	XC2-24R-C	XC2-24T-C	XC2-24RT-C	14	10
P N	XC2-32R-E	XC2-32T-E	XC2-32RT-E	XC2-32R-C	XC2-32T-C	XC2-32RT-C	18	14
14	XC2-42R-E	XC2-42T-E	XC2-42RT-E	XC2-42R-C	XC2-42T-C	XC2-42RT-C	24	18
	XC2-48R-E	XC2-48T-E	XC2-48RT-E	XC2-48R-C	XC2-48T-C	XC2-48RT-C	28	20
	XC2-60R-E	XC2-60T-E	XC2-60RT-E	XC2-60R-C	XC2-60T-C	XC2-60RT-C	36	24
	XC2-14PR-E	XC2-14PT-E	XC2-14PRT-E	XC2-14PR-C	XC2-14PT-C	XC2-14PRT-C	8	6
	XC2-16PR-E	XC2-16PT-E	XC2-16PRT-E	XC2-16PR-C	XC2-16PT-C	XC2-16PRT-C	8	8
Р	XC2-24PR-E	XC2-24PT-E	XC2-24PRT-E	XC2-24PR-C	XC2-24PT-C	XC2-24PRT-C	14	10
N P	XC2-32PR-E	XC2-32PT-E	XC2-32PRT-E	XC2-32PR-C	XC2-32PT-C	XC2-32PRT-C	18	14
•	XC2-42PR-E	XC2-42T-E	XC2-42RT-E	XC2-42R-C	XC2-42PT-C	XC2-42RT-C	24	18
	XC2-48PR-E	XC2-48PT-E	XC2-48PRT-E	XC2-48PR-C	XC2-48PT-C	XC2-48PRT-C	28	20
	XC2-60PR-E	XC2-60PT-E	XC2-60PRT-E	XC2-60PR-C	XC2-60PT-C	XC2-60PRT-C	36	24
	XC3-14R-E	XC3-14T-E	XC3-14RT-E	XC3-14R-C	XC3-14T-C	XC3-14RT-C	8	6
N	XC3-24R-E	XC3-24T-E	XC3-24RT-E	XC3-24R-C	XC3-24T-C	XC3-24RT-C	14	10
Р	XC3-32R-E	XC3-32T-E	XC3-32RT-E	XC3-32R-C	XC3-32T-C	XC3-32RT-C	18	14
N	XC3-42R-E	XC3-42T-E	XC3-42RT-E	XC3-42R-C	XC3-42T-C	XC3-42RT-C	24	18
	XC3-48R-E	XC3-48T-E	XC3-48RT-E	XC3-48R-C	XC3-48T-C	XC3-48RT-C	28	20
	XC3-60R-E	XC3-60T-E	XC3-60RT-E	XC3-60R-C	XC3-60T-C	XC3-60RT-C	36	24
	XC3-14PR-E	XC3-14PT-E	XC3-14PRT-E	XC3-14PR-C	XC3-14PT-C	XC3-14PRT-C	8	6
Р	XC3-24PR-E	XC3-24PT-E	XC3-24PRT-E	XC3-24PR-C	XC3-24PT-C	XC3-24PRT-C	14	10
N	XC3-32PR-E	XC3-32PT-E	XC3-32PRT-E	XC3-32PR-C	XC3-32PT-C	XC3-32PRT-C	18	14
Р	XC3-42PR-E	XC3-42PT-E	XC3-42PRT-E	XC3-42PR-C	XC3-42PT-C	XC3-42PRT-C	24	18
	XC3-48PR-E	XC3-48PT-E	XC3-48PRT-E	XC3-48PR-C	XC3-48PT-C	XC3-48PRT-C	28	20
	XC3-60PR-E	XC3-60PT-E	XC3-60PRT-E	XC3-60PR-C	XC3-60PT-C	XC3-60PRT-C	36	24
NPN	-	XC5-24T-E	XC5-24RT-E	-	XC5-24T-C	XC5-24RT-C	14	10
	-	XC5-32T-E	XC5-32RT-E	-	XC5-32T-C	XC5-32RT-C	18	14
PNP	-	XC5-24PT-E	XC5-24PRT-E	-	XC5-24PT-C	XC5-24PRT-C	14	10
	-	XC5-32PT-E	XC5-32PRT-E	-	XC5-32PT-C	XC5-32PRT-C	18	14
NPN	-	XCM-60T-E	-	-	XCM-60T-C	-	36	24
PNP	-	XCM-60PT-E	-	-	XCM-60PT-C	-	36	24
NPN	-	XCC-24T-E	-	-	XCC-24T-C	-	14	10
	-	XCC-32T-E	-	-	XCC-32T-C	-	18	14
PNP	-	XCC-24PT-E	-	-	XCC-24PT-C	-	14	10
	-	XCC-32PT-E	-	-	XCC-32PT-C	-	18	14

\* Note: NPN and PNP are for input terminal.

#### I/O extension

		Model				
		Output  Relay output Transistor output		I/O numbers	Input numbers (DC24V)	Output numbers (R,T)
	Input				(55241)	(1.5.7)
	XC(L)-E8X	-	-	8	8	-
	-	XC(L)-E8YR	XC(L)-E8YT	8	-	8
	-	XC(L)-E8X8YR	XC(L)-E8X8YT	16	8	8
	XC(L)-E16X	-	-	16	16	-
NPN	-	XC(L)-E16YR	XC(L)-E16YT	16	-	16
INI IN	-	XC(L)-E16X16YR-E	XC(L)-E16X16YT-E	32	16	16
	-	XC-E16X16YR-C	XC(L)-E16X16YT-C	32	16	16
	XC(L)-E32X-E	-	-	32	32	-
	XC-E32X-C	-	-	32	32	-
	-	XC(L)-E32YR-E	XC(L)-E32YT-E	32	-	32
	-	XC-E32YR-C	XC(L)-E32YT-C	32	-	32
	XC-E8PX	-	-	8	8	-
	-	XC-E8PX8YR	XC-E8PX8YT	16	8	8
PNP	XC-E16PX	-	-	16	16	-
	-	XC(L)-E16PX16YR-E	-	32	16	16
	-	XC-E16PX16YR-C	-	32	16	16
	XC-E32PX-E	-	-	32	32	-

\* Note: NPN and PNP are for input terminal.

#### Analog and temperature extension modules

	Model	Description
	XC-E2AD(-H)	2 channels analog input
	XC-E4AD(-H)	4 channels analog input
Analog input	XC-E8AD(-H)	8 channels analog input (first 4 channels are voltage input, last 4 channels are current input)
/ maiog input	XC-E8AD-B	first 4 channels are voltage input (-10~10V/-5~5V), last 4 channels are current input (-20~20mA)
	XC(L)-E4AD2DA(-H)	4 channels analog input, 2 channels analog output
	XC-E4AD2DA-B-H	4 channels analog input (voltage/current), 2 channels voltage output (-10~10V/-5~5V)
	XC-E2DA(-H)	2 channels analog output
Analog output	XC-E4DA(-H)	4 channels analog output
Allalog output	XCL-E4DA	4 channels analog output
	XC-E4DA-B-H	4 channels voltage output (-10~10V/-5~5V)
	XC-E2PT(-H)	2 channels PT100 input
	XC-E6PT(-H)	6 channels PT100 input
Temperature measurement	XC-E6PT-P(-H)	6 channels PT100 input, with PID control function
measurement	XC(L)-E6TCA-P	6 channels K, S, E, N, J, T, R thermocouple input, each channel has PID function
	XC-E2TCA-P	2 channels K, S, E, N, J, T, R thermocouple input, each channel has PID function
	XC-E3AD4PT2DA	3 channels analog input, 4 channels PT100 input, 2 channels analog output
	XC-E2AD2PT2DA	2 channels analog input, 2 channels PT100 input, each channel has PID function, 2 channels analog output

 ${\rm *Note:} \ the \ model \ with \ H \ is \ photoelectric \ isolation \ for \ each \ channel.$ 

#### Extension BD board model list

	Model	Description
Temperature measurement	XC-2AD2PT-BD	2 channels analog input, 2 channels PT100 input
Communication	XC-COM(-H)-BD	RS232/485 communication
SD card	XC-SD-BD	Extend the XC PLC data capacity
Analog I/O	XC-2AD2DA-BD	2 channels analog input, 2 channels analog output
Ethernet	XC-TBOX-BD	Connect to the Ethernet
Optical fiber communication	XC-OFC-BD	Connect PLC and make optical fiber communication
Analog input	XC-4AD-BD	2 channels voltage input, 2 channels current input

#### Connection accessory model list

	Model	Description
USB convertor	USB-COM	PLC connect to PC via USB port
Bluetooth	COM-BLT	Short distance wireless connection between PLC and PC

#### **Basic instructions**

Instruction	Function
LD	Initial logic normally open contactor
LDI	Initial logic normally close contactor
AND	Serial connection normally open contactor
ANI	Serial connection normally close contactor
OR	Parallel connection normally open contactor
ORI	Parallel connection normally close contactor
LDP	Initial logic rising-edge of pulse
LDF	Initial logic falling-edge of pulse
ANDP	Serial connection rising-edge of the pulse
ANDF	Serial connection falling-edge of the pulse
ORP	Parallel connection rising-edge of the pulse
ORF	Parallel connection falling-edge of the pulse
LDD	Read normally open contactor
LDDI	Read normally close contactor
ANDD	Read normally open contactor, serial connection
ANDDI	Read normally close contactor, serial connection
ORD	Read normally open contactor, parallel connection
ORDI	Read normally close contactor, parallel connection
OUT	Coil drive
OUTD	Output to the contactor
ORB	Parallel connection of serial circuit block
ANB	Serial connection of parallel circuit block
MCS	New generatrix start
MCR	Generatrix reset
ALT	Coil reverse
PLS	ON for one scanning period at rising-edge
PLF	ON for one scanning period at falling-edge
SET	Keep the coil ON
RST	Reset the coil
TMR	Timer drive
OUT	Counter drive
RST	Reset the contactor or present value
END	I/O operation and return to step 0
GROUP	Instruction block folding start
GROUPE	Instruction block folding end

#### Motion control instruction

Instruction	Function
ABS	Absolute address
CCW	Arc anticlockwise interpolation
CHK	Servo checking
CW	Arc clockwise interpolation
DRV	High speed positioning
DRVR	Electrical back to zero
DRVZ	Mechanical back to zero
FOLLOW	Follow
INC	Incremental address
LIN	Linear interpolation
PLAN	Plane or space choice
TIM	Stable time
SETR	Set the electrical zero
SETP	Set the coordinate system

#### Application instruction

уре	Instruction	Function	Туре	Instruction	Function
	CJ	Condition jump		MEAN	Get the mean value
	CALL	Call the subprogram	Da	WAND	Logic AND
SRET STL STLE SET		Subprogram return	Data calculation	WOR	Logic OR
		Process start		WXOR	Logic XOR
		Process end			-
		Open assigned process, close present process	Ē.	NEG	Reverse Negative
	ST ST	Open assigned process, not close present process		SHL	Arithmetic shift left
SS	FOR	Cycle start		<u> </u>	
	NEXT	Cycle end		SHR	Arithmetic shift right
	FEND	Main program end	D	LSL	Logic shift left
	LD =	Initial logic ON when (S1)=(S2)	LSR ROL		Logic shift right
	LD>	Initial logic ON when (S1)>(S2)			Cycle shift left
	LD<	Initial logic ON when (S1)<(S2)	7	ROR	Cycle shift right
	LD<>	Initial logic ON when (S1)≠(S2)		SFTL	Bit shift left
	LD>=	Initial logic ON when (S1)≥(S2)		SFTR	Bit shift right
	LD<=	Initial logic ON when (S1)≤(S2)		WSFL	Word shift left
Da	AND =	Serial connection ON when (S1)=(S2)		WSFR	Word shift right
tac	AND >	Serial connection ON when (S1)>(S2)		WTD	Word integer change to double w
Data comparison	AND <	Serial connection ON when (S1)<(S2)		FLT	16 bits integer change to floating
pai	AND <>	Serial connection ON when (S1)#(S2)	. D	FLTD	64 bits integer change to floating
is o	AND >=	Serial connection ON when (S1)≥(S2)		INT	Floating number change to integ
š	AND <=	Serial connection ON when (S1)≤(S2)	n ON when (S1)≤(S2)		BCD code change to binary
	OR =	Parallel connection ON when (S1)=(S2)	a	BCD	Binary change to BCD code
	OR >	Parallel connection ON when (S1)>(S2)	Data transformation	ASCI	Hex change to ASCII
	OR <	Parallel connection ON when (S1)<(S2)		HEX	ASCII change to hex
	OR <>	Parallel connection ON when (S1)≠(S2)		DECO	Decoding
	OR >=			ENCO	High-bit encoding
	OR >= Parallel connection ON when (S1) ≥ (S2)  OR <= Parallel connection ON when (S1) ≤ (S2)			ENCOL	Low-bit encoding
	CMP	Data comparison		GRY	Binary change to gray code
	ZCP	· · · · · · · · · · · · · · · · · · ·		GBIN	Gray code change to binary
_	MOV	Data range comparison  Transmission		ECMP	Floating number comparison
)at	BMOV	Data block transmission		EZCP	Floating number range comparis
Data transmission	FMOV	Multi-point repeat transmission		EADD	Floating number addition
ans	FWRT	Write in FlashROM	프	ESUB	Floating number subtraction
ä.	MSET	Batch set on	Floating calculation	EMUL	Floating number multiplication
SSi	ZRST	Batch reset	ng	EDIV	Floating number division
ň	SWAP	Exchange the high byte and low byte	<u>a</u>	ESQR	Floating number square
	XCH	Exchange the data	=	SIN	Floating number sine
_	ADD	Addition	<u>∓</u> .	cos	Floating number cosine
ADD	SUB	Subtraction		TAN	Floating number tangent
аса	MUL	Multiplication		ASIN	Floating number arcsine
Cu	DIV	Division		ACOS	Floating number arccosine
Data calculation	INC	Increase by one		ATAN	Floating number arctangent
on	DEC	Decrease by one	C	TRD	Read clock data
			Cloc	TWR	Write clock data

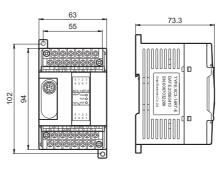
#### **Special instruction**

Type	Instruction	Function	
	PLSY	Single-segment pulse output without acceleration and deceleration	
	PLSA	Absolute position multi-segment pulse output	
	PLSR	Relative position multi-segment pulse output	
	PLSF	Variable frequency pulse output	
-	PLSNEXT/PLSNT	Pulse segment changing	
Pulse output	DRVA	Absolute position single segment pulse control	
ě	DRVI	Relative position single segment pulse control	
튵	PLSMV	Store the pulse numbers in the register	
≒	STOP	Stop the pulse	
	ZRN	Mechanical return to zero	
	PTO	Relative multi-segment pulse output	
	PTOA	Absolute multi-segment pulse output	
	PSTOP	Pulse stop	
	PTF	Variable frequency pulse output	

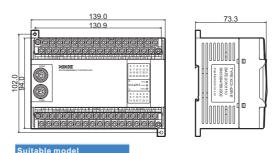
Туре	Instruction	Function	
о п	HSCR	Read 32 bits high speed counter	
igh s	HSCW	Write 32 bits high speed counter	
High speed counter	OUT	24-segment high speed count interruption	
۵	RST	Reset high speed counter	
	COLR	Modbus read coil	
Mod	INPR	Modbus read input coil	
sud	COLW	Modbus write single coil	
Modbus communication	MCLW	Modbus write multi coils	
a n	REGR	Modbus read register	
icati	INRR	Modbus read input register	
9	REGW	Modbus write single register	
	MRGW	Modbus write multi registers	
Free format communica	SEND	Free format data send	
Free format communication	RCV	Free format data receive	

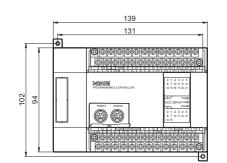
Type	Instruction	Function	
Precise timing	STR	Precise timing	
	STRR	Read precise timing register	
	STRS	Stop precise timing	
	EI	Enable the interruption	
Interruption	DI	Disable the interruption	
	IRET	Interruption return	
	SBLOCK	Block start	
	SBLOCKE	Block end	
Sequence block	BSTOP	Stop block	
	BGOON	Continue running the stop block	
	WAIT	Wait	
Write and read	FROM	Read the module	
the module	то	Write in	
Others	FRQM	Frequency measurement	
	PWM	Pulse width modulation	
	PID	PID control	
	NAME_C	C function block	

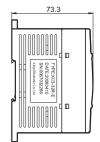
#### Dimension of basic unit



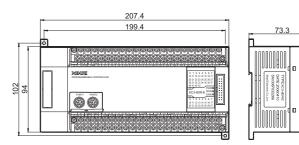
Suitable model			
Series	I/O numbers		
XC1	10/16		
XC2	14/16		
XC3	14		







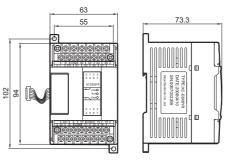
Suitable model			
Series	I/O numbers		
XC1	24/32		
XC2	24/32		
XC3	24/32		
XC5	24/32		
xcc	24/32		



uitable model			
Series	I/O numbers		
XC2	48/60		
XC3	48/60		
XCM	60		

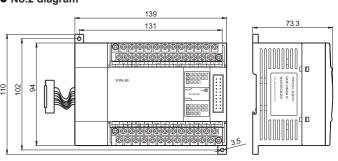
#### Dimension of extension module

#### ● No.1 diagram



Suitable model			
Series	I/O numbers		
I/O	8, 16		
Analog	All		
Temperature	All		
Mixed	All		

#### • No.2 diagram



Suitable model			
Series	I/O numbers		
I/O	32		
Analog	-		
Temperature	-		
Mixed	-		